

How well do we know the equation of state in neutron stars?

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Root
Insurance Co



THE OHIO STATE UNIVERSITY

Background

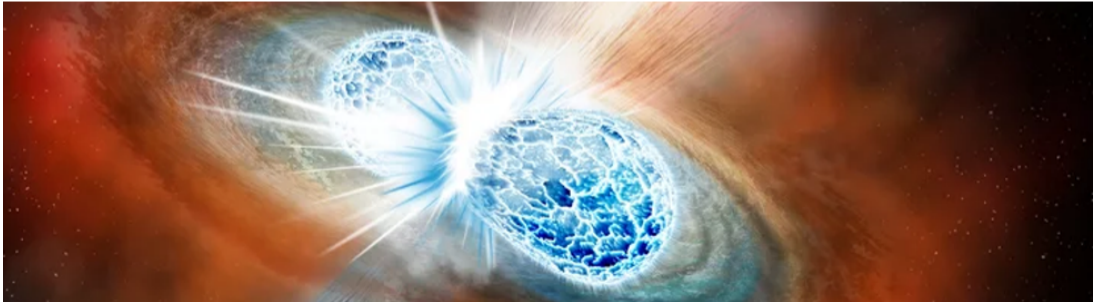
Motivation

- The era of multi-messenger astronomy is here



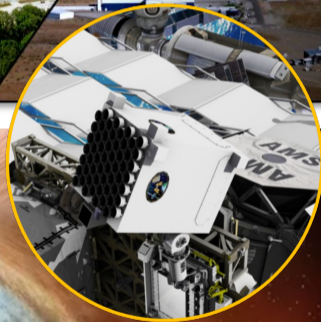
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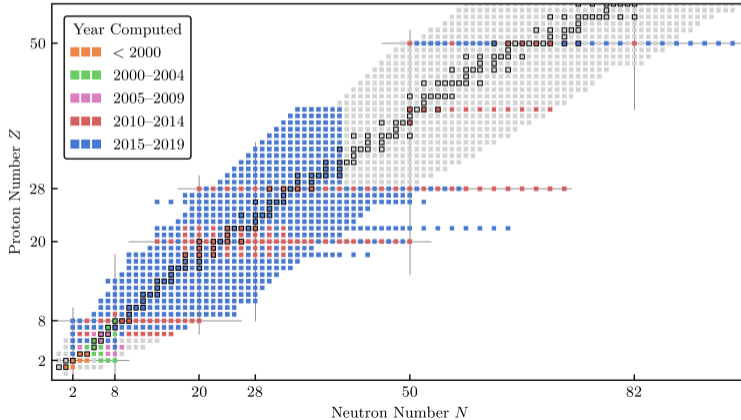
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- The era of multi-messenger astronomy is here
- LIGO/Virgo are measuring black hole and neutron star collisions
- NICER x-ray telescope
- Where does gold come from?



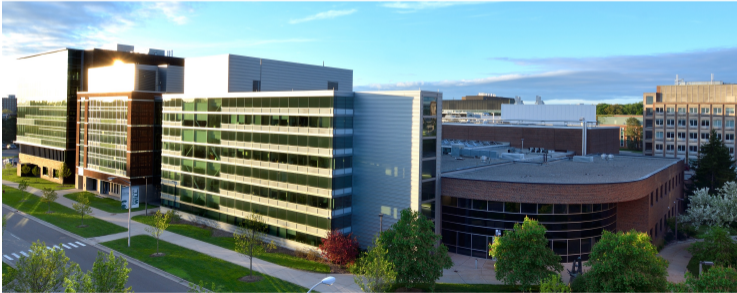
New facilities

- Requires understanding of nuclei “far from stability”
- Bottom right of nuclear chart; many more neutrons than protons



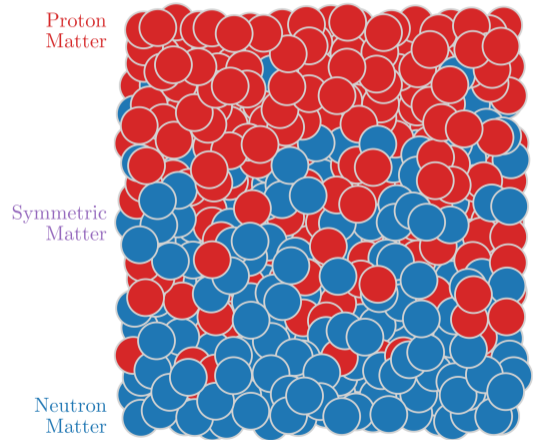
New facilities

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- Bottom right of nuclear chart; many more neutrons than protons
- FRIB just opened to study these rare isotopes



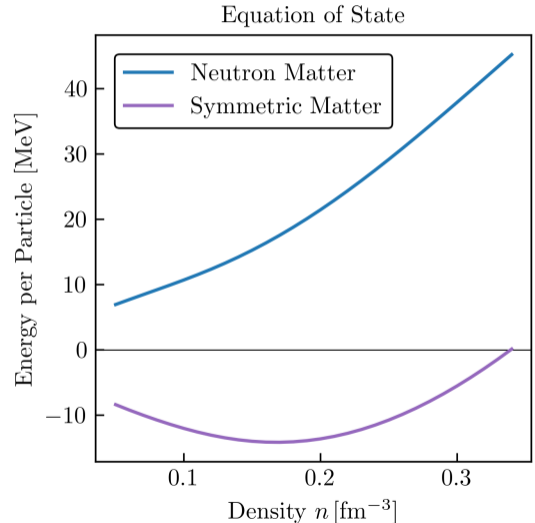
Key nuclear input: the equation of state

- **Nuclear matter:** infinite in extent, no electromagnetism, and can be made up of any ratio of neutrons/protons



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- Some key observables
 E/A : Energy per particle

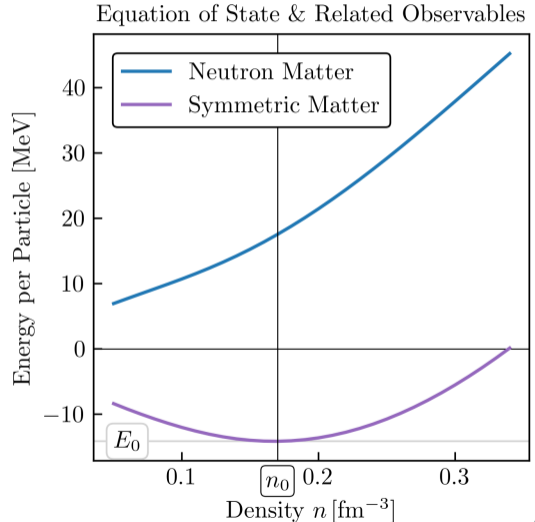


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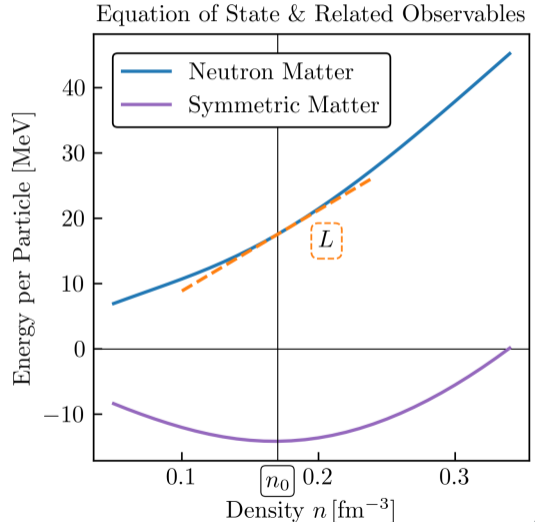
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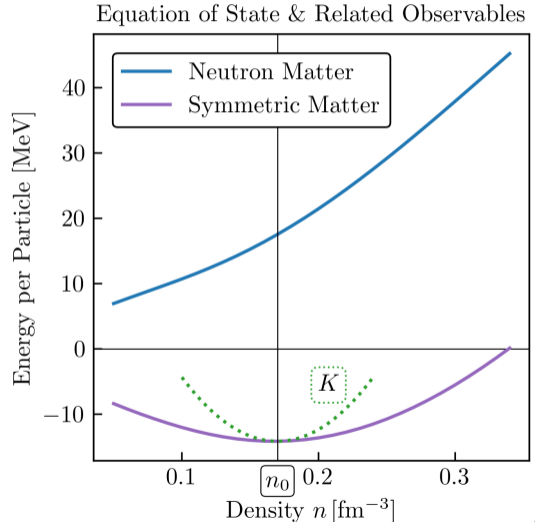
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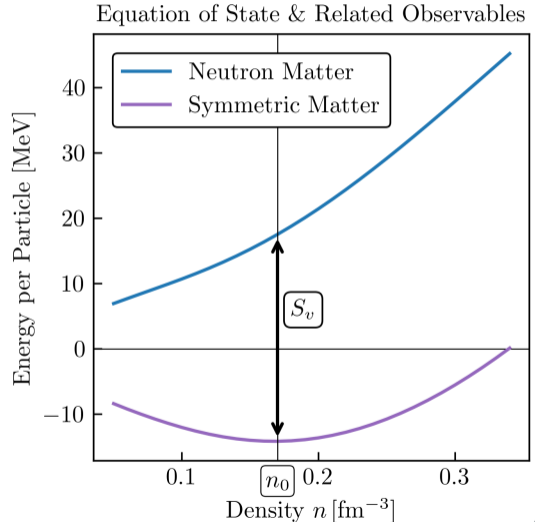
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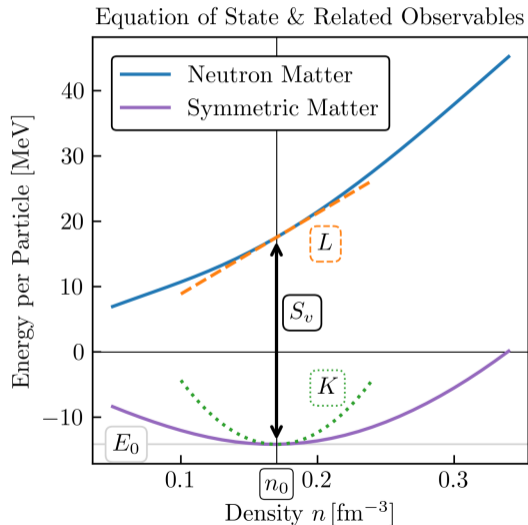
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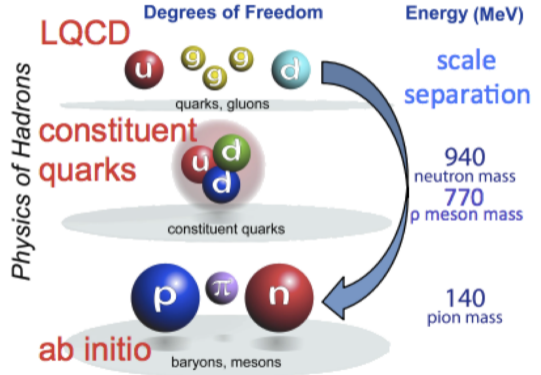
- Want **consistent** error propagation!



Predicting the Equation of State

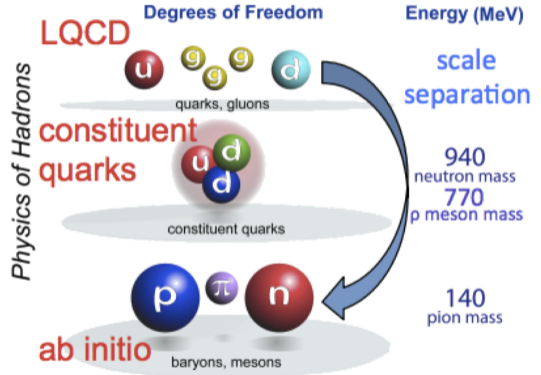
Predictions in low-energy nuclear physics

- We need to know how protons/neutrons interact
- There is interesting physics at all scales



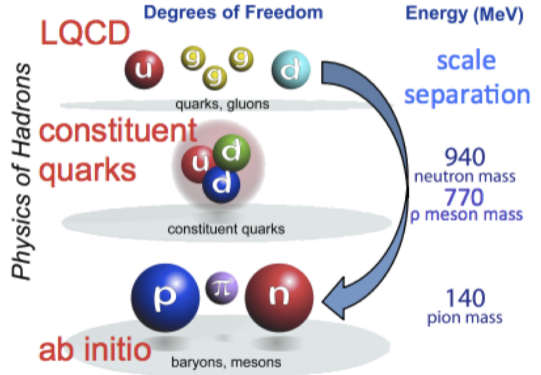
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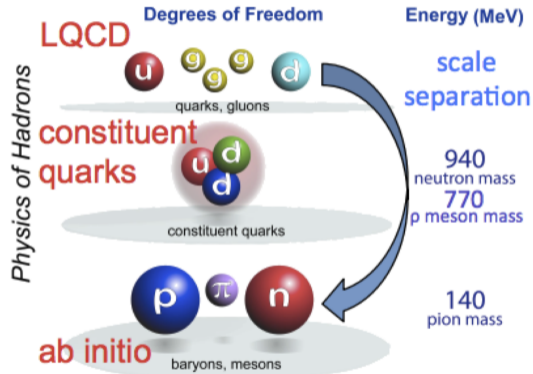
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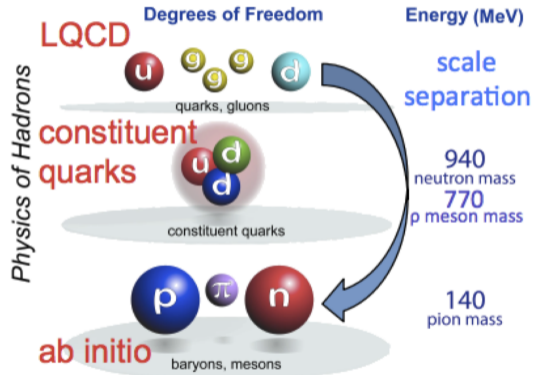
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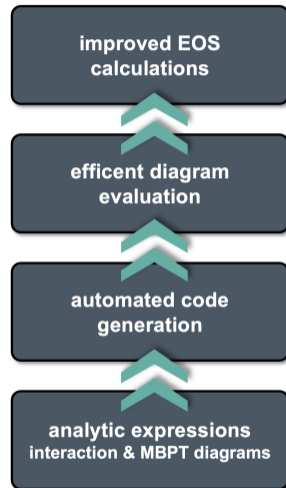
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- We use **chiral effective field theory** here.
- **Truncation error must be quantified!**



Evaluating diagrams: automatic code generation [[arxiv:1710.08220](https://arxiv.org/abs/1710.08220)]

- Chiral EFT provides forces; we need to simulate **large** systems → many-body perturbation theory (MBPT)
- Number of many-body diagrams increases rapidly
 - $n = 2 : 1$
 - $n = 3 : 3$
 - $n = 4 : 39$
 - $n = 5 : 840$
 - $n = 6 : 27,300$
 - $n = 7 : 1,232,280$
- Need a systematic way to build & evaluate diagrams → automatic code generation
- Accelerated with GPU, MPI, and openMP

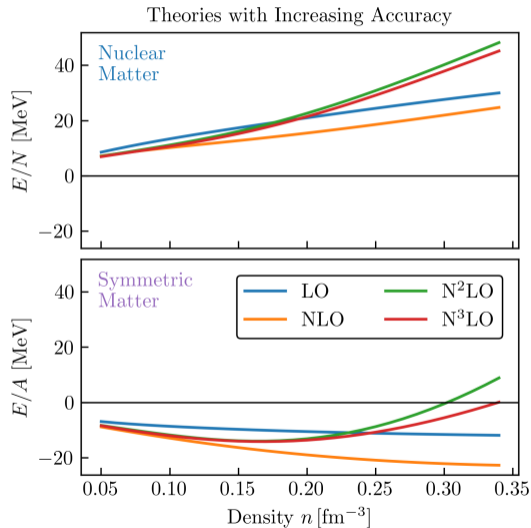


Drischler, Hebeler, and Schwenk, PRL 122, 042501
Drischler & McElvain, in prep.

A Model for Effective Field Theory Uncertainty

Takeaway points

- Theory error enabled by **multiple** models + physical intuition

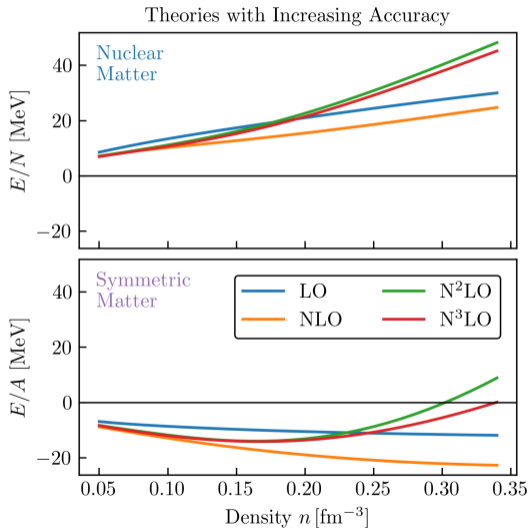


Takeaway points

- Theory error enabled by **multiple** models + physical intuition
- Correlations in errors matter

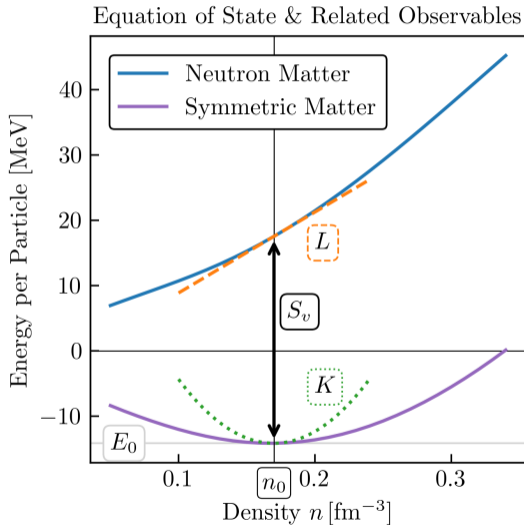
Type-x: One observable at multiple locations $y(x)$ vs $y(x')$

Type-y: Multiple observables $y(x)$ vs $y(x')$



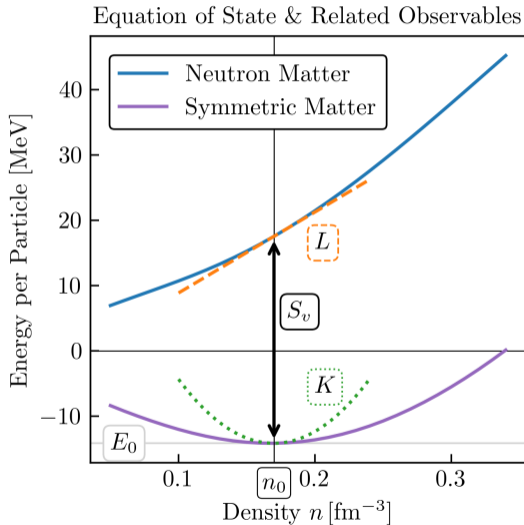
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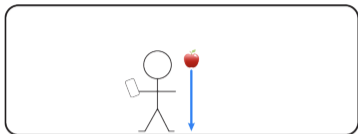
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- Correlations in errors matter
 - Type-x:** One observable at multiple locations $y(x)$ vs $y(x')$
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- One model connects uncertainties across **multiple** observables



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- Theory error enabled by **multiple** models + physical intuition
- Correlations in errors matter
 - Type-x:** One observable at multiple locations $y(x)$ vs $y(x')$
 - Type-y:** Multiple observables $y(x)$ vs $y'(x')$
- One model connects uncertainties across **multiple** observables
- The truncation error model makes testable predictions

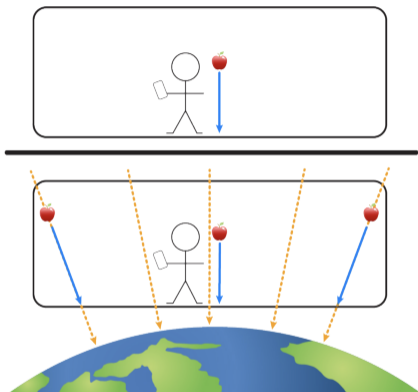




Grav. force (short distances):

$$F = -mg$$

Scales in Physics



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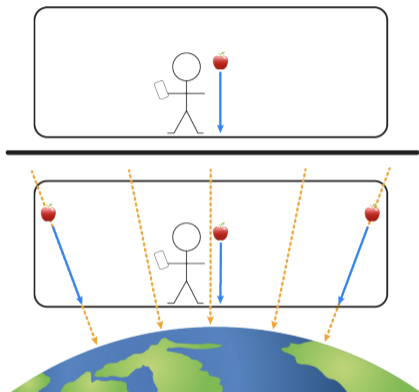
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The laws look quite different!

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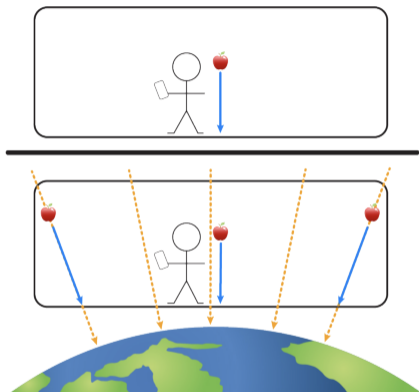
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Connected via series expansion about radius of Earth R :

$$F \approx -mg + 2mg \left(\frac{r-R}{R} \right) - 3mg \left(\frac{r-R}{R} \right)^2 + \mathcal{O} \left[\left(\frac{r-R}{R} \right)^3 \right]$$

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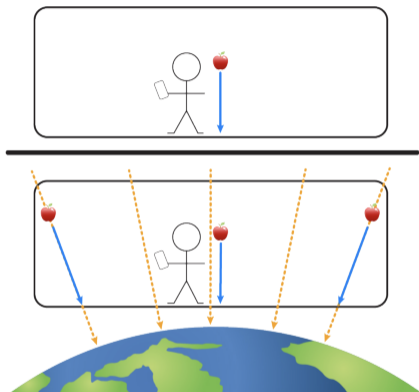
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Can fit unknown parameters to data \Rightarrow inverse problem!

$$F \approx a_0 + a_1 \left(\frac{r-R}{R} \right) + a_2 \left(\frac{r-R}{R} \right)^2 + \mathcal{O} \left[\left(\frac{r-R}{R} \right)^3 \right]$$

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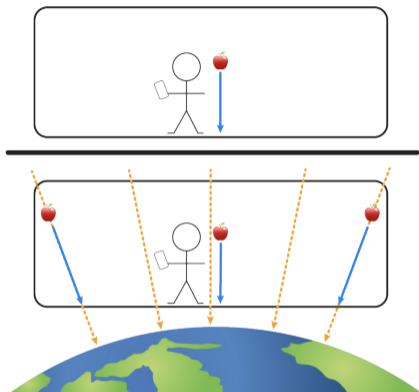
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Use prior info from physics:

$$F \approx mg \left\{ a'_0 + a'_1 \left(\frac{r-R}{R} \right) + a'_2 \left(\frac{r-R}{R} \right)^2 + \mathcal{O} \left[\left(\frac{r-R}{R} \right)^3 \right] \right\}$$

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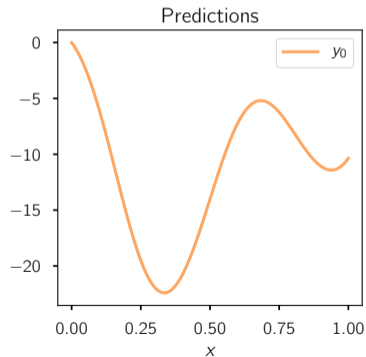
Propagate full uncertainty

$$F \approx mg \left\{ a'_0 + a'_1 \left(\frac{r-R}{R} \right) + a'_2 \left(\frac{r-R}{R} \right)^2 + \mathcal{O} \left[\left(\frac{r-R}{R} \right)^3 \right] \right\}$$

Chiral EFT in one slide

$$\bullet V_{NN}(\vec{a}) = V_{LO} + V_{NLO} + \dots + V_{N^kLO} \implies \boxed{\text{MBPT}} \implies y_k(x; \vec{a})$$

$\{y_0\}$

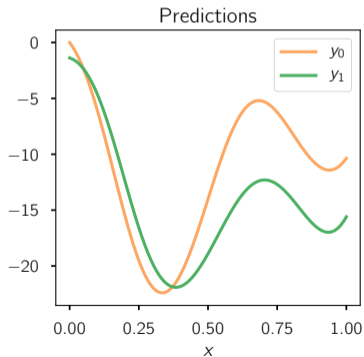


$y_0 \rightarrow \text{LO}$

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$\{y_0, y_1\}$



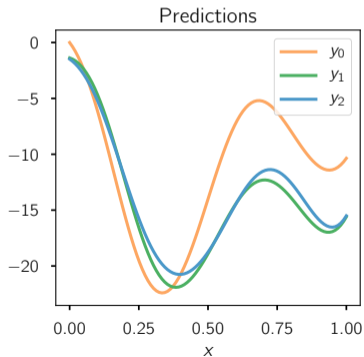
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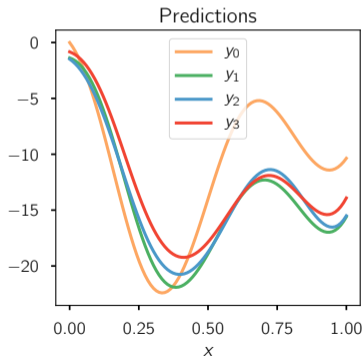
$y_1 \rightarrow \text{NLO}$

$y_2 \rightarrow \text{N}^2\text{LO}$

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$\{y_0, y_1, y_2, y_3\}$



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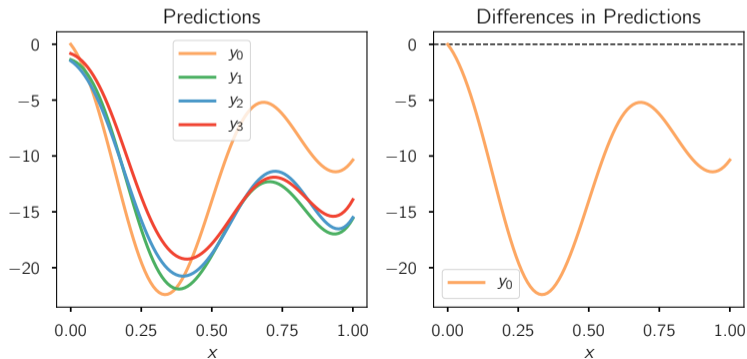
\vdots

$y_k \rightarrow \text{N}^k\text{LO}$

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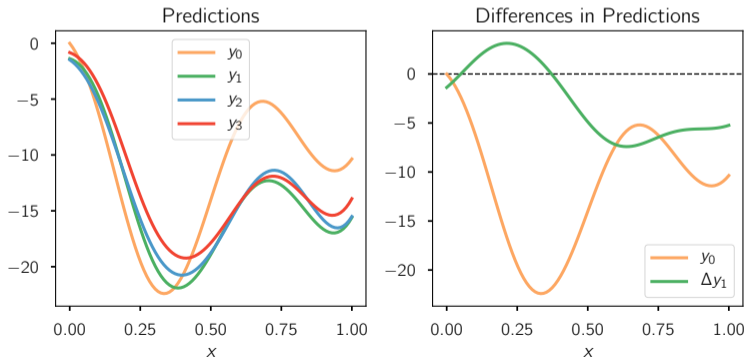
$$y_0 = y_0$$



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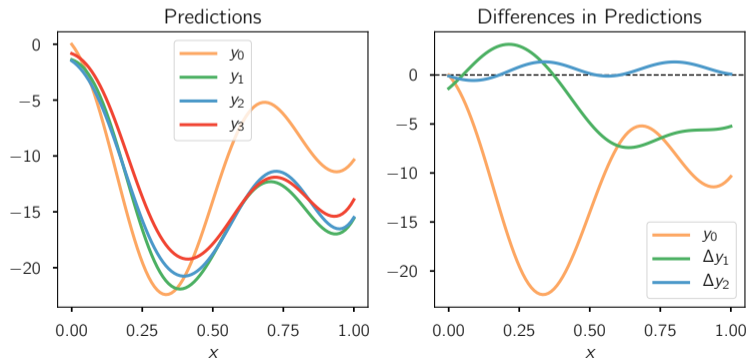
$$y_1 = y_0 + \Delta y_1$$



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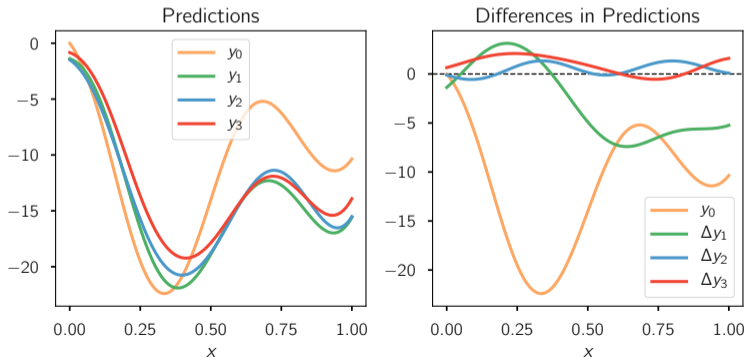
$$y_2 = y_0 + \Delta y_1 + \Delta y_2$$



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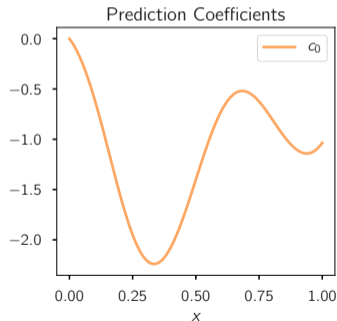
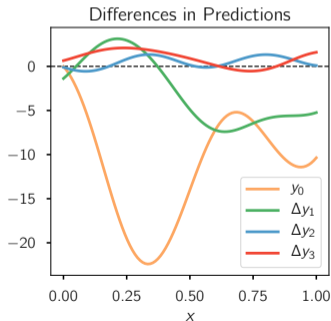
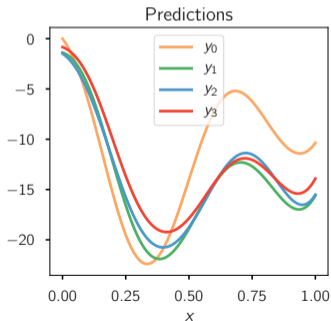
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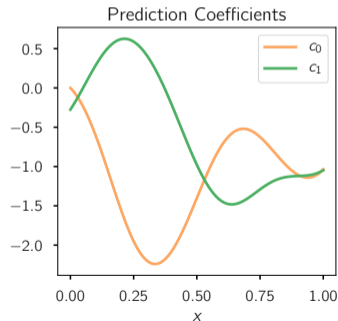
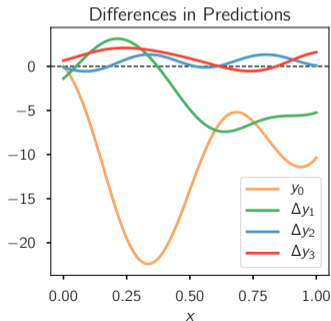
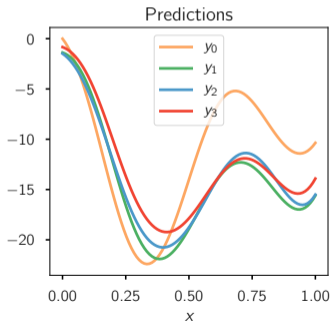
$$y_0 = y_{\text{ref}} [c_0 Q^0]$$



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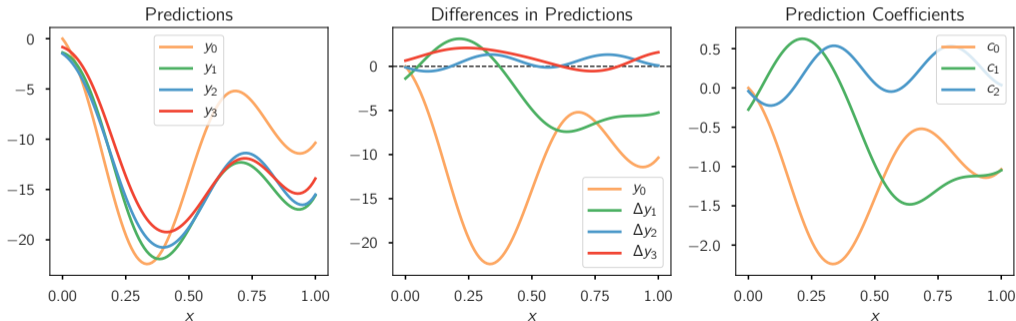
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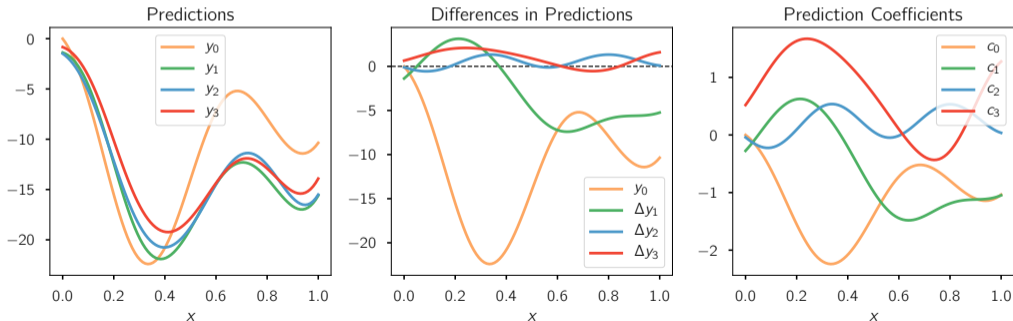
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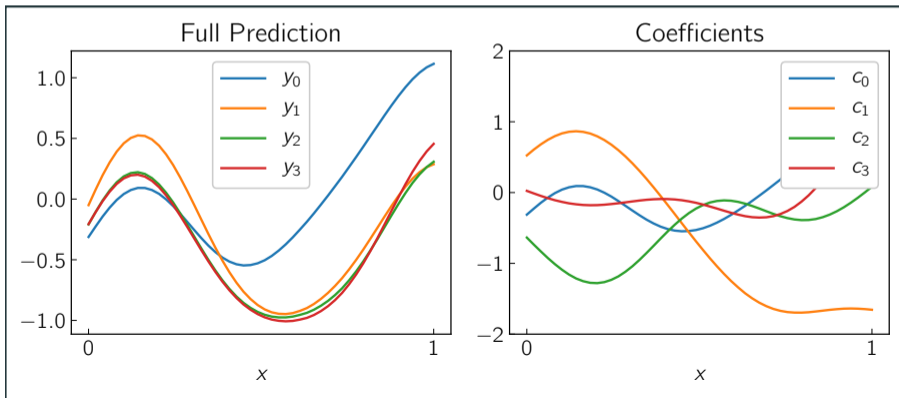
$$y_3 = y_{\text{ref}} [c_0 Q^0 + c_1 Q^1 + c_2 Q^2 + c_3 Q^3]$$



Main equation

$$y_k = y_{\text{ref}} \sum_{n=0}^k c_n Q^n$$

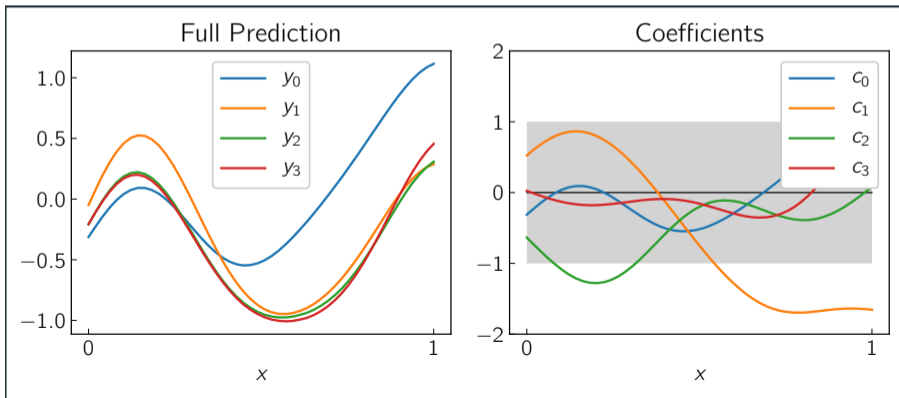
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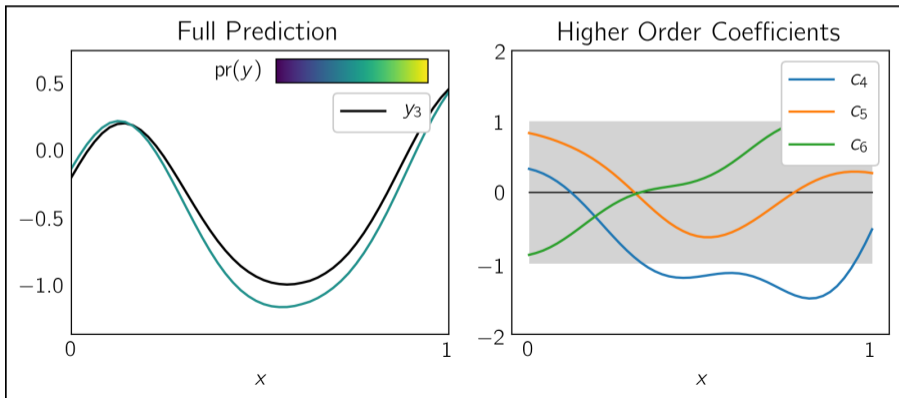
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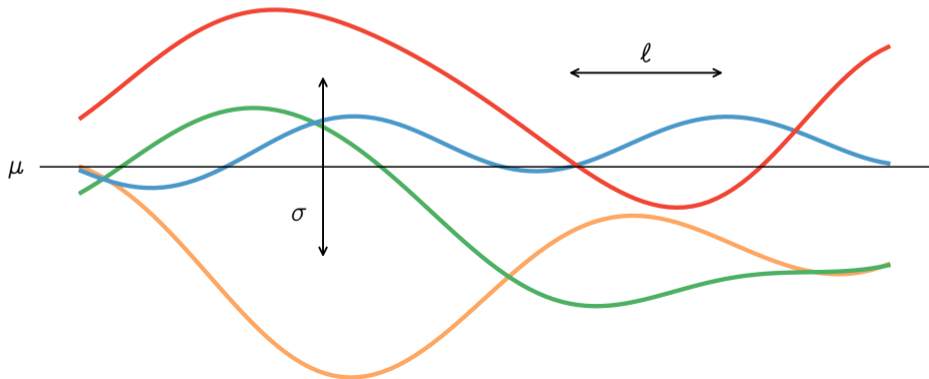
$$y = y_{\text{ref}} \sum_{n=0}^{\infty} c_n Q^n$$

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Gaussian processes: how we induct on the c_n

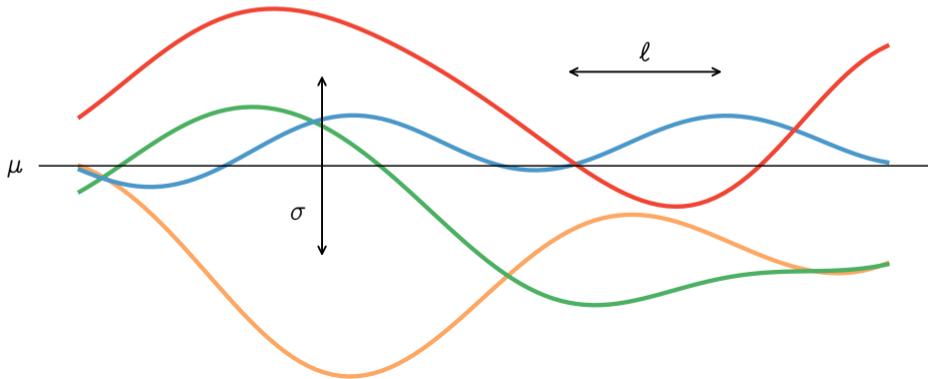
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Gaussian processes: how we induct on the c_n

What are Gaussian processes?

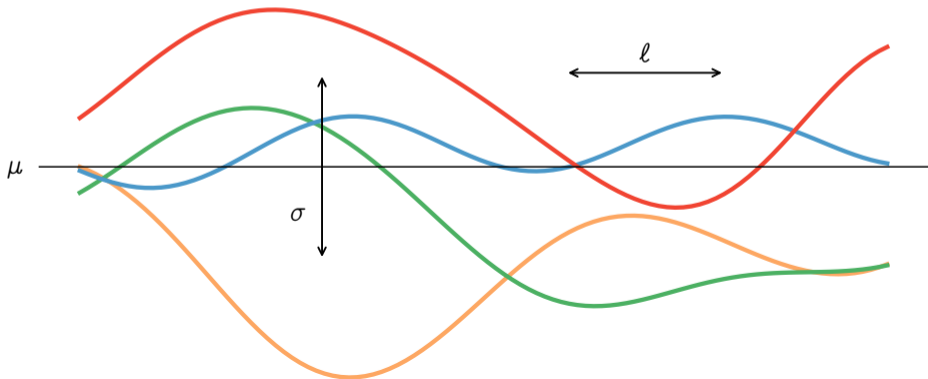
- An infinite dimensional generalization of the Gaussian distribution



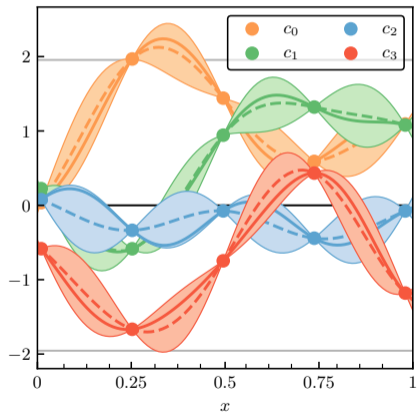
Gaussian processes: how we induct on the c_n

What are Gaussian processes?

- An infinite dimensional generalization of the Gaussian distribution
- A popular **machine learning** tool for non-parametric regression

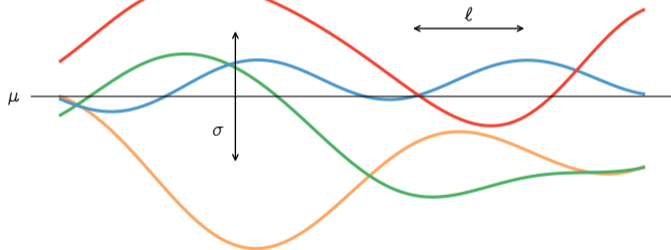
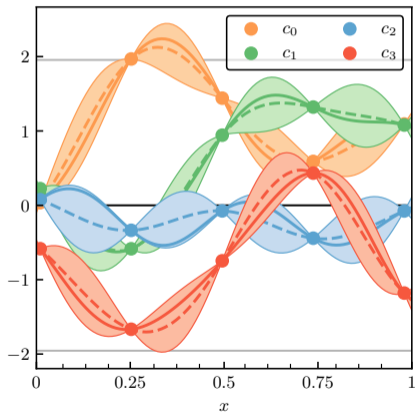


Learning parameters



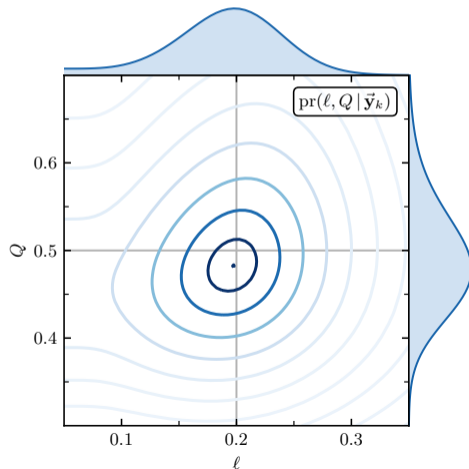
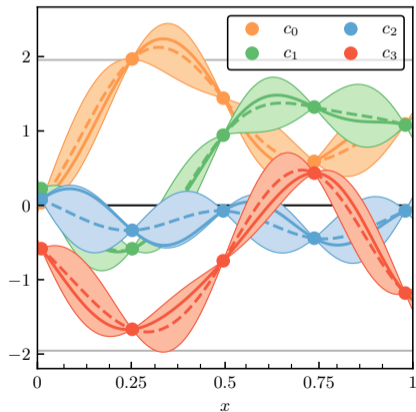
Learning parameters

$$y_3 = y_{\text{ref}} [c_0 Q^0 + c_1 Q^1 + c_2 Q^2 + c_3 Q^3]$$

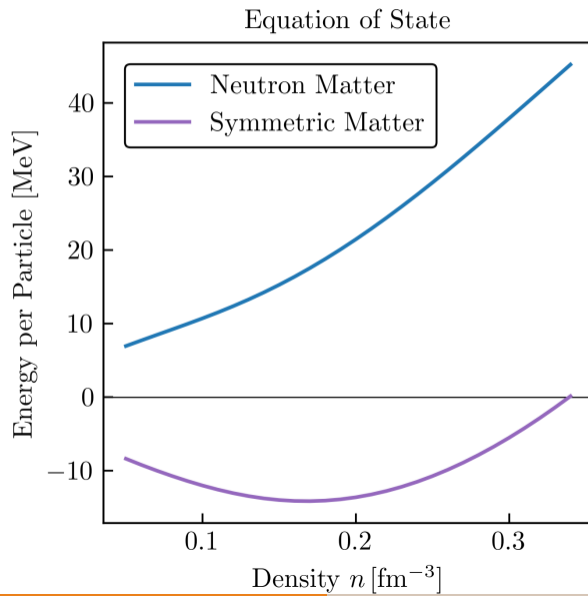


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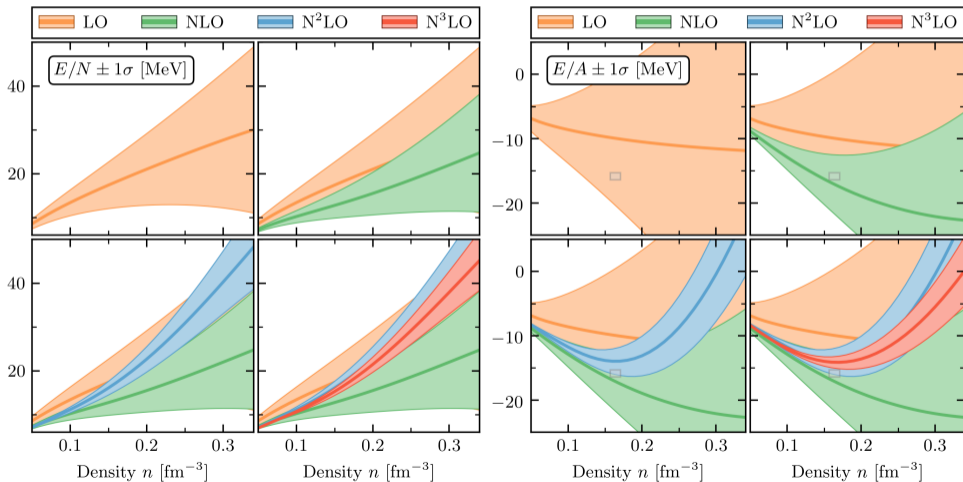


Uncertainty quantification: the equation of state

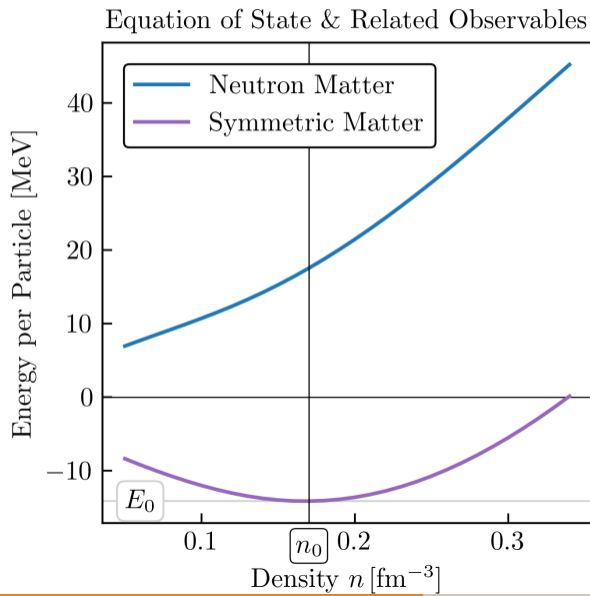


The equation of state

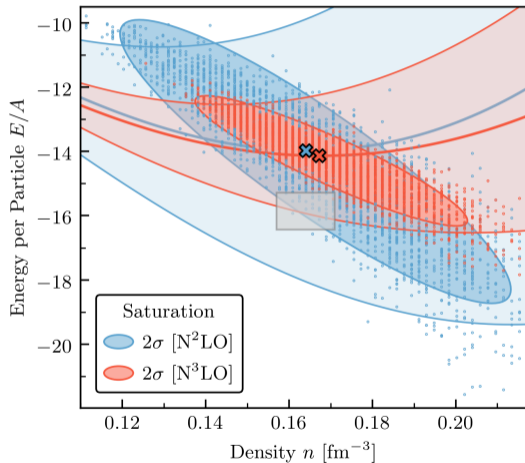
Note: correlations not shown!



Uncertainty quantification: the saturation point



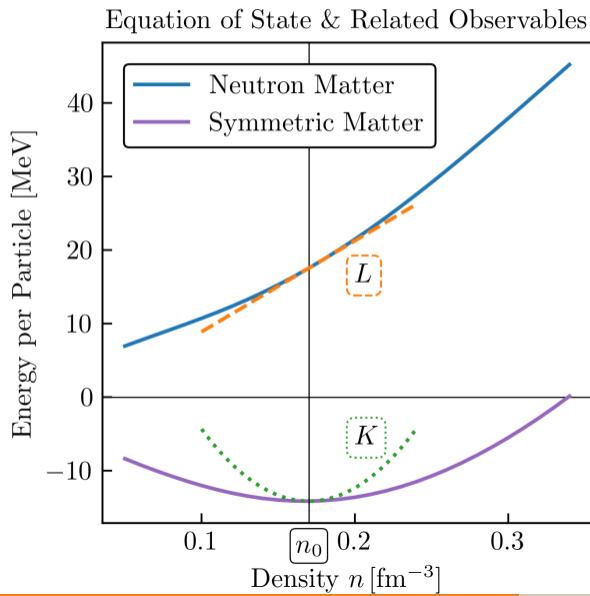
Saturation properties



$$\text{pr}(E_0, n_0 | \mathcal{D})$$

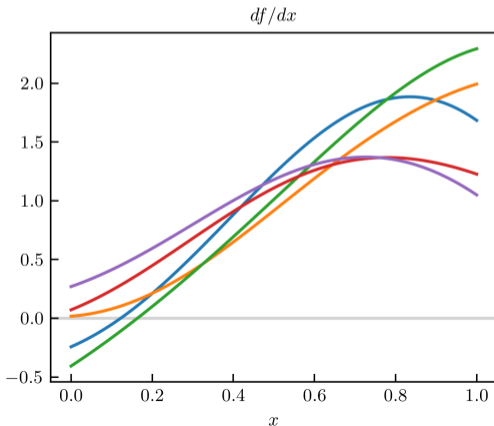
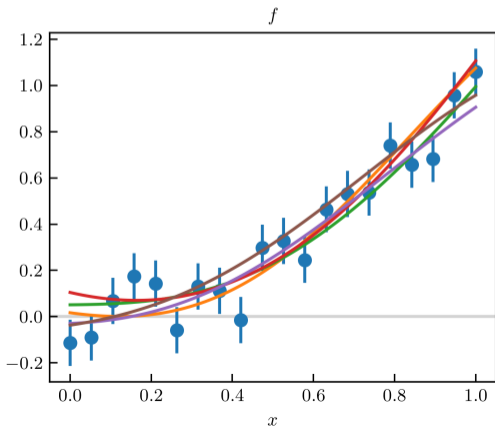
- Crosses denote minimum of theory curve
- Blue: our 2nd-best theory; Red: our best theory
- Create distribution by sampling: draw curve, get minimum, repeat
- Approximate by ellipse
- (Little grey box shows constraints from density function theory)

Uncertainty quantification: gradient properties

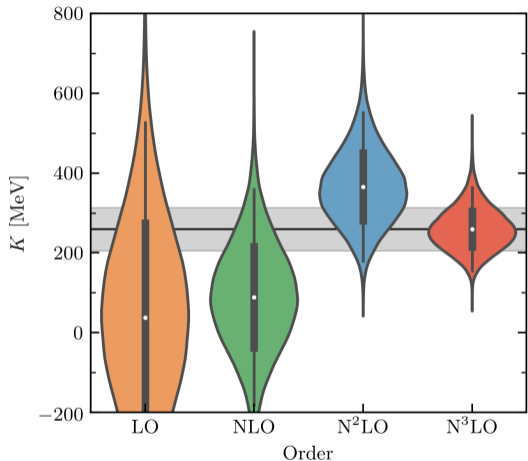


Obtaining derivatives

- Gaussian processes are closed under differentiation
- Can draw random functions and its corresponding derivative
- Correlations between f and f' come free!



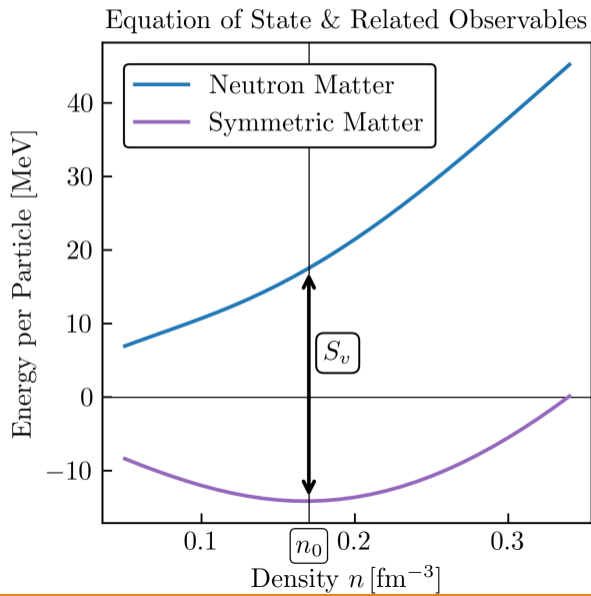
Gradient examples



$$\text{pr}(K | \mathcal{D}) = \int dn_0 \text{pr}(K | n_0, \mathcal{D}) \text{pr}(n_0 | \mathcal{D})$$

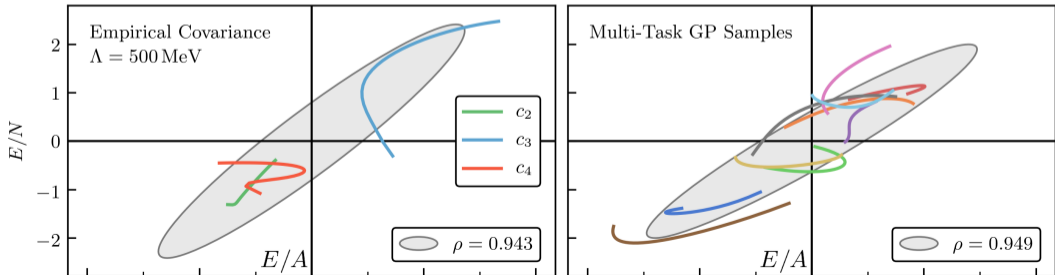
- Incompressibility is defined at saturation density n_0
- We don't know what n_0 is, but can marginalize over it (see previous slides)

Uncertainty quantification: symmetry energy



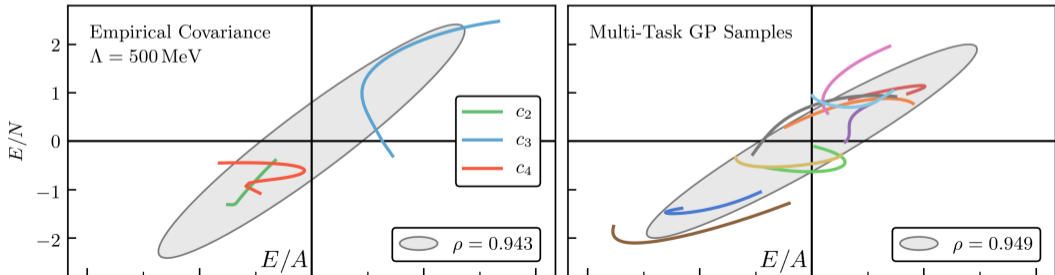
Correlated observables: estimating symmetry energy

- The convergence pattern of E/N is correlated with that of E/A .



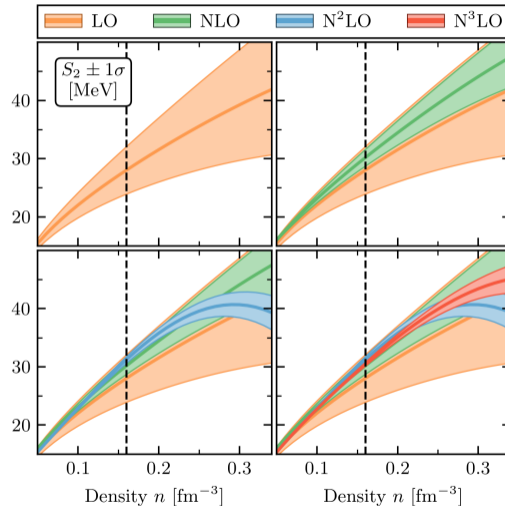
Correlated observables: estimating symmetry energy

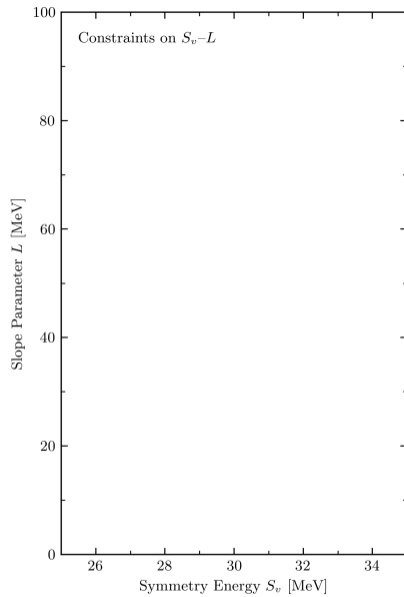
- The convergence pattern of E/N is correlated with that of E/A .
- Model with **multi-task** Gaussian process

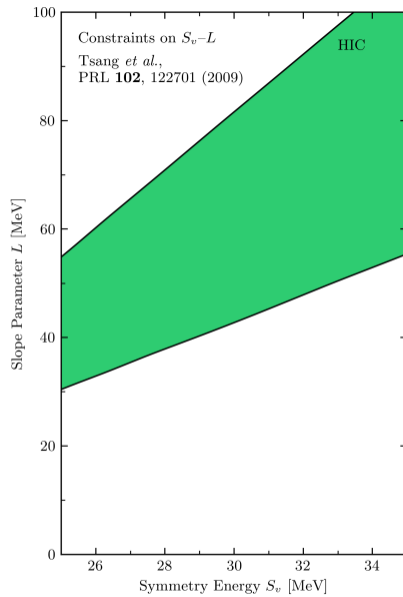


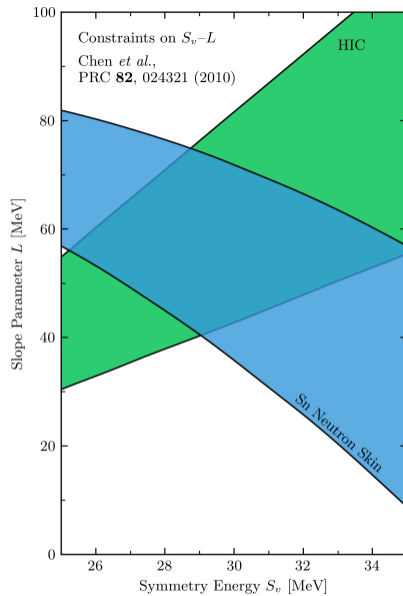
Correlated observables: estimating symmetry energy

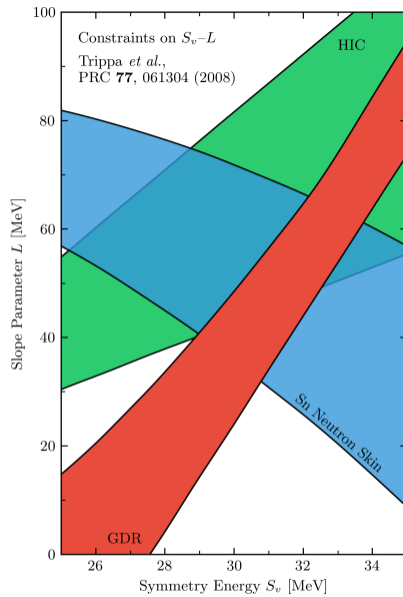
- The convergence pattern of E/N is correlated with that of E/A .
- Model with **multi-task** Gaussian process
- So the uncertainty in $S_2 = E/N - E/A$ is smaller than naively expected

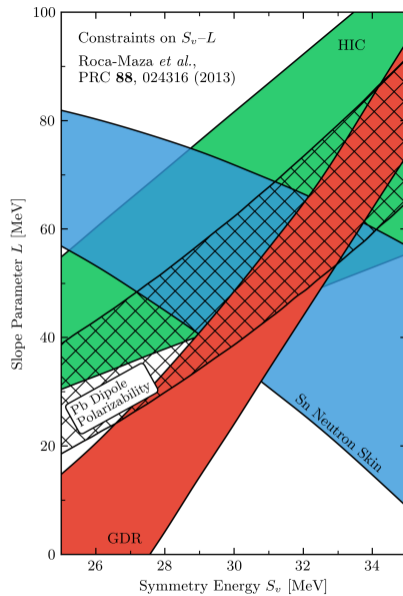


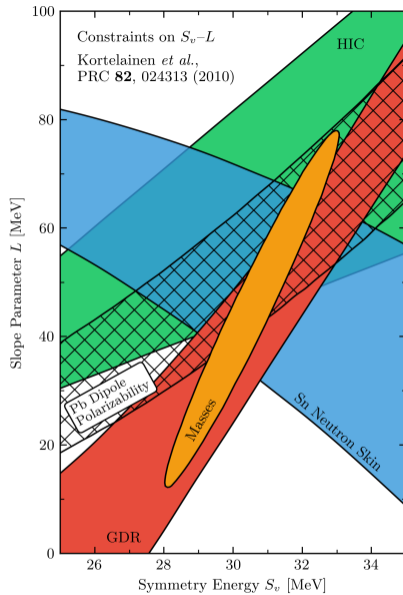


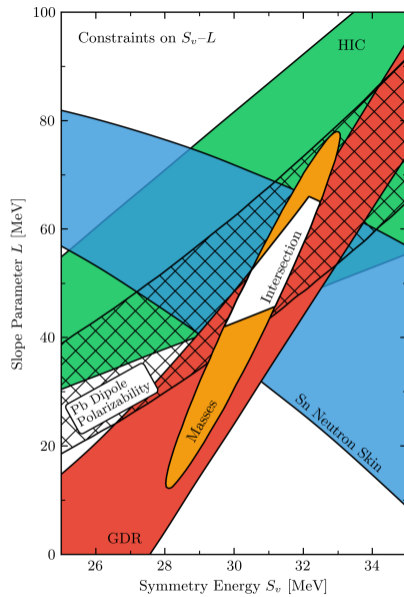


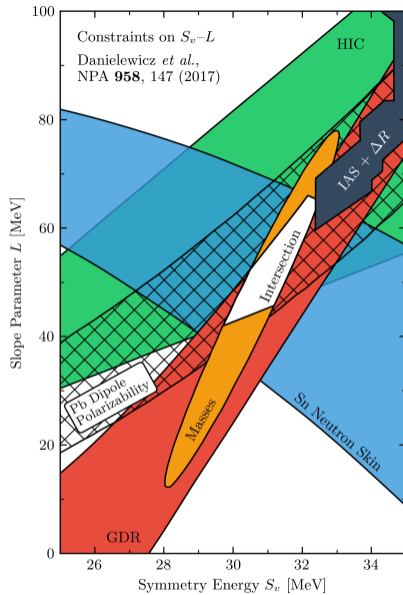


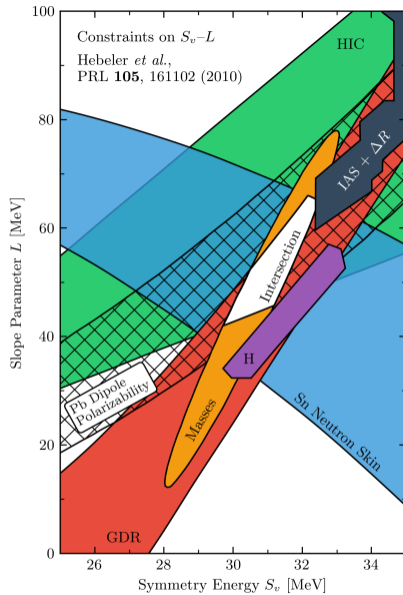


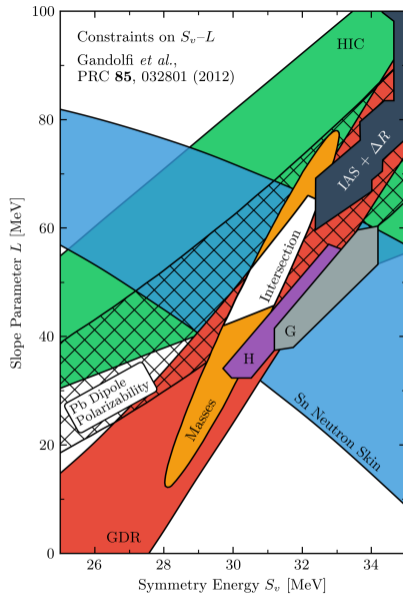


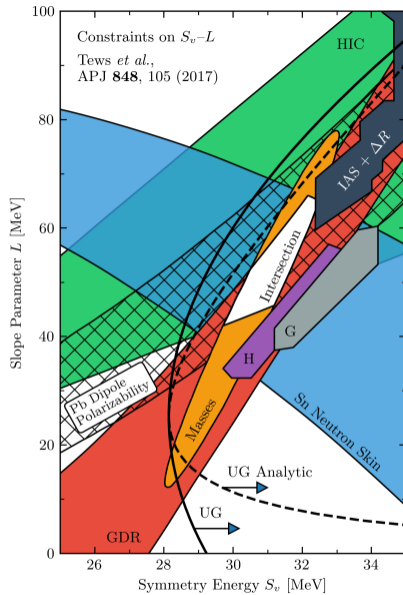


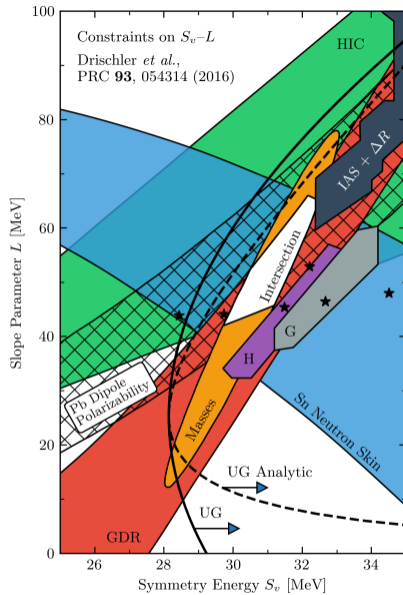


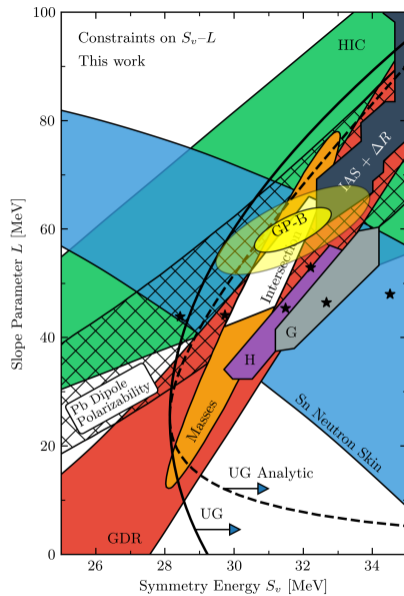




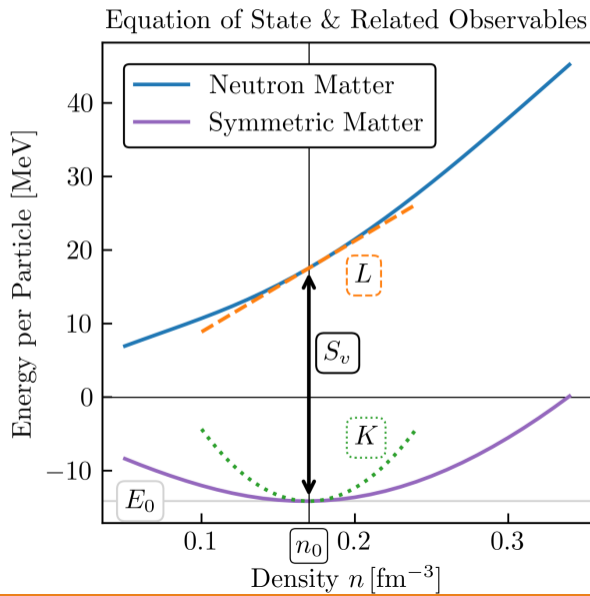




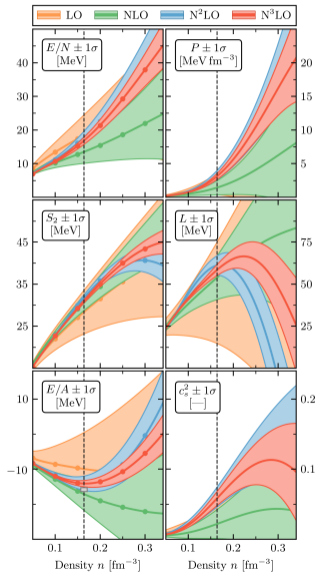
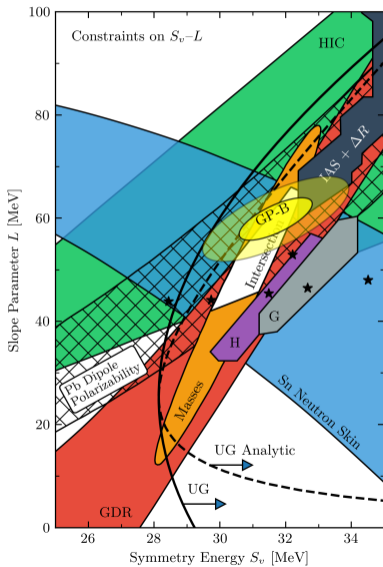


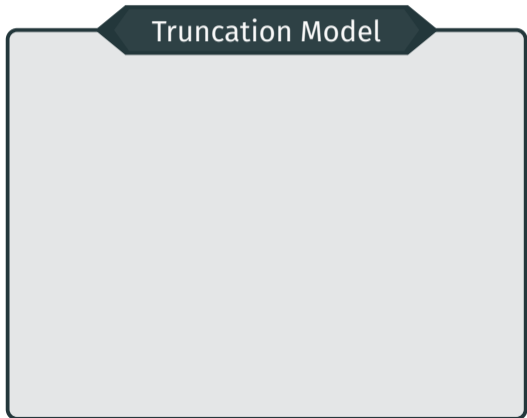


Uncertainty quantification: putting it all together



Key results





Truncation Model

- Truncation and interpolation error informed by convergence pattern

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- Full error can be propagated, using physics insight

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- All code is publicly available

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Implications

- To progress, science must reason under uncertainty
- This work is the first rigorous UQ accounting for nuclear matter
- All code is publicly available
- This promotes reproducibility and extendability

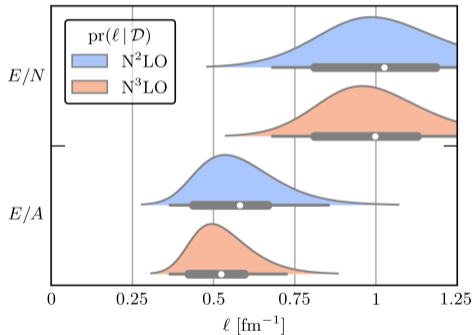
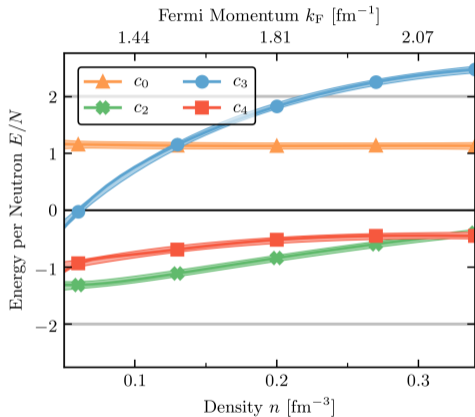
Thank you!

buqeye.github.io



Model Checking Diagnostics

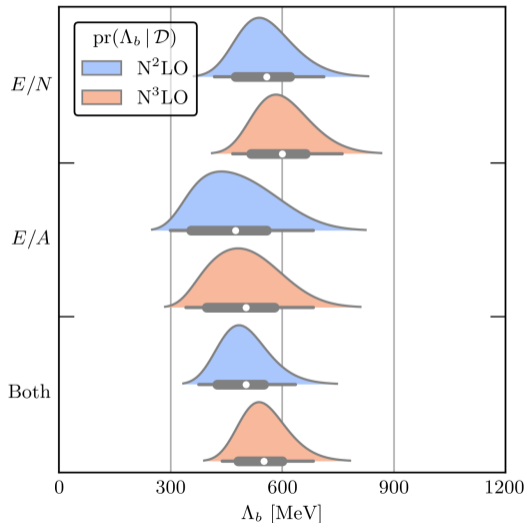
Observable coefficients



Breakdown scale estimation

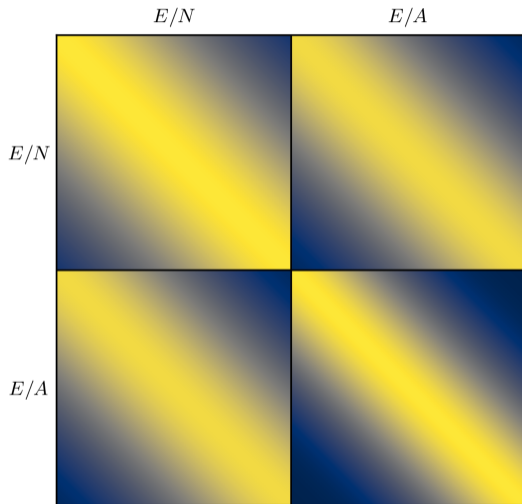
$$Q(k_F) = \frac{k_F}{\Lambda_b}$$

- k_F is the fermi momentum
- in 1-1 correspondence with the density n
- $\Lambda_b \approx 600$ MeV agrees with nucleon-nucleon scattering predictions



Multi-task correlations

- Each diagonal quadrant shows correlations within either E/N or E/A
- Diagonals are densities that are close together; off-diagonals are densities that are far apart
- Off-diagonal quadrants show correlations **between** E/N and E/A
- Yellow means highly correlated, blue means less correlated



Model checking diagnostics

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Does our model refer to reality? How can we check?

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Assumptions

1. c_n are iid stationary GPs

Tests

1. Define a metric to measure GP-ness

Model checking diagnostics

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Model checking diagnostics

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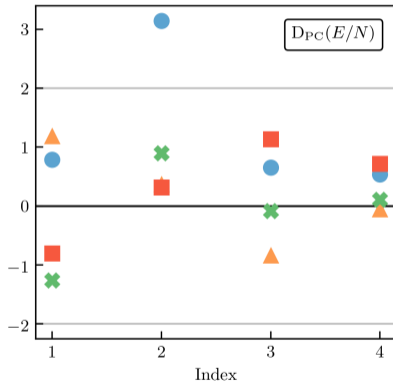
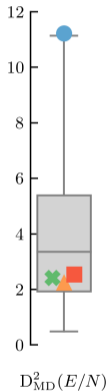
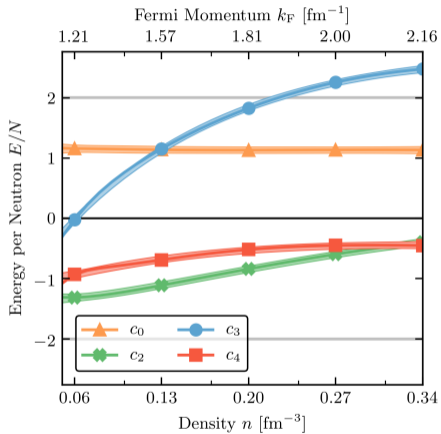
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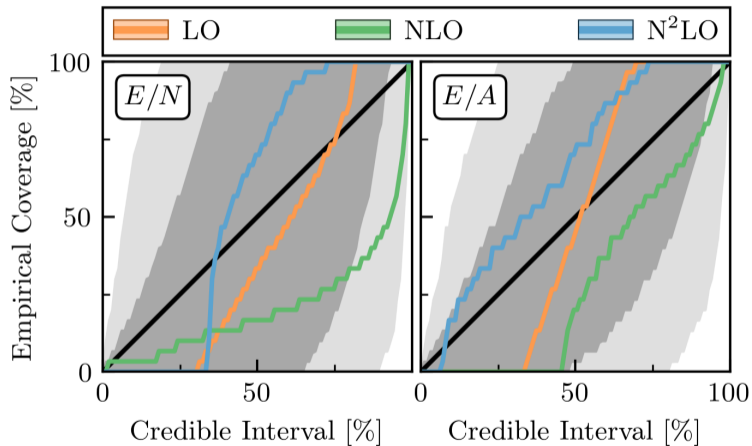
1. Define a metric to measure GP-ness
2. Credible interval diagnostic

- See Bastos & O'Hagan (2009) "Diagnostics for Gaussian Process Emulators"
- But we have **multiple** curves on which to test

Neutron matter diagnostics



Neutron matter diagnostics



- PREx uses parity violating electron scattering to probe the size of neutrons inside a 208-Pb nucleus.
- The error bars are only 1σ
- At 2σ , it agrees with everything

