BBGKY hierarchy for quantum error mitigation

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Motivation

Numerical simulation of many-body physical systems is classically difficult. Such systems can be studied for instance by

- Monte Carlo methods, but they suffer the sign problem
- ► **Hierarchies**, but their **truncation** introduces inaccuracies

Quantum computers to avoid both issues: they are noisy, but that can be **mitigated**. How can the **BBGKY hierarchy** help to mitigate quantum errors?

Improving ZNE with BBGKY

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The proposed $\langle n \rangle_0$ are interpolated in time with a Bernstein polynomial, giving access to time derivatives. The former are then required to satisfy the additional BBGKY constraints, producing an improved $\langle n \rangle_{\emptyset}$ extrapolation.





BBGKY hierarchy [1]

Consider a quantum spin model of sites $S = \{1, \ldots, N\}$ with

$$H = \frac{1}{2} \sum_{i \in S} h_i^{\mu} \sigma_i^{\mu} + \frac{1}{4} \sum_{\substack{i,j \in S \\ i < j}} V_{ij}^{\mu\nu} \sigma_i^{\mu} \sigma_j^{\nu}$$

Let $A \subseteq S$ with $\{\mu_i\}_{i \in A}$ be a Pauli string. The **BBGKY equation** associated to A of $\{\mu_i\}_{i \in A}$ directions is

$$\frac{\mathrm{d}}{\mathrm{d}t} \left\langle \prod_{i \in A} \sigma_i^{\mu_i} \right\rangle = \sum_{\substack{i,j \in A \\ i \neq j}} \frac{V_{ij}^{\mu_i \nu}}{2} \varepsilon_{\mu_j \nu \lambda} \left\langle \sigma_j^{\lambda} \prod_{k \in A \setminus \{i,j\}} \sigma_k^{\mu_k} \right\rangle$$
$$+ \sum_{i \in A} h_i^{\lambda} \varepsilon_{\mu_i \lambda \nu} \left\langle \sigma_i^{\nu} \prod_{j \in A \setminus \{i\}} \sigma_j^{\mu_j} \right\rangle$$
$$+ \sum_{\substack{i \in A \\ j \notin A}} \frac{V_{ij}^{\mu \nu}}{2} \varepsilon_{\mu_i \mu \lambda} \left\langle \sigma_i^{\lambda} \sigma_j^{\nu} \prod_{k \in A \setminus \{i\}} \sigma_k^{\mu_k} \right\rangle$$

Preliminary results

Consider the lattice Schwinger model [3] of N = 4 sites at initial state $|0101\rangle$

$$\begin{split} H &= \frac{x}{2} \sum_{i=1}^{N-1} \left(\sigma_i^x \sigma_{i+1}^x + \sigma_i^y \sigma_{i+1}^y \right) + \frac{1}{2} \sum_{\substack{i,j \in S \\ i < j}} (N - j + \lambda) \sigma_i^z \sigma_j^z \\ &+ \sum_{i=1}^{N-1} \left(\frac{N}{4} - \frac{1}{2} \left[\frac{i-1}{2} \right] + l_0 (N - i) \right) \sigma_i^z - \frac{m}{g} \sqrt{x} \sum_{i \in S} (-1)^i \sigma_i^z \end{split}$$

with parameters $(x, \lambda, l_0, m/g) = (2, 1, 0, 10^{-3})$. Measure the total charge and particle number observables

$$Q = \frac{1}{2} \sum_{i \in S} \sigma_i^z \qquad \qquad P = \frac{N}{2} - \frac{1}{2} \sum_{i \in S} (-1)^i \sigma_i^z$$

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Schematically, for n = |A|,

$$\begin{array}{c} \mathbf{o} \\ \frac{\mathrm{d}}{\mathrm{d}t} \left\langle n \right\rangle \end{array} = \begin{array}{c} \mathbf{o} \\ \left\langle n - 1 \right\rangle \end{array} \left\langle n \right\rangle \quad \left\langle n + 1 \right\rangle \end{array}$$

Different choices of A generate a **hierarchy** of equations, each of which composed of a **polynomial** in *n* amount of terms, which in principle can be used to mitigate the effects of quantum errors.

Zero noise extrapolation (ZNE) [2]

The time evolution of the system is obtained by **Trotterization**, with time steps U of duration Δt .



Different **unitary foldings** give different realizations of the same quantum circuit. Each realization produces a noisy observable







The zero noise extrapolation $\langle n \rangle_0$ is obtained as the noiseless **limit** $\varepsilon \to 0$ of the least squares polynomial of degree d

$$\langle n \rangle (\varepsilon) = \langle n \rangle_0 + a_1 \varepsilon + \dots + a_d \varepsilon^d \quad \xrightarrow{\varepsilon \to 0} \quad \langle n \rangle_0 \approx \langle n \rangle_0$$

References

[1] T. Cox. Aspects of Decoherence in Qubit Systems. PhD thesis, The University of British Columbia, 2019.

[2] K. Temme S. Bravyi J.M. Gambetta. Error Mitigation for Short-Depth Quantum Circuits. *Phys. Rev. Lett.*, 119(18):180509, 2017.

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