# **Exploring Generative Networks for Manifolds with Non-Trivial Topology**

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### **Content**

- ●**Generative Networks**
- ●**Topology Problem**
- ●**Our network**
- $\bullet$  2D- $\phi$ <sup>4</sup> theory

#### **Generative Networks**

●Estimate Observables via annealed importance sampling,

$$
\mathbb{E}_{\phi \sim \mu(\phi)}[\mathcal{O}(\phi)] = \int d\phi \frac{\mu(\phi)}{\mathcal{Z}} \mathcal{O}(\phi) \approx \frac{\sum_{\phi \sim \mathcal{Q}(\phi)} \omega(\phi) \mathcal{O}(\phi)}{\sum_{\phi \sim \mathcal{Q}(\phi)} \omega(\phi)}, \quad \omega(\phi) = \frac{\mu(\phi)}{\mathcal{Q}(\phi)}.
$$

 $\mu(\phi)$ : un-normalized target distribution.  $Q(\phi)$ : normalized model distribution. : normalization constant

Precondition

- 1. Support set  $supp\{\mu\} \subset supp\{Q\};$ <br>2. Distribution  $Q$  pot for gway from  $\mu$ , Support set  $supp\{\mu\} = \{\forall \phi | \mu \neq 0\}$
- 2. Distribution Q not far away from  $\mu$ .

Q could be estimated by neural networks!

#### **Generative Networks**

●Estimate Observables via annealed importance sampling,

$$
\mathbb{E}_{\phi \sim \mu(\phi)}[O(\phi)] = \int d\phi \frac{\mu(\phi)}{Z} O(\phi) \approx \frac{\sum_{\phi \sim Q(\phi)} \omega(\phi) O(\phi)}{\sum_{\phi \sim Q(\phi)} \omega(\phi)}, \quad \omega(\phi) = \frac{\mu(\phi)}{Q(\phi)}.
$$

Available neural network:

#### Train on Function

#### Normalizing flow (NF),

[Kim A. Nicoli, et al., arXiv: 2007.07115 [hep-lat]] [Ryan Abbott, et al., arXiv:2207.08945 [hep-lat]] Continuous flow,

[Mathis Gerdes, et al., arXiv:2207.00283 [hep-lat]]

#### Hamiltonian neural network,

[Sam Greydanus, et al., arXiv:1906.01563 [cs.NE]] Stochastic NF

[Michele Caselle. et al., arXiv:2210.03139 [hep-lat]]

#### Train on Data

Langevin based diffusion model,

[Lingxiao Wang,et al., arXiv:2309.17082 [hep-lat]]

A-Nice-MC [Jiaming Song, et al., arXiv:1706.07561 [stat.M]]

NF using adversarial learning

[Vikas Kanaujia, et al., arXiv:2401.15948 [cs.LG]]

Topology: Geometry feature preserved under continuous maps. Connectivity, Compactness, Countability, etc.



Triple Ring: a disconnected and compact Manifold. Normal Distribution: <sup>a</sup> simple



connected and non-compact Manifold.

●Invertible Flows are topology preserved map

$$
Q(\phi) = P(z) \left| \frac{\partial \phi}{\partial z} \right| - 1
$$
 *P(z)*: the prior and  
Normal distribution

 $-2$ 

Flow models are differentible,



Flow models are differentible,<br> **Modeled manifold is diffeomorphism**<br> **Continuous and invertible.**<br> **Continuous and invertible.** to the prior manifold



Modeled manifold: 1. open ring 2. simple connected and non-compact 3. outer rings missing

- Avoid dependence of the choice of hyper-parameters.
	- 1. Ideal case to the worst output from the network;
	- 2. Improve the architecture.
- $\bullet$  The diffusion network learns from the action.
	- 1.Drift and diffusion for forward and backward are estimated by two independent networks.
	- 2.Results from diffusion will be different from one learning from data.

#### ●Langevin Based Diffusion may suffer from topology problem

carefully chosen hype-parameters and prior will lead to a better result.



●The expected worst outcome for ideal case (understand from topology side)

$$
z_{t+1} = z_t - K_t(z_t)dt + \sqrt{2dt}D_t(z_t)\eta_t, \qquad \eta_t \text{-Gauss}
$$

- 1. Ideal case: $K_t(z_t)$  and  $D_t(z_t)$  are continuous maps
- 2. Continuous map preserves topology
- 3. For two connected vector space,  $X$  and  $Y$ ,

The vector space  $Z_1 = \{x + y | \forall x \in X, \forall y \in Y\}$  and  $Z_2 = \{ xy | \forall x \in X, \forall y \in Y, \}$  are connected vector space.

• The modelled manifold is connected.

#### ●Langevin Based Diffusion may suffer from topology problem

carefully chosen hype-parameters and prior will lead to a better result.



### **Our network**

![](_page_10_Figure_1.jpeg)

 $P_{f,t}(z_{f,t} | z_t, s(z_t))$ : forward process  ${P}_{b,t}(z_{b,t} | z_t, s(z_t))$ : backward process  $s(z_t)$ : action

- $P_{b,t}(z_{b,t} | z_t, s(z_t))$  is the inverse process of  $P_{f,t}(z_{f,t} | z_t, s(z_t));$
- $P_{f,t}(z_{f,t} | z_t, s(z_t)), P_{b,t}(z_{b,t} | z_t, s(z_t))$  and  $P({z}_{f,t}, {z}_t, {z}_{b,t})$  estimated by networks;
- $P_{f,t}(z_{f,t} | z_t, s(z_t)), P_{b,t}(z_{b,t} | z_t, s(z_t))$ have time dependence;
- Possible way to generate multiple and well seperated models. 11

![](_page_11_Figure_0.jpeg)

Trian network by inverse Kullback–Leibler (KL) divergence

#### **Our network**

![](_page_12_Figure_1.jpeg)

- Good samples from correct support set
- Noisy samples

# $2D - \phi^4$  theory

• 2D- $\phi^4$  model has  $\mathbb{Z}_2$  symmetry,  $S(\phi) = S(-\phi)$ ,

$$
S(\phi) = \sum_{x \in A} -2\kappa \sum_{\hat{\mu}=1}^{2} \phi_x \phi_{x+\hat{\mu}} + (1 - 2\lambda) \phi_x^2 + \lambda \phi_x^4
$$
  
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M = \frac{1}{|A|} \sum_{x \in A} \phi
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# $2D - \phi^4$  theory

• 2D- $\phi^4$  model has  $\mathbb{Z}_2$  symmetry,  $S(\phi) = S(-\phi)$ ,

$$
S(\phi) = \sum_{x \in \Lambda} -2\kappa \sum_{\hat{\mu}=1}^{2} \phi_x \phi_{x+\hat{\mu}} + (1 - 2\lambda) \phi_x^2 + \lambda \phi_x^4
$$

![](_page_14_Figure_3.jpeg)

$$
|A| = N_L \times N_t = 64 \times 32
$$
  

$$
\lambda = 0.022 \quad \kappa = 0.3
$$

$$
M = \frac{1}{|A|} \sum_{x \in A} \phi
$$

$$
\lambda=0.022, \ \kappa=0.3
$$

• Invertible NF and diffusion models recover one peak,

• Stochastic mean pathway help generate  $\mathbb{Z}_2$  configurations

#### Summary

- ●Invertible flow based and diffusion (possible) methods suffer from topology problem if the network learns from the action;
- Some part of configurations may not be generated with invertible flows and diffusion models;
- ●Stochastic mean pathway helps sample for seperated models.