# Exploring Generative Networks for Manifolds with Non-Trivial Topology

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### Content

- •Generative Networks
- •Topology Problem
- •Our network
- •2D- $\phi^4$  theory

#### **Generative Networks**

• Estimate Observables via annealed importance sampling,

$$\mathbb{E}_{\phi \sim \mu(\phi)}[\mathcal{O}(\phi)] = \int d\phi \frac{\mu(\phi)}{\mathcal{Z}} \mathcal{O}(\phi) \approx \frac{\sum_{\phi \sim Q(\phi)} \omega(\phi) \mathcal{O}(\phi)}{\sum_{\phi \sim Q(\phi)} \omega(\phi)}, \quad \omega(\phi) = \frac{\mu(\phi)}{Q(\phi)}.$$

 $\mu(\phi)$ : un-normalized target distribution.  $Q(\phi)$ : normalized model distribution.  $\mathcal{Z}$ : normalization constant

Precondition

- 1. Support set  $supp\{\mu\} \subset supp\{Q\}$ ;
- 2. Distribution Q not far away from  $\mu$ .

Support set  $supp\{\mu\} = \{\forall \phi | \mu \neq 0\}$ 

*Q* could be estimated by neural networks!

#### **Generative Networks**

• Estimate Observables via annealed importance sampling,

$$\mathbb{E}_{\phi \sim \mu(\phi)}[\mathcal{O}(\phi)] = \int d\phi \frac{\mu(\phi)}{Z} \mathcal{O}(\phi) \approx \frac{\sum_{\phi \sim Q(\phi)} \omega(\phi) \mathcal{O}(\phi)}{\sum_{\phi \sim Q(\phi)} \omega(\phi)}, \quad \omega(\phi) = \frac{\mu(\phi)}{Q(\phi)}.$$

Available neural network:

#### **Train on Function**

#### Normalizing flow (NF),

[Kim A. Nicoli, et al., arXiv:2007.07115 [hep-lat]] [Ryan Abbott, et al., arXiv:2207.08945 [hep-lat]] **Continuous flow,** 

[Mathis Gerdes, et al., arXiv:2207.00283 [hep-lat]]

#### Hamiltonian neural network,

[Sam Greydanus, et al., arXiv:1906.01563 [cs.NE]] Stochastic NF

[Michele Caselle. et al., arXiv:2210.03139 [hep-lat]]

#### Train on Data

Langevin based diffusion model, [Lingxiao Wang, et al., arXiv:2309.17082 [hep-lat]]

A-Nice-MC [Jiaming Song, et al., arXiv:1706.07561 [stat.M]]

NF using adversarial learning

[Vikas Kanaujia, et al., arXiv:2401.15948 [cs.LG]]

Topology: Geometry feature preserved under continuous maps.



Triple Ring: a disconnected and compact Manifold.



Normal Distribution

Normal Distribution: a simple connected and non-compact Manifold.

Invertible Flows are topology preserved map

$$Q(\phi) = P(z) \left| \frac{\partial \phi}{\partial z} \right|^{-1}$$

P(z): the prior and Normal distribution

Flow models are differentible, continuous and invertible.



Modeled manifold is diffeomorphism to the prior manifold





Modeled manifold: 1. open ring 2. simple connected and non-compact 3. outer rings missing

- Avoid dependence of the choice of hyper-parameters.
  - 1. Ideal case to the worst output from the network;
  - 2. Improve the architecture.
- The diffusion network learns from the action.
  - 1. Drift and diffusion for forward and backward are estimated by two independent networks.
  - 2. Results from diffusion will be different from one learning from data.

#### •Langevin Based Diffusion may suffer from topology problem

carefully chosen hype-parameters and prior will lead to a better result.



• The expected worst outcome for ideal case (understand from topology side)

$$z_{t+1} = z_t - K_t(z_t)dt + \sqrt{2dt}D_t(z_t)\eta_t, \qquad \eta_t \sim \text{Gauss}$$

1. Ideal case: $K_t(z_t)$  and  $D_t(z_t)$  are continuous maps

- 2. Continuous map preserves topology
- 3. For two connected vector space, *X* and *Y*,

The vector space  $Z_1 = \{x + y | \forall x \in X, \forall y \in Y\}$  and  $Z_2 = \{xy | \forall x \in X, \forall y \in Y, \}$  are connected vector space.

• The modelled manifold is connected.

#### •Langevin Based Diffusion may suffer from topology problem

carefully chosen hype-parameters and prior will lead to a better result.



#### Our network



 $P_{f,t}(z_{f,t}|z_t, s(z_t))$ : forward process  $P_{b,t}(z_{b,t}|z_t, s(z_t))$ : backward process  $s(z_t)$ : action

- $P_{b,t}(z_{b,t}|z_t, s(z_t))$  is the inverse process of  $P_{f,t}(z_{f,t}|z_t, s(z_t))$ ;
- $P_{f,t}(z_{f,t}|z_t, s(z_t)), P_{b,t}(z_{b,t}|z_t, s(z_t))$  and  $P(z_{f,t}, z_t, z_{b,t})$  estimated by networks;
- $P_{f,t}(z_{f,t}|z_t, s(z_t)), P_{b,t}(z_{b,t}|z_t, s(z_t))$ have time dependence;
- Possible way to generate multiple and well seperated models.



Trian network by inverse Kullback–Leibler (KL) divergence

#### Our network



- Good samples from correct support set
- Noisy samples

## **2D**- $\phi^4$ theory

• 2D- $\phi^4$  model has  $\mathbb{Z}_2$  symmetry,  $S(\phi) = S(-\phi)$ ,

$$S(\phi) = \sum_{x \in \Lambda} -2\kappa \sum_{\hat{\mu}=1}^{2} \phi_{x} \phi_{x+\hat{\mu}} + (1-2\lambda) \phi_{x}^{2} + \lambda \phi_{x}^{4}$$

$$|\Lambda| = N_{L} \times N_{t} = 64 \times 32$$

$$\lambda = 0.022, \ \kappa = 0.3$$

$$M = \frac{1}{|\Lambda|} \sum_{x \in \Lambda} \phi$$
Flow models for multiple peak
[Daniel C. Hackett, arXiv:2107.00734[hep-lat]]
$$P_{mix}(\phi) = P(\phi) \sum_{b} \frac{t_{b}^{-1} \circ \phi}{P(t_{a} \circ t_{b}^{-1} \circ \phi)} \left| \frac{\partial t_{a} \circ z}{\partial \phi} \right|$$

$$I. \{t_{a}\} : a finite group of invertible transformation$$
2. break invertibility

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• Stochastic mean pathway help generate  $\mathbb{Z}_2$  configurations

#### Summary

- Invertible flow based and diffusion (possible) methods suffer from topology problem if the network learns from the action;
- •Some part of configurations may not be generated with invertible flows and diffusion models;
- Stochastic mean pathway helps sample for seperated models.