



Caltech

Detecting ultralight dark matter with trapped-ion interferometers

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with Diego Blas, Sebastian A. R. Ellis, and John R. Ellis

Based on 2507.XXXX

PASCOS 2025

The dark matter landscape

10^{-22} eV

DM mass range

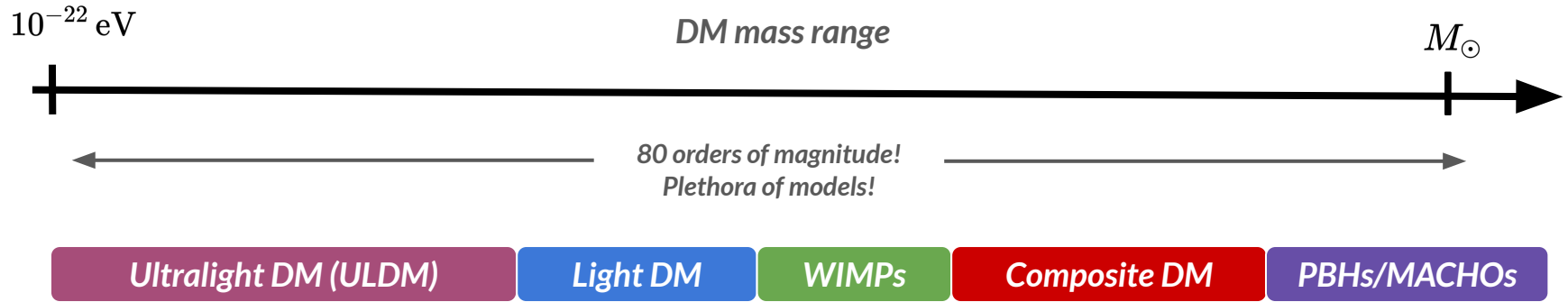
$M_{\odot}$



The dark matter landscape



The dark matter landscape

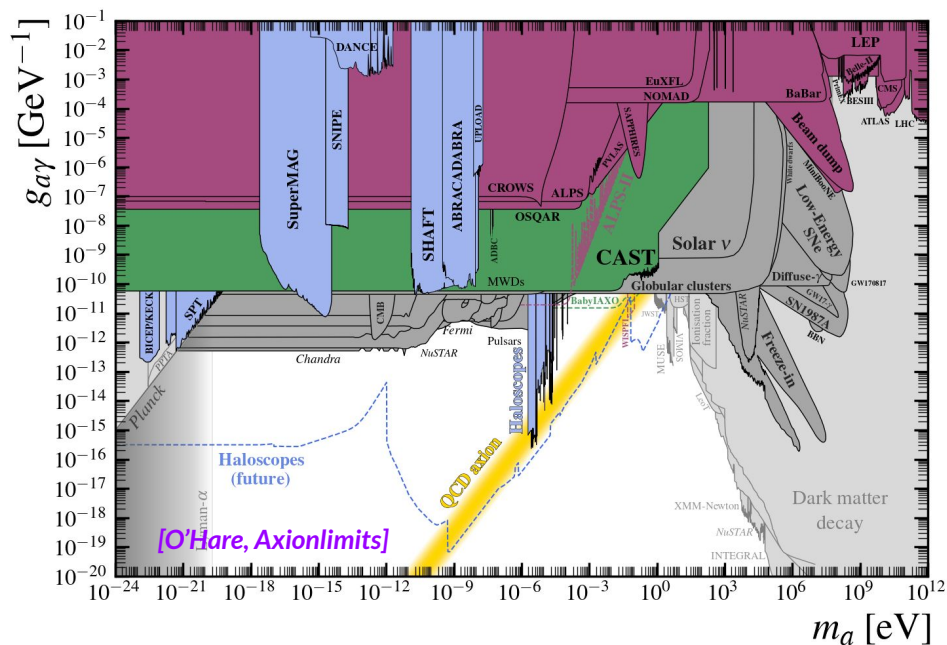


Many different interactions & many different probes

The dark matter landscape

Many different interactions & many different probes

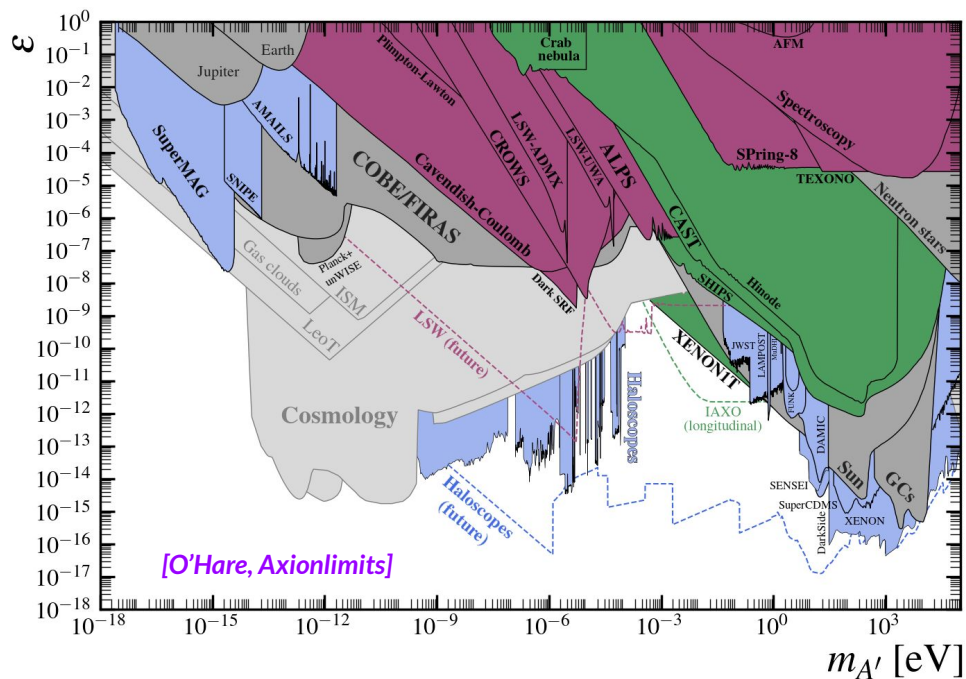
Examples: coupling to photons, axion-like particles (ALPs)



The dark matter landscape

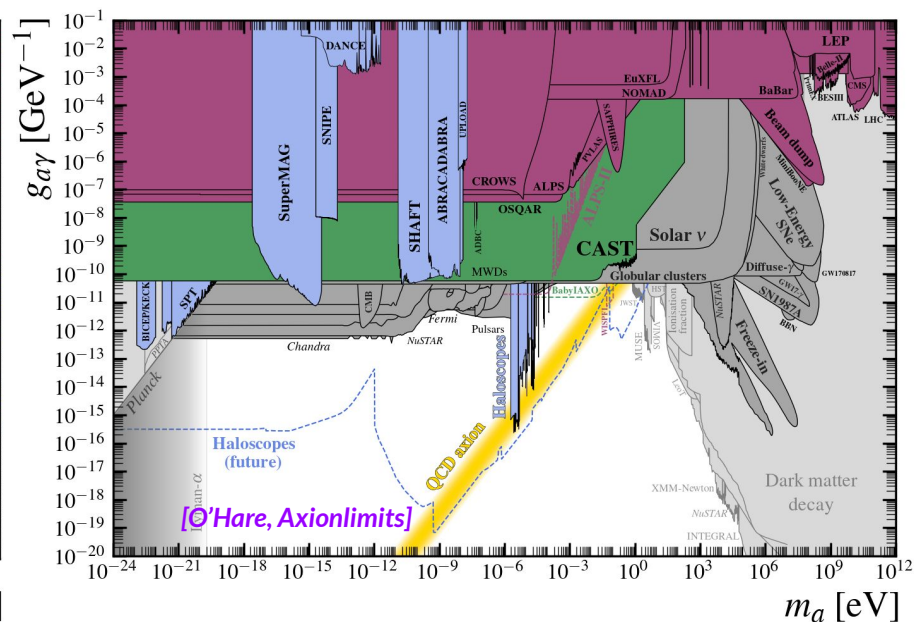
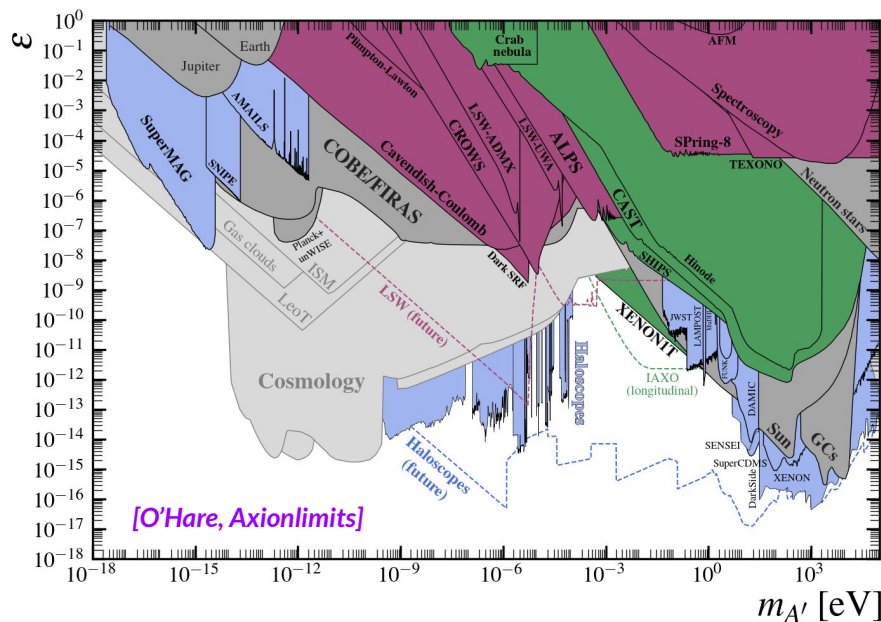
Many different interactions & many different probes

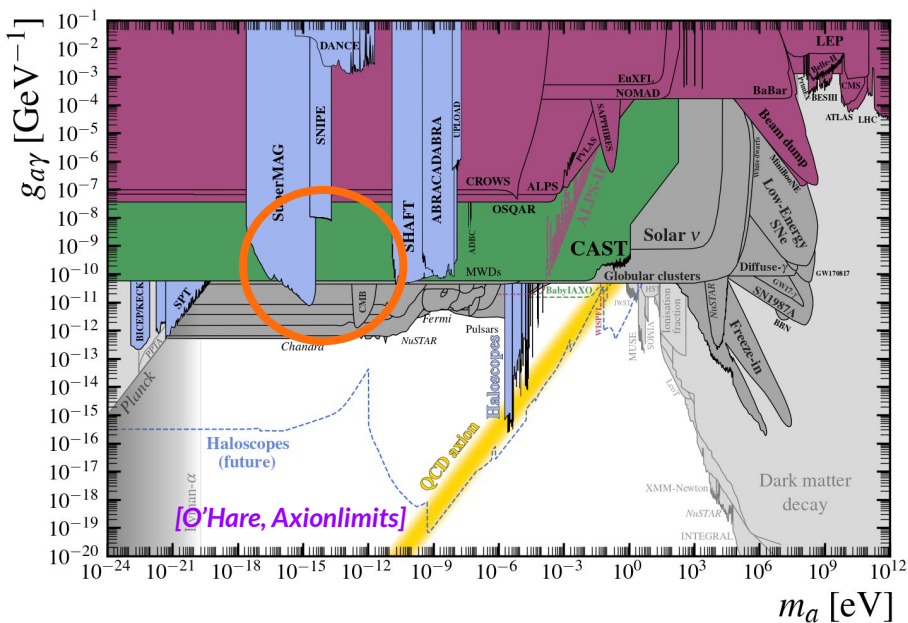
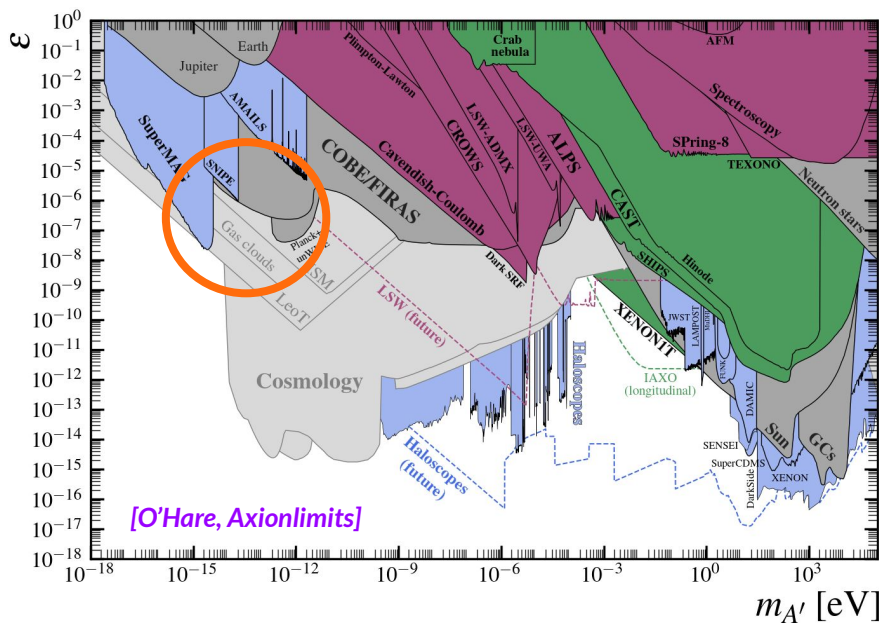
Examples: coupling to photons, kinetically-mixed dark photons



Motivation

Can we leverage quantum sensing techniques to probe unexplored regions of DM model space with tabletop experiments?





Key features of trapped-ion interferometry

Proposal developed by Wes Campbell and Paul Hamilton for rotation sensing [JPB, 2017]

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Matter-wave interferometry (Ramsey sequence) with electrically charged states

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Entanglement of spin and motional degrees of freedom

Magnetically-insensitive states -> long coherence times of the excited state

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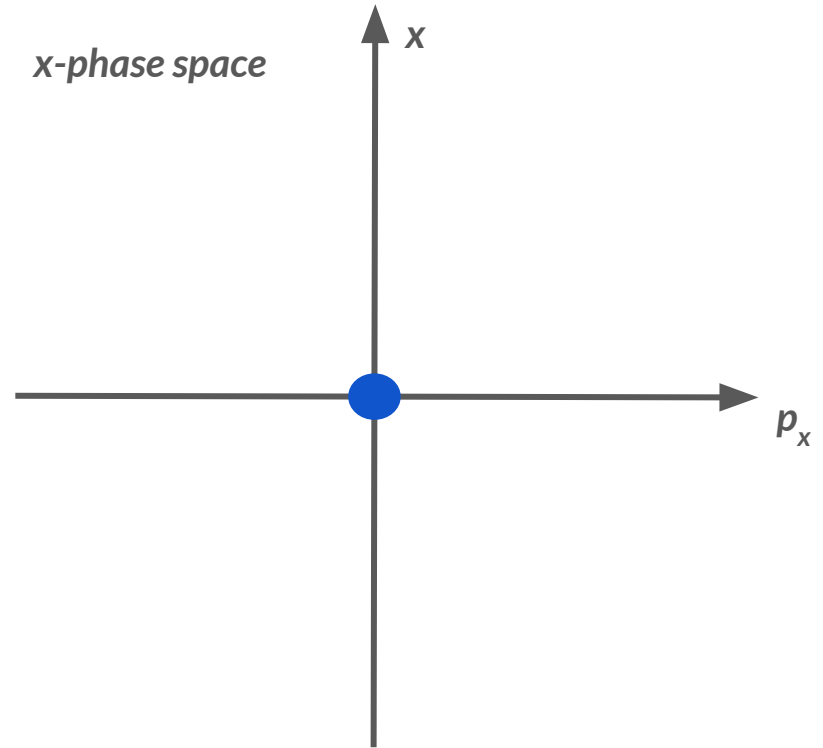
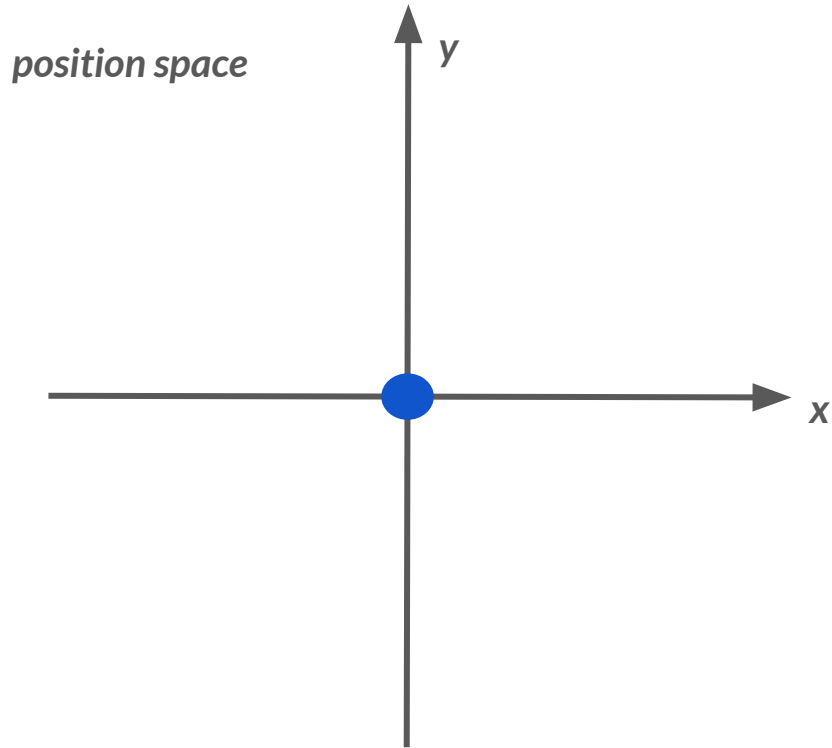
Magnetically-insensitive states -> long coherence times of the excited state

Harmonic and rotationally symmetric potential in 2D

Excellent control over systematics [West, PRA 2019]

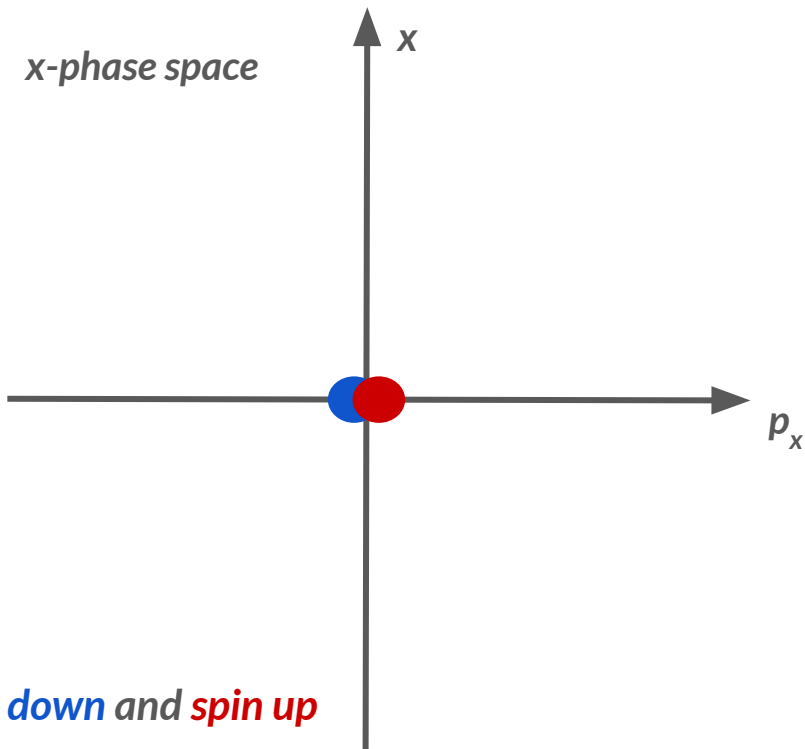
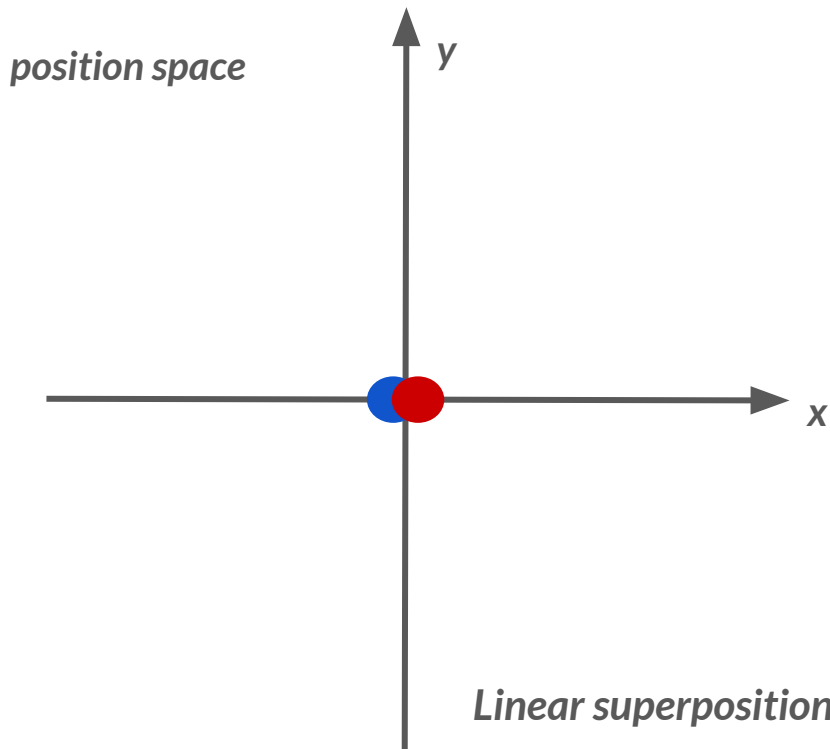
A sketch of trapped-ion interferometry

Step 1: ion is prepared in the *spin down state* and placed at the centre of the trap



A sketch of trapped-ion interferometry

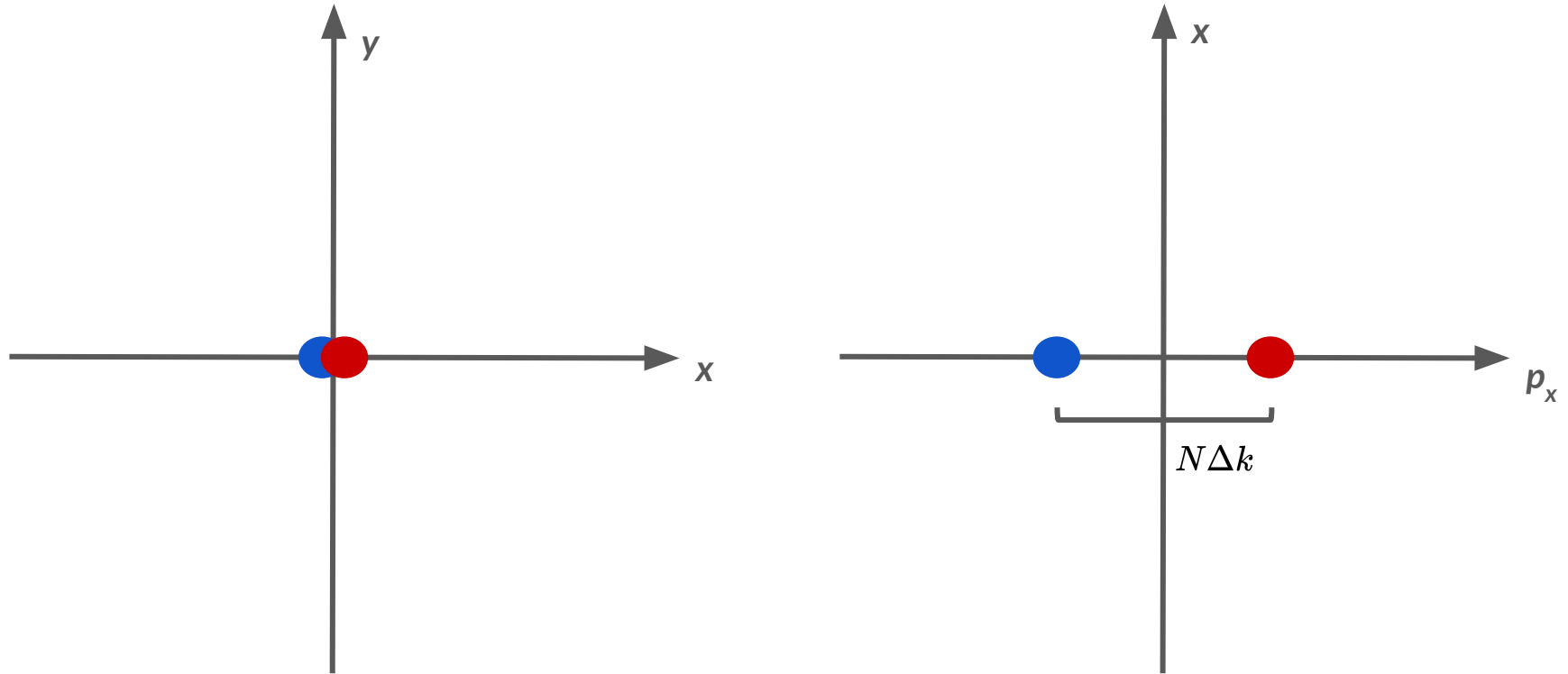
Step 2: apply a beam-splitter pulse



Linear superposition of *spin down* and *spin up*

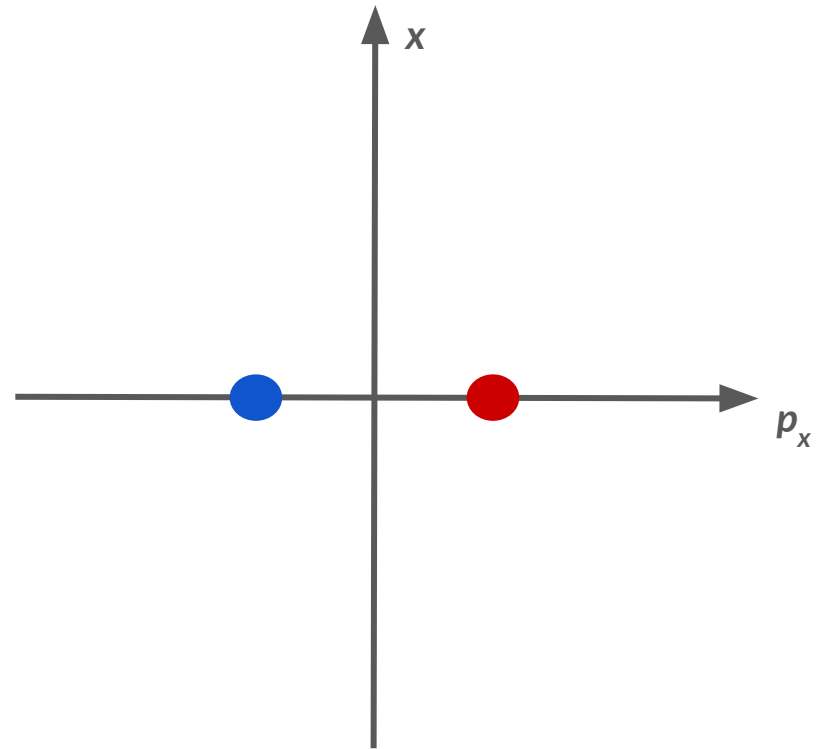
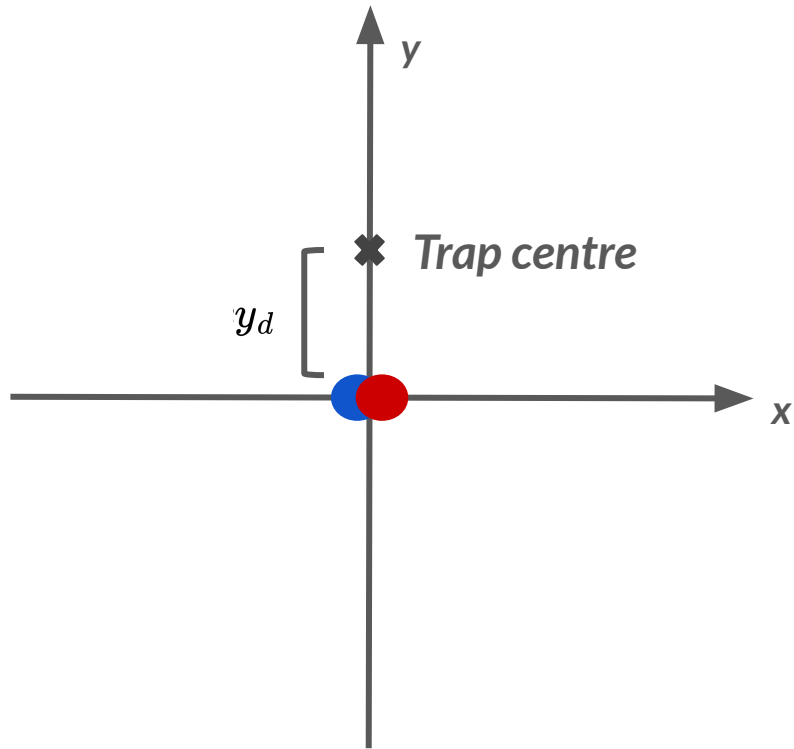
A sketch of trapped-ion interferometry

Step 3: apply N successive spin-dependent laser kicks (SDKs) in the x -direction



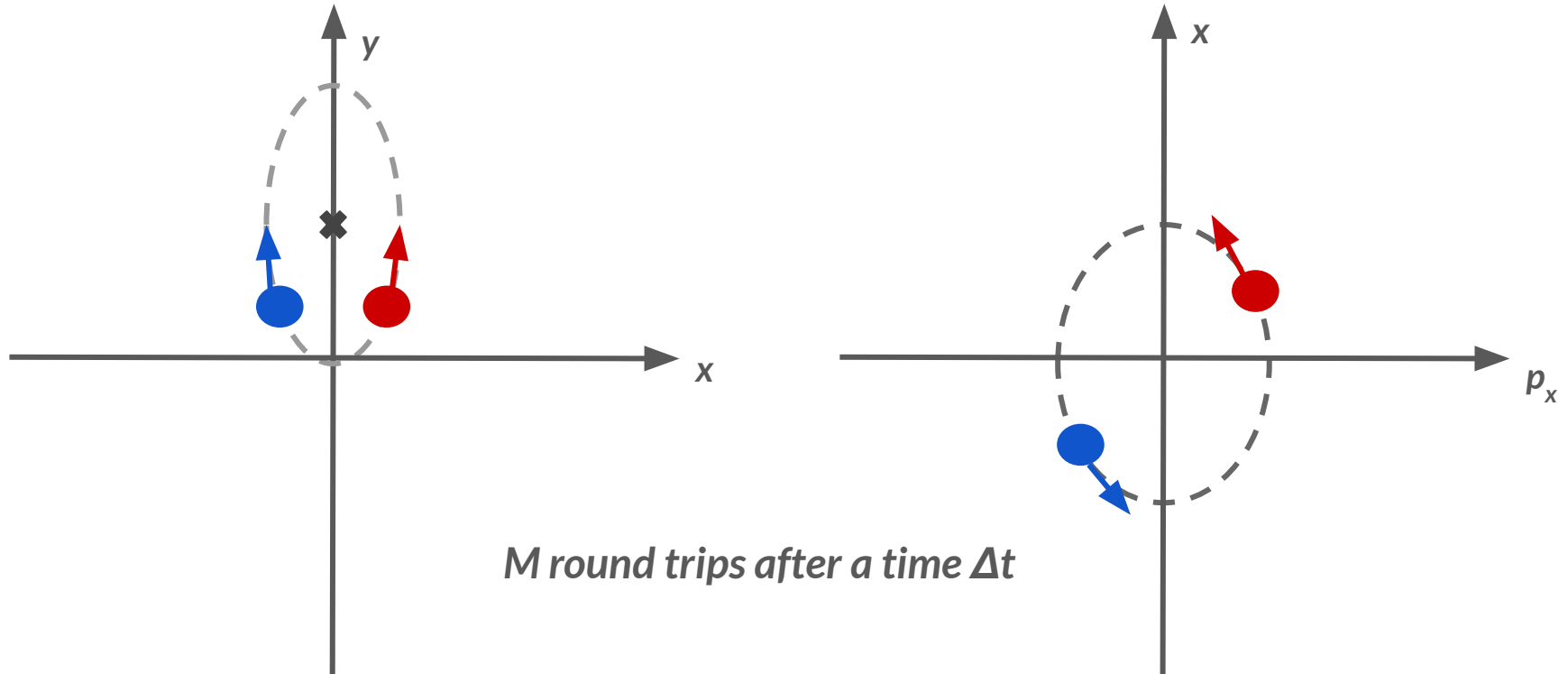
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Step 4: non-adiabatic displacement of the trap centre in the y-direction



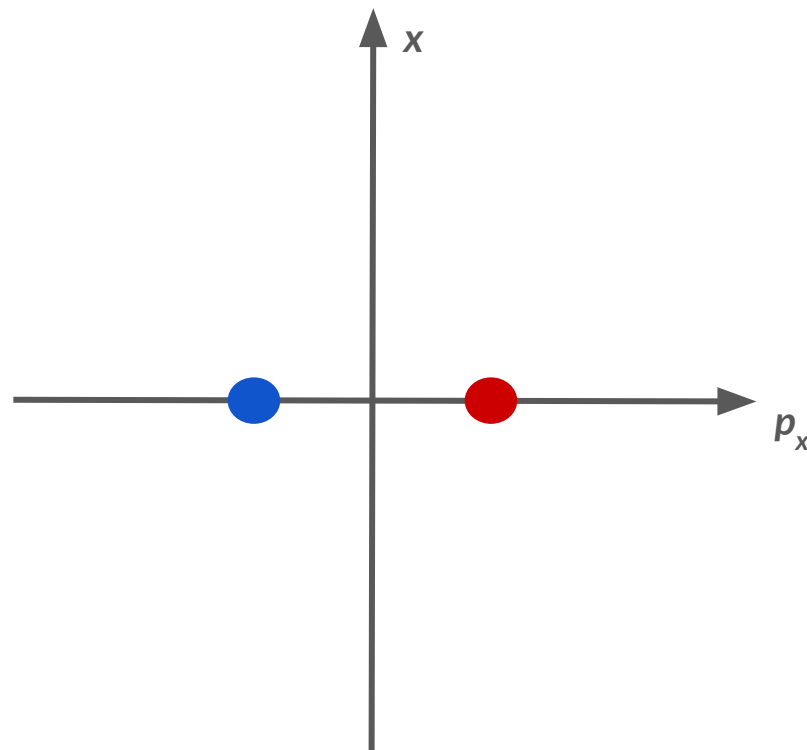
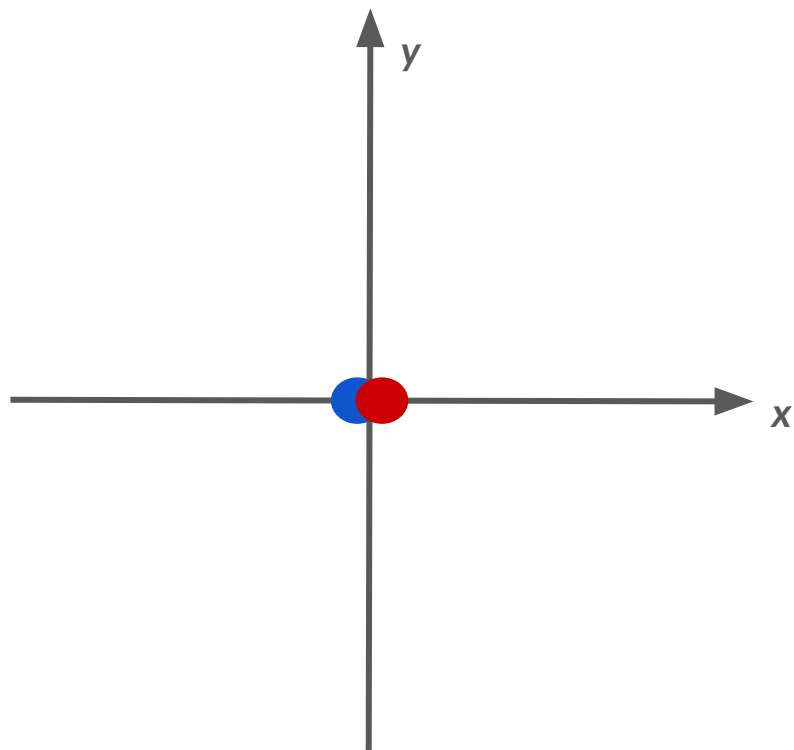
A sketch of trapped-ion interferometry

Step 5: free evolution of the ions in the trap



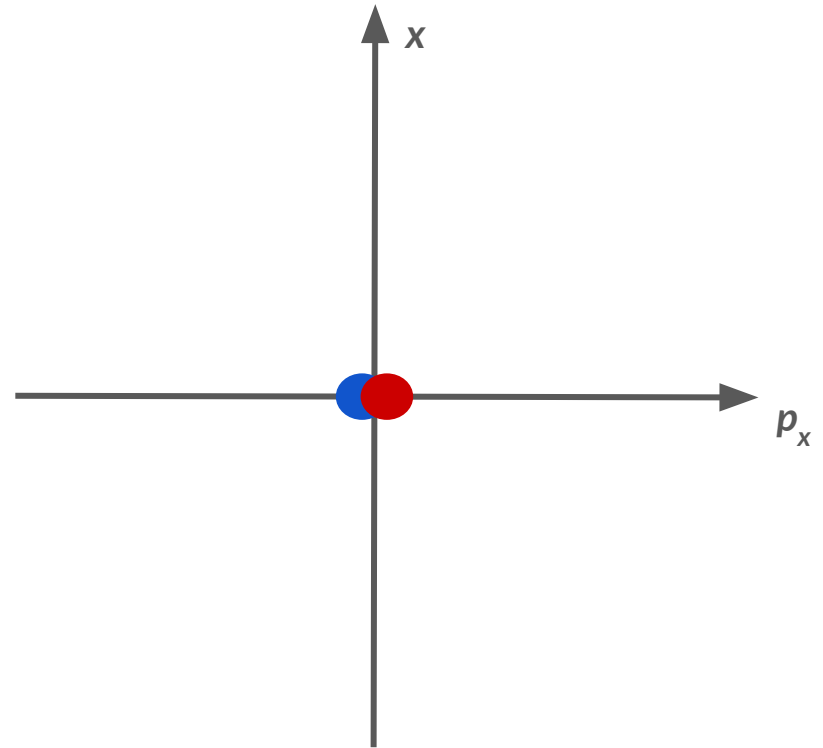
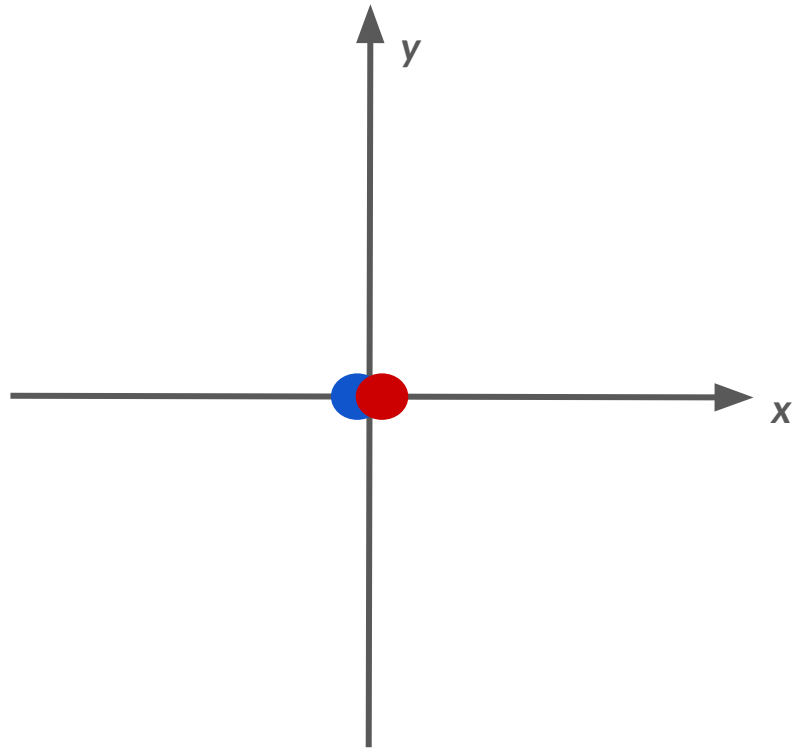
A sketch of trapped-ion interferometry

Step 6: reverse trap displacement non-adiabatically



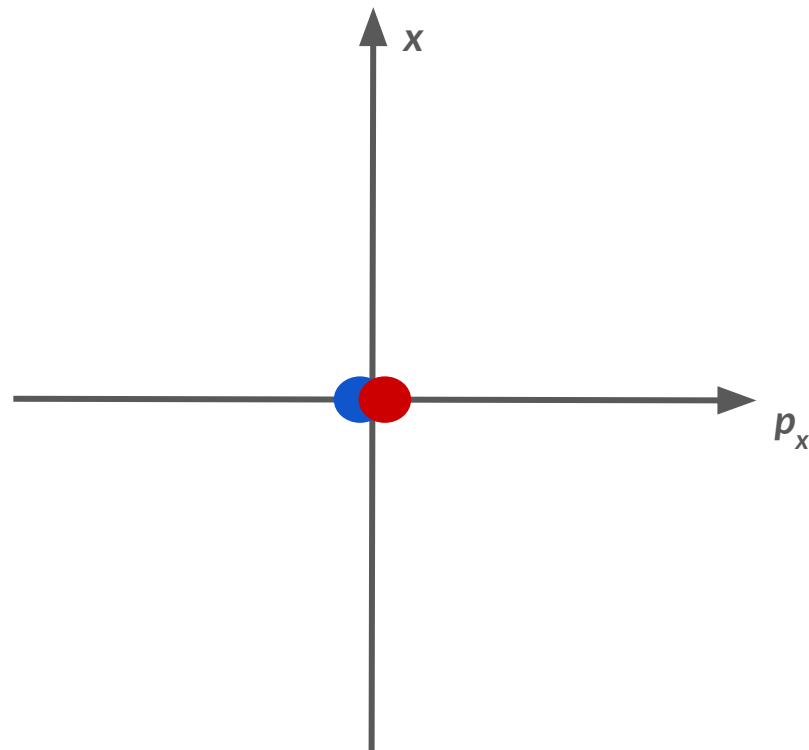
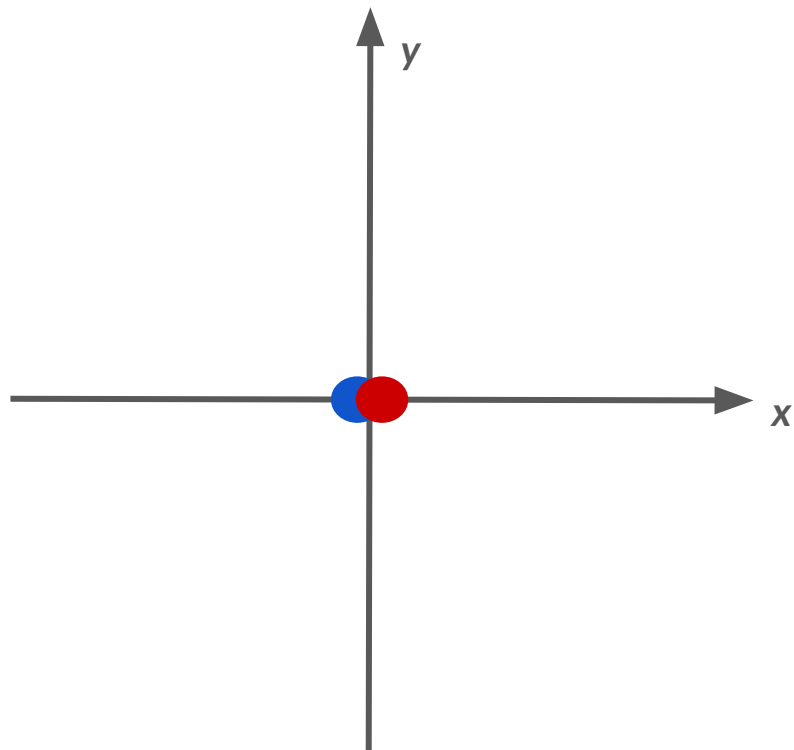
A sketch of trapped-ion interferometry

Step 7: reverse SDKs



A sketch of trapped-ion interferometry

Step 8: measure the ions in the qubit spin states



Trapped-ion interferometers as B-field sensors

Ions evolve in counterpropagating orbital motion

Trapped-ion interferometers as B-field sensors

Ions evolve in counterpropagating orbital motion



Electromagnetic phase shift only depends on the magnetic vector potential

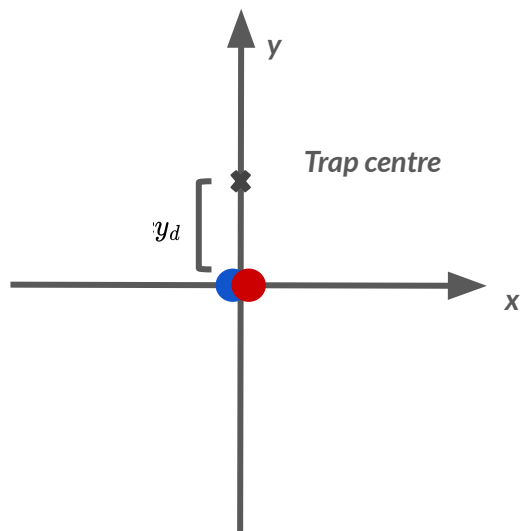
$$\begin{aligned}\Delta\phi &= 2e \oint \mathbf{A} \cdot d\mathbf{l} \\ &\simeq 2e \int_0^{\Delta t} \mathbf{B} \cdot \frac{d\mathbf{S}}{dt} dt\end{aligned}$$

Trapped-ion interferometers as B-field sensors

Ions evolve in counterpropagating orbital motion

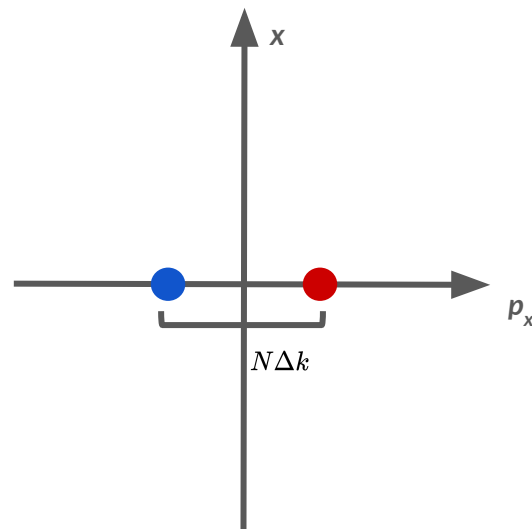


Electromagnetic phase shift only depends on the magnetic vector potential



$$\Delta\phi = 2e \oint \mathbf{A} \cdot d\mathbf{l}$$
$$\simeq 2e \int_0^{\Delta t} \mathbf{B} \cdot \frac{d\mathbf{S}}{dt} dt$$

$$\frac{d\mathbf{S}}{dt} \sim y_d \frac{N\Delta k}{m_{\text{ion}}}$$



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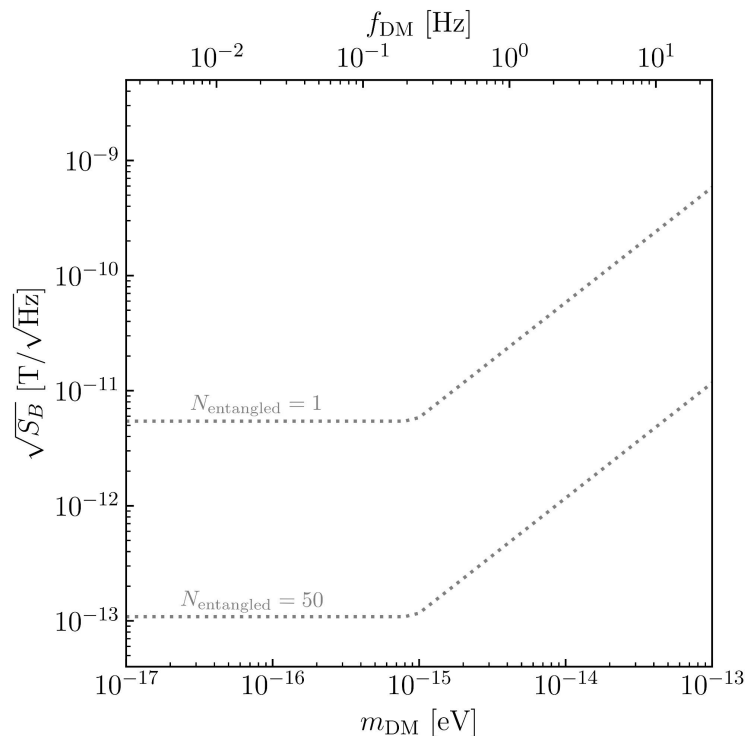
Dynamical Zeeman shift with (motional) magnetic moment

$$\mu_m \sim \mu_B N \Delta k y_d \frac{m_e}{m_{\text{ion}}}$$

Trapped-ion interferometers as B-field sensors

$$\sqrt{S_B} = 5 \times 10^{-12} \text{ T}/\sqrt{\text{Hz}} \left| \text{sinc} \left(\frac{\omega \Delta t}{2} \right) \right|^{-1} \left(\frac{1 \text{ s}}{\Delta t} \right) \left(\frac{1}{N_{\text{GHZ}}} \right)$$

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[Campbell, Hamilton, JPB 2017]

$^{171}\text{Yb}^+$

$\Delta k = 4\pi/355 \text{ nm}$

$N = 100$

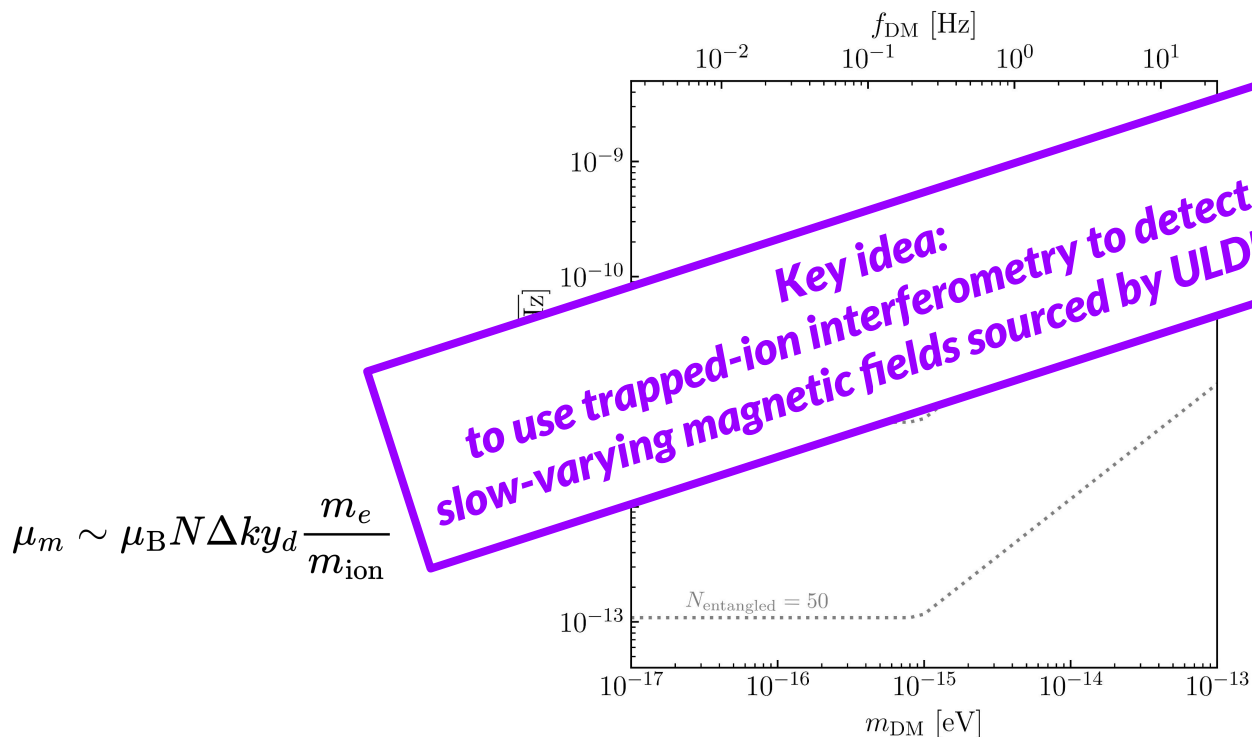
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Models

Kinetically-mixed DPs

ALPs

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$$\mathcal{L} \supset \epsilon m_{A'}^2 A'_{\mu} A^{\mu}$$

$$\mathbf{A}' \sim \frac{\sqrt{2\rho_{\text{DM}}}}{\sqrt{3}m_{A'}} e^{im_{A'}t - i\mathbf{k}\cdot\mathbf{x}} \sum_i \hat{\mathbf{n}}_i e^{i\varphi_i},$$

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$$\mathcal{L} \supset -\frac{g_{a\gamma\gamma}}{4} a \tilde{F}_{\mu\nu} F^{\mu\nu}$$

$$a \sim \frac{\sqrt{2\rho_{\text{DM}}}}{m_a} e^{im_a t - i\mathbf{k}\cdot\mathbf{x} + i\varphi}$$

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ULDM sources e.m. fields with angular frequency m

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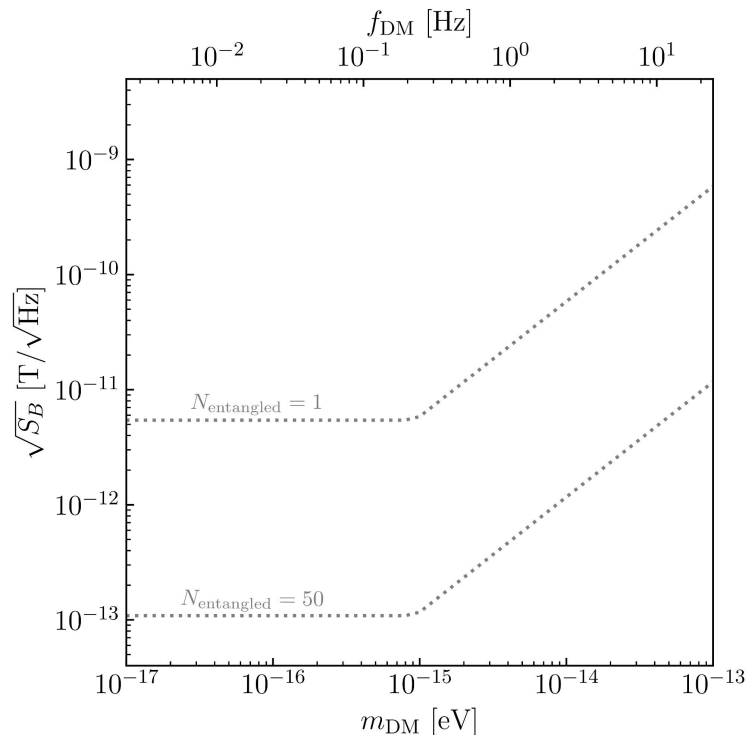
WARNING:
Boundary conditions $\rightarrow$ cavity

$$\nabla \times \mathbf{B} - \partial_t \mathbf{E} = \mathbf{J}_{\text{eff}}$$

ULDM sources e.m. fields with angular frequency m

Which cavity should we use?

Since $\Delta t > 1$ s, a TI would be most sensitive to signals oscillating with frequencies below 1 Hz.

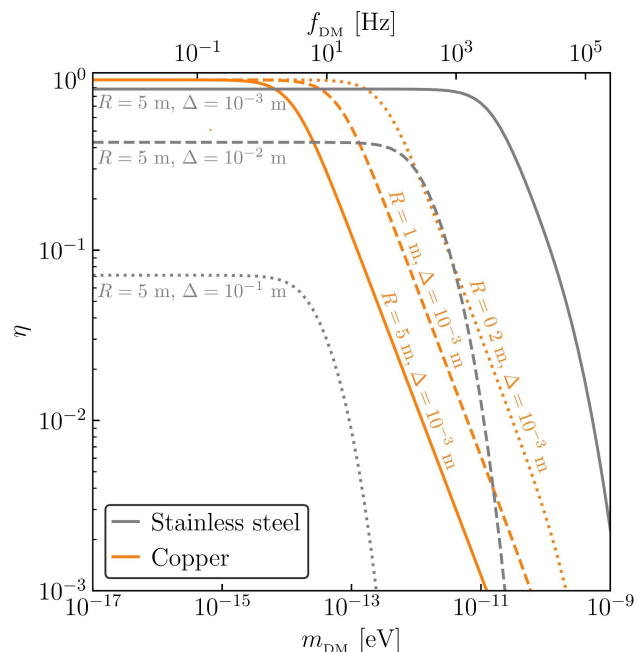


Key point:
Most sensitive to
DM with mass
 $\lesssim 10^{-15}$ eV

Which cavity should we use?

Since $\Delta t > 1$ s, a TI would be most sensitive to signals oscillating with frequencies below 1 Hz.

We expect that shielding in the lab suppresses high-frequency magnetic fields

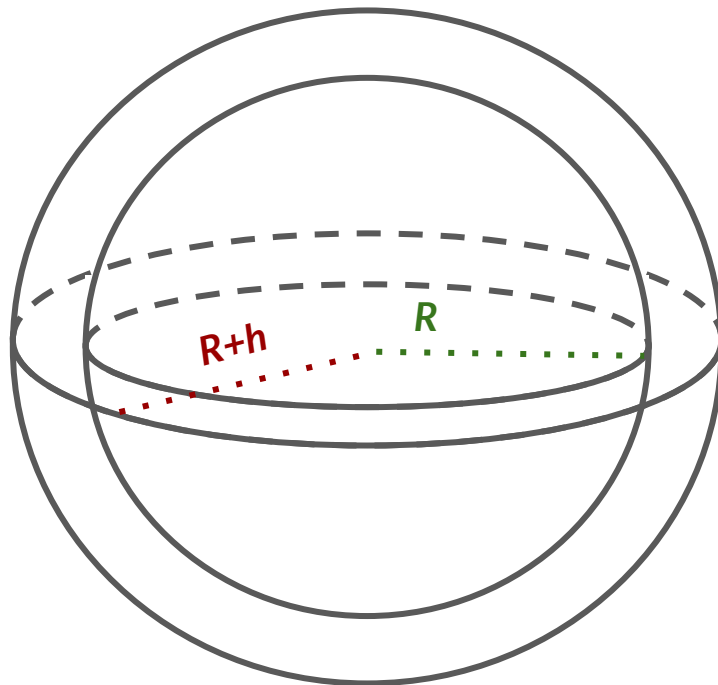


Key point:
In the lab, limited
sensitivity to DM
with mass $\gtrsim 10^{-13}$ eV

Which cavity should we use? The Earth-ionosphere/IPM!

Well below 10 Hz, the Earth's core and the ionosphere/interplanetary medium act as good concentric spherical conducting boundaries [Fedderke et al., PRD 2021; Arza et al., PRD 2022]

$$h \sim \mathcal{O}(100 \text{ km})$$
$$R_{\oplus} \approx 6 \times 10^3 \text{ km}$$



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Skin depths (frequency-dependent)

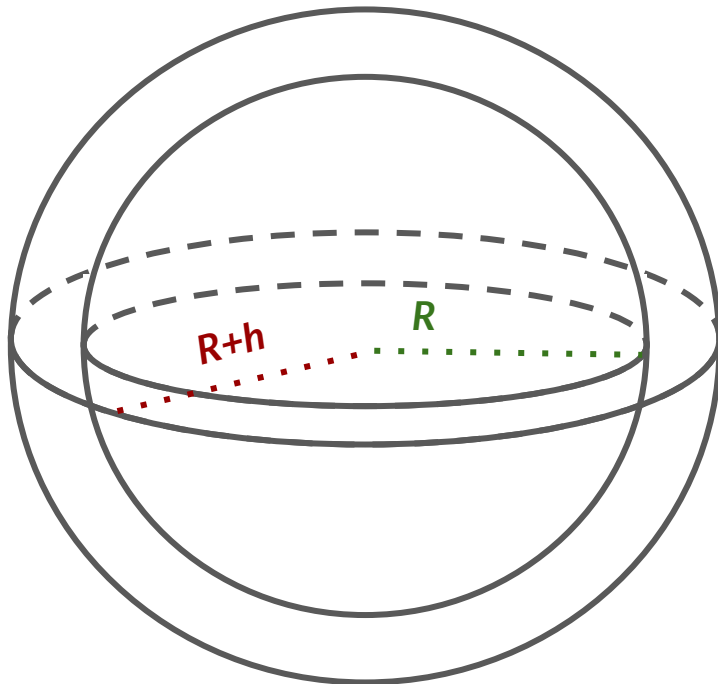
Inner boundary

$$\delta|_{\text{core}} \ll h \text{ for } m_{\text{DM}} \gtrsim 10^{-18} \text{ eV}$$

Outer boundary

$$\delta|_{\text{ionosphere}} \ll h \text{ for } 10^{-13} \text{ eV} \lesssim m_{\text{DM}} \lesssim 10^{-8} \text{ eV}$$

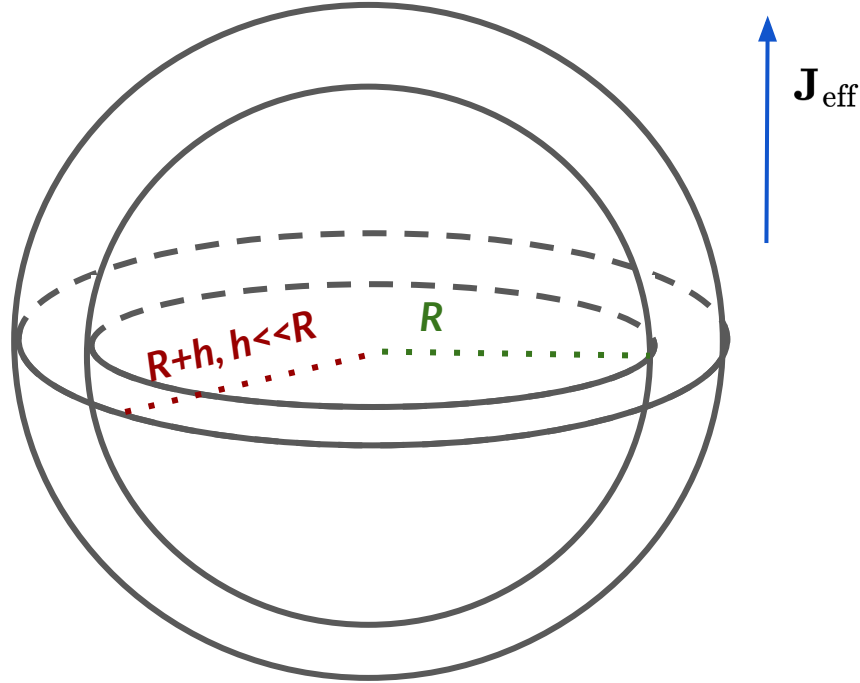
$$\delta|_{\text{IPM}} \ll h \text{ for } 10^{-22} \text{ eV} \lesssim m_{\text{DM}} \lesssim 10^{-13} \text{ eV}$$



Signal in a cavity with concentric spherical boundaries

Boundary conditions

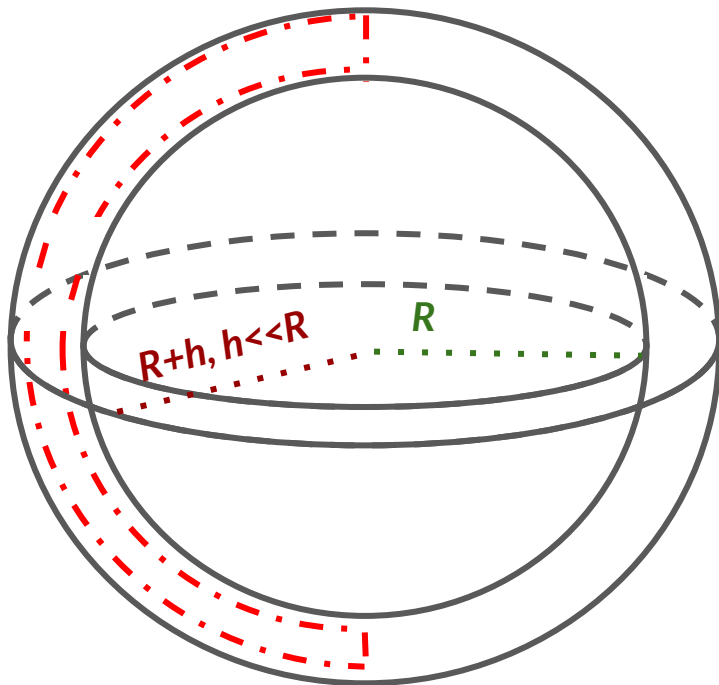
$$\hat{\mathbf{n}} \cdot \mathbf{B} = 0 \quad \hat{\mathbf{n}} \times \mathbf{E} = 0$$



Signal in a cavity with concentric spherical boundaries

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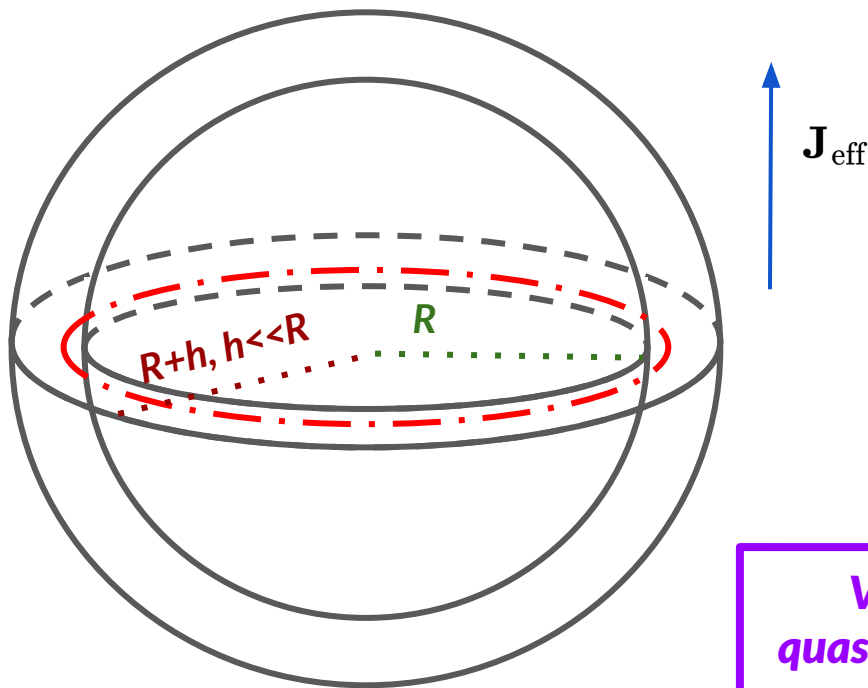
*E field is
parametrically
suppressed in the
quasistatic regime*

$$\oint \mathbf{E} \cdot d\mathbf{l} = \int (\nabla \times \mathbf{E}) \cdot d\mathbf{S} = \int \partial_t \mathbf{B} \cdot d\mathbf{S} \implies E \sim (m_{\text{DM}} R) B$$

Signal in a cavity with concentric spherical boundaries

Boundary conditions

$$\hat{\mathbf{n}} \cdot \mathbf{B} = 0 \quad \hat{\mathbf{n}} \times \mathbf{E} = 0$$



*Valid in the
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$$\oint \mathbf{B} \cdot d\mathbf{l} = \int (\nabla \times \mathbf{B}) \cdot d\mathbf{S} = \int \mathbf{J}_{\text{eff}} \cdot d\mathbf{S} \implies B \sim (m_{\text{DM}} R) J_{\text{eff}}$$

Signal in a cavity with concentric spherical boundaries

Boundary conditions

$$\hat{\mathbf{n}} \cdot \mathbf{B} = 0 \quad \hat{\mathbf{n}} \times \mathbf{E} = 0$$

Key take-home message:

$$|\mathbf{B}| \sim \epsilon m_{A'}^2 R_{\oplus} |\mathbf{A}'|$$

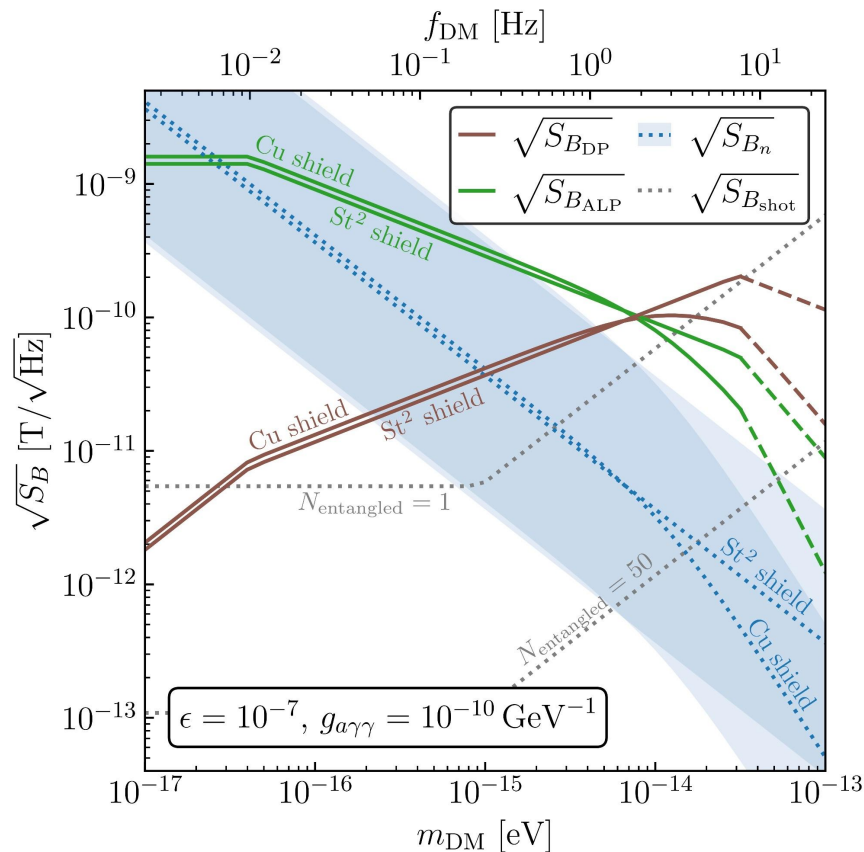
$$|\mathbf{B}| \sim g_{a\gamma\gamma} m_a R_{\oplus} |\mathbf{B}_{\oplus}| a$$

$$m_{\text{DM}} \ll 1/R_{\oplus}$$

**Valid in the
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$$\oint \mathbf{B} \cdot d\mathbf{l} = \int (\nabla \times \mathbf{B}) \cdot d\mathbf{S} = \int \mathbf{J}_{\text{eff}} \cdot d\mathbf{S} \implies B \sim (m_{\text{DM}} R) J_{\text{eff}}$$

Noise projections



[Campbell, Hamilton, JPB 2017]

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$$N = 100$$

$$\Delta t = 1 \text{ s}$$

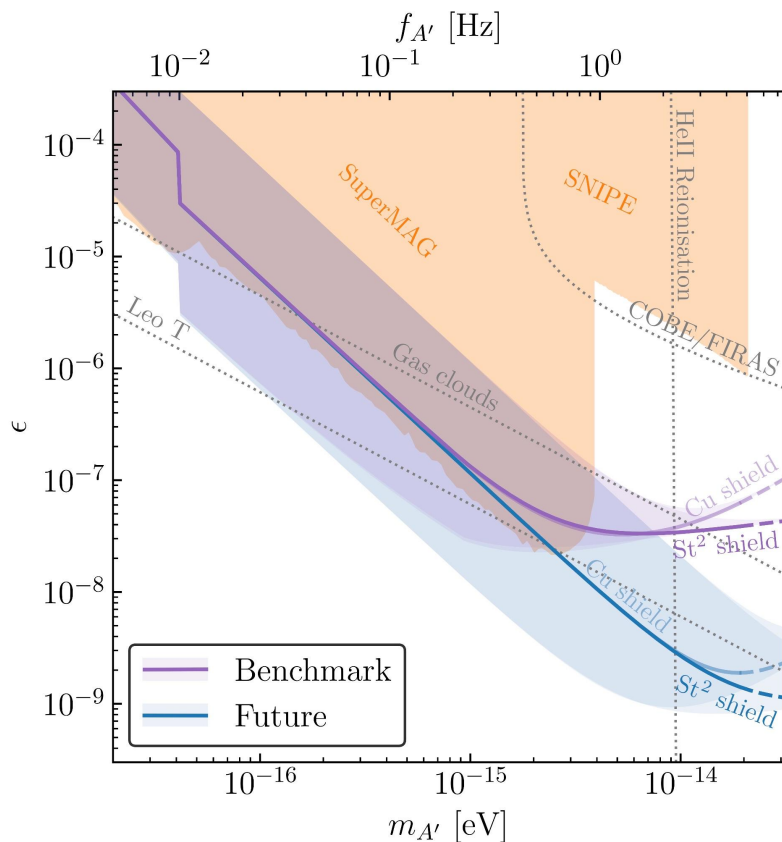
$$y_d = 100 \text{ } \mu\text{m}$$

$$\delta\phi = 1 \text{ rad}/\sqrt{\text{Hz}}$$

**Dominated by ambient
magnetic noise**

Fullerkrug and Fraser-Smith [2011],
Constable and Constable [2023]

Projected sensitivity: DPs



*Signal is insensitive to
latitude + longitude + trap
orientation tangent to the
Earth's surface*

$$\sqrt{\left\langle \left| \tilde{\mathbf{B}}_{A'}(\omega) \cdot \hat{\mathbf{\Sigma}} \right|^2 \right\rangle} = \epsilon m_{A'} R_{\oplus} \sqrt{\frac{\rho_{\text{DM}}}{6}},$$

*[Campbell, Hamilton, JPB
2017]*

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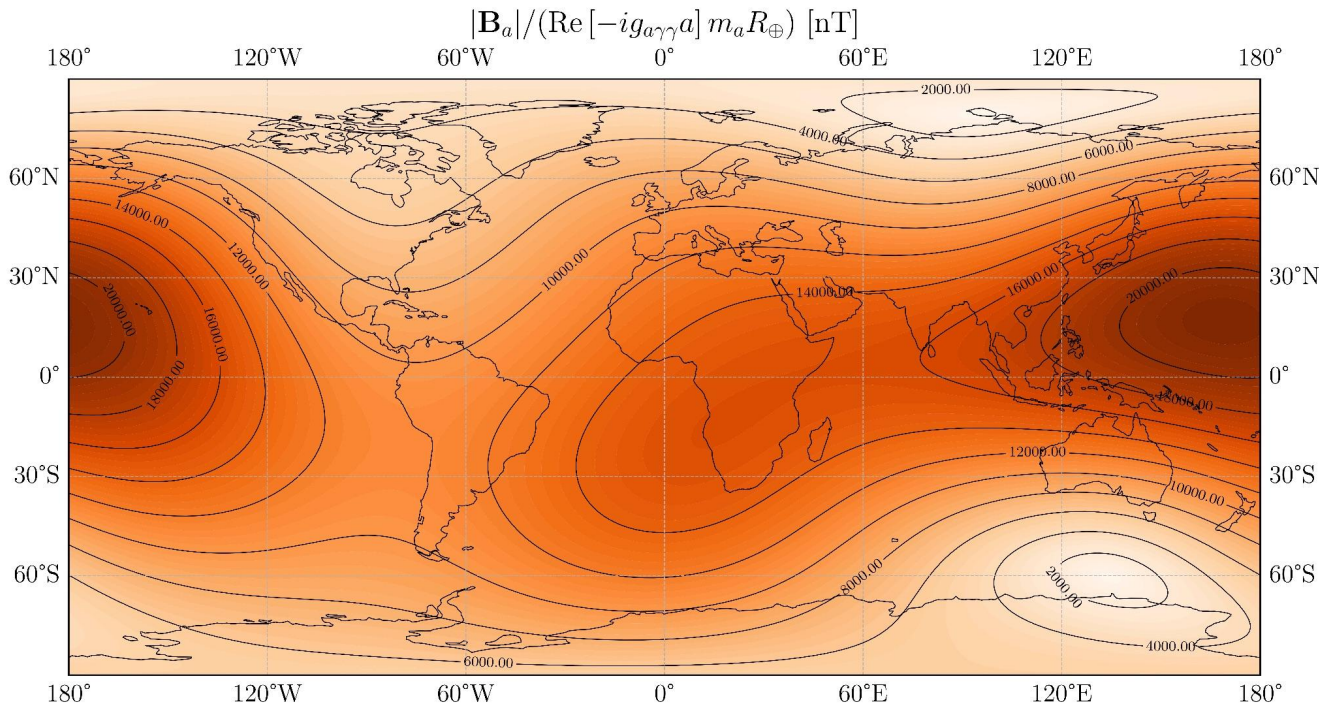
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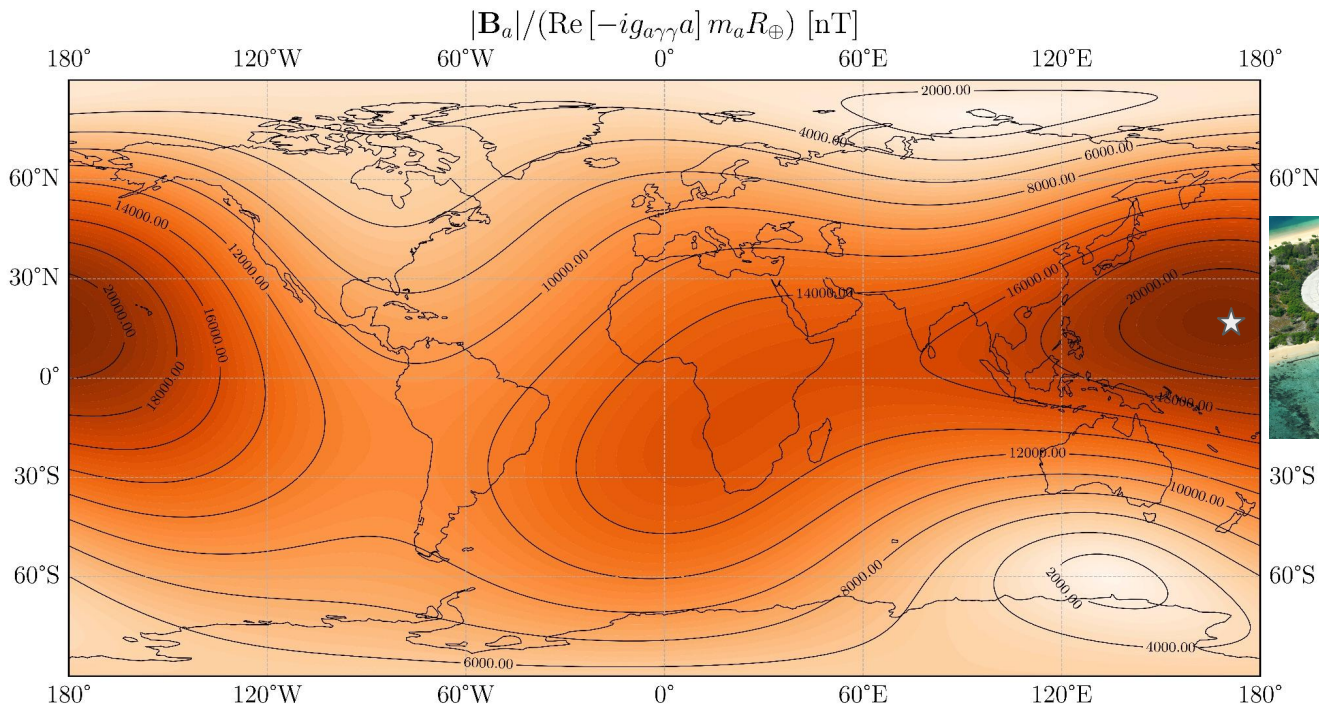
Projected sensitivity: ALPs

Signal is sensitive to latitude + longitude + directionality known a priori (set by the Earth's magnetic field) [IGRF 2021]



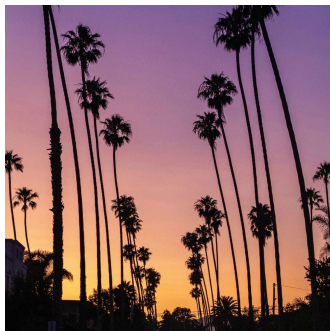
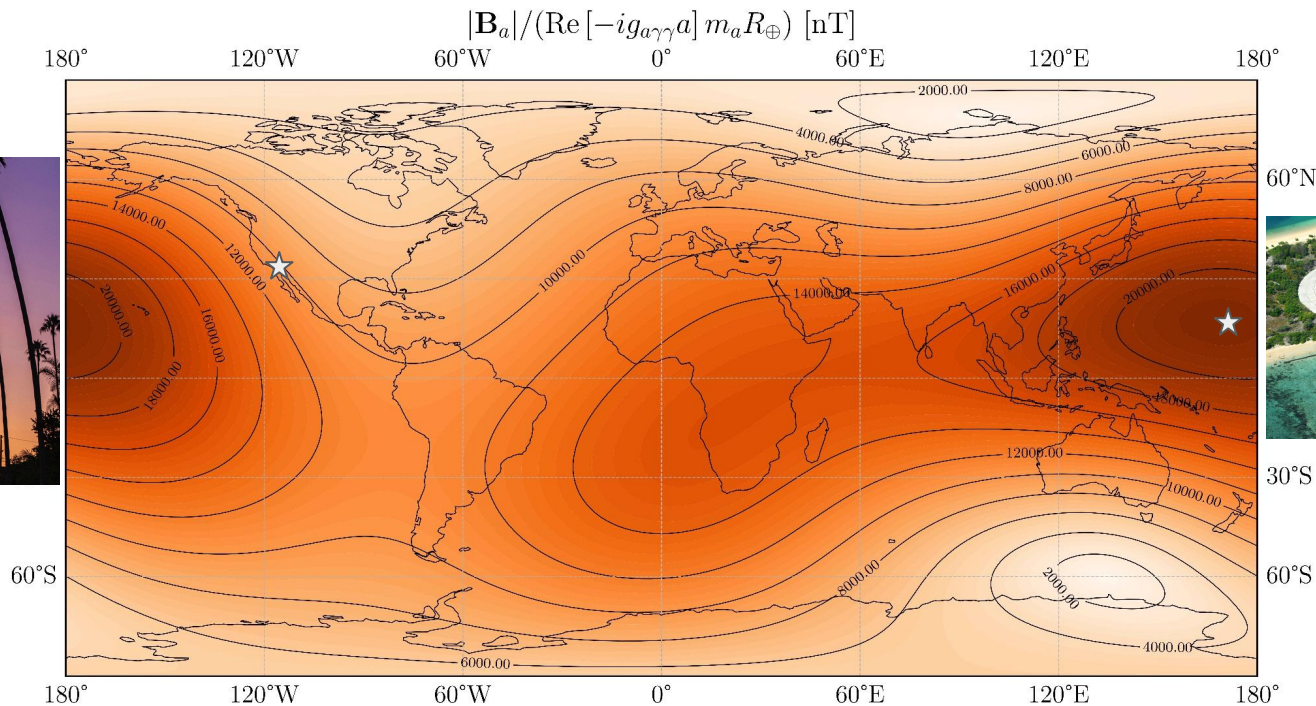
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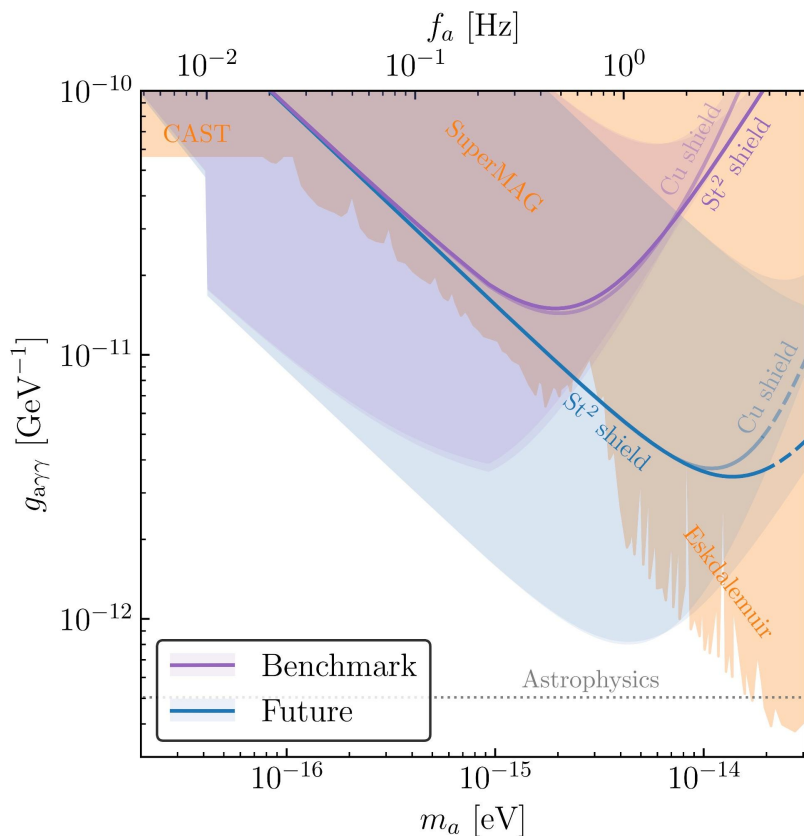


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[Campbell, Hamilton, JPB 2017]

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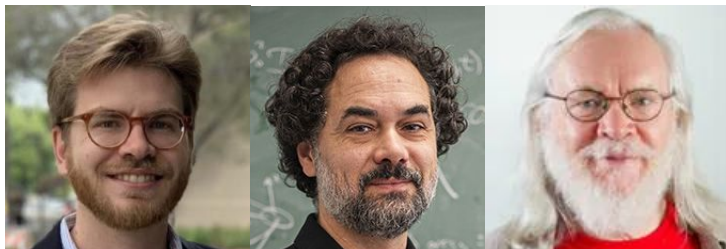
$\delta\phi = 1 \text{ rad}/\sqrt{\text{Hz}}$

Summary

Trapped-ion interferometers are sensitive to small B -fields via the dynamical Zeeman effect

In light of their promising projected reach, trapped-ion interferometers are poised to probe unexplored regions of ULDM parameter space!

*Thank you for your attention.
Stay tuned!*



Caltech