
Target Shock Wave Study



Stefan Hesselbach
IPPP, University of Durham



6th ILC Positron Source Collaboration Meeting, IPPP, Durham

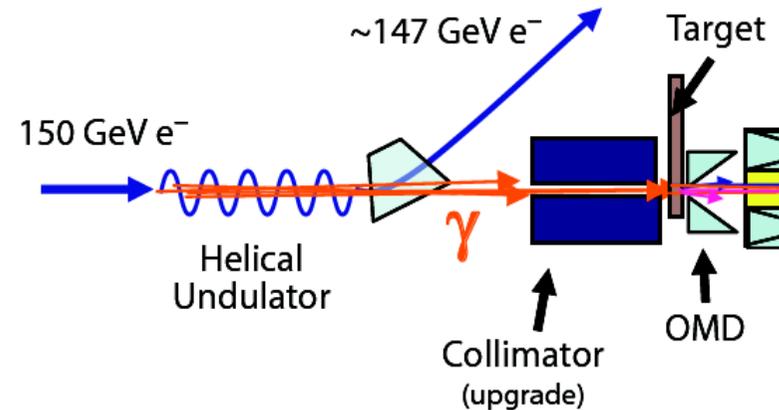
30 October 2009

Outline

- Introduction
- Thermal shocks in target
- Energy deposition in target
- Simulations with FlexPDE
- Hydrodynamical model for temperature and pressure
- Summary

Introduction

- Positron source, e.g. ILC RDR:



- Polarized γ on target \Rightarrow polarized e^+
- Leading production process: e^+e^- pair creation
 - Quasi-classical approximations
 - Simulation with e.g. GEANT, FLUKA \rightarrow tested against data
- Possible problems: heat load, thermal shocks in target, ...
- Rotating wheel targets
- Prototype in Daresbury (Ti alloy) [Ian's talk]
- Alternatives: Liquid metals (Bi-Pb, Hg) [e.g. A.A. Mikhailichenko, CBN06-1, 2006]

Thermal shocks in target

- Rapid energy deposition of γ beam \Rightarrow pressure shock wave
- Hydrodynamical model [e.g. A.A. Mikhailichenko, CBN06-1, 2006]
 - \rightarrow Temperature $T = T(\vec{x}, t)$, pressure $P = P(\vec{x}, t)$
described by hydrodynamical equations
- Simulations at LLNL and Cornell
[talks at Argonne meeting, Sept. 2007, by T. Piggott and A.A. Mikhailichenko, respectively]
- Cornell simulations
 - FlexPDE
 - Large negative pressure at $\mathcal{O}(10^{-10} \text{ s})$ at target exit
 - Results: *“Ti target not surviving with present margins”*

Thermal shocks in target

Hydrodynamic model behind simulations

E.g. for Cornell simulations [A.A. Mikhailichenko, CBN06-1, 2006, talk at Argonne meeting]

- Temperature: $\nabla(k\nabla T) + \dot{Q} = \rho c_V \dot{T}$

$\dot{Q}(\vec{x}, t)$: density of energy deposition; c_V : heat capacity

- Pressure: $\ddot{P} - \nabla(c_0^2 \nabla P) = \Gamma / V_0 \dot{Q}$

c_0 : speed of sound; $\Gamma = \Gamma(V) = V / c_V (\partial P / \partial T)_V$

- Gaussian distribution of energy deposition:

$$\dot{Q} = \sum_j \frac{2cQ_{\text{bunch}}}{\pi\sqrt{\pi}\sigma_z\sigma_{\perp}^2 l_T} \frac{z}{l_T} \exp\left(-\frac{(z + z_0 - c(t - jt_0))^2}{\sigma_z^2}\right) \exp\left(-\frac{r^2}{\sigma_{\perp}^2}\right)$$

$\int \dot{Q}(\vec{x}, t) dV dt = Q_{\text{bunch}}$; σ_z, σ_{\perp} : bunch dimensions; l_T : target thickness

- Density of energy distribution: $Q(\vec{x}) = \int \dot{Q}(\vec{x}, t) dt$

Energy deposition in target

Comparison with FLUKA simulations

[Zeuthen group: S. Riemann, A. Schälicke, A. Ushakov]

Include higher harmonics of undulator radiation

[A. Ushakov, talk at Zeuthen meeting, April 2008]

- γ -beam intensity extends to larger r than for Gaussian distribution
- Energy is distributed in larger volume
- Gaussian approximation underestimates volume for $K \sim 1$
- Better for $K \lesssim 0.5$

Simulations with FlexPDE

- FlexPDE 6.07 available in Zeuthen [S. Riemann, A. Schälicke, A. Ushakov]
- Solves Partial Differential Equations (PDEs)
- 2-dim description of target via cylinder coordinates

```
COORDINATES XCYLINDER
```

```
...
```

```
BOUNDARIES
```

```
REGION 1
```

```
START(0,0)
```

```
LINE TO (15,0)
```

```
LINE TO (15,15)
```

```
LINE TO (0,15)
```

```
LINE TO CLOSE
```

→ Natural boundary conditions

Simulations with FlexPDE

- For $P = 0$ on target surface ($z = 0$ and $z = 15$ mm)

```
BOUNDARIES
```

```
REGION 1
```

```
START(0,0)
```

```
LINE TO (15,0)
```

```
Value(p)=0
```

```
LINE TO (15,15)
```

```
Natural(p)=0
```

```
LINE TO (0,15)
```

```
Value(p)=0
```

```
LINE TO CLOSE
```

- Read in e.g. energy distribution from FLUKA simulation

```
Q0 = table('energy.tbl')
```

Hydrodynamical model

Heat Equation

$$\nabla(k\nabla T) + \dot{Q} = \rho c_V \dot{T}$$

$\dot{Q}(\vec{x}, t)$: density of energy deposition; c_V : heat capacity

- Heat flow in $O(1 \text{ s}) \rightarrow$ energy deposition \dot{Q} instantaneous
- FlexPDE:

INITIAL VALUES

temp=t0 + cfac*Q0/(C*rho)

EQUATIONS { PDE's, one for each variable }

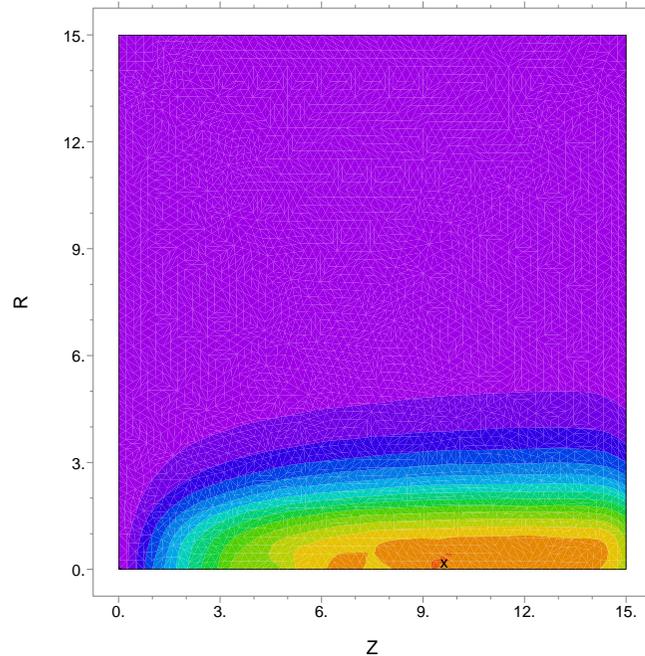
div(K*grad(temp)) = C*rho*dt(temp) { heat equation }

Hydrodynamical model

Heat Equation

$t = 0$

Temperature in target

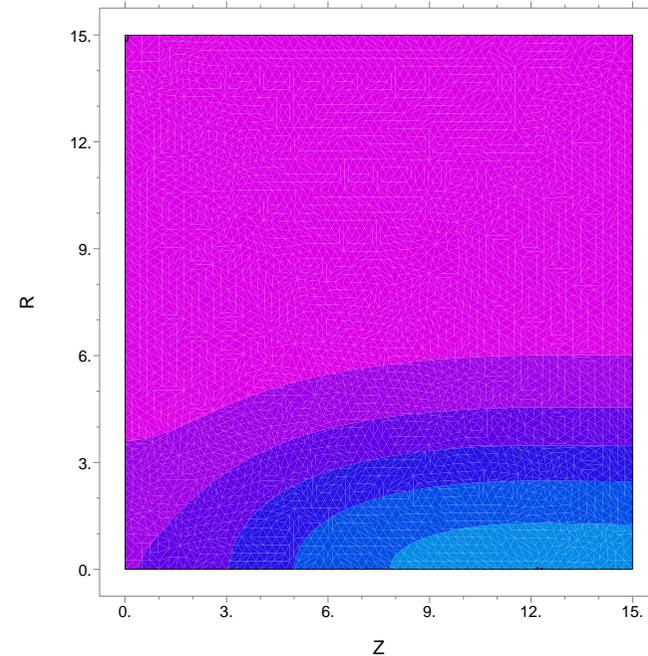


16:39:56 10/27/09
FlexPDE 6.07

temperature1: Cycle=0 Time= 0.0000 dt= 0.0100 P2 Nodes=1105 Cells=522 RMS Err= 1.
Vol_Integral= 3202838.

$t = 1 \text{ s}$

Temperature in target



16:39:56 10/27/09
FlexPDE 6.07

temperature1: Cycle=33 Time= 1.0000 dt= 0.0891 P2 Nodes=1184 Cells=561 RMS Err= 9.5e-5
Vol_Integral= 3202863.

for 100 bunches on 1 spot

Hydrodynamical model

PDE for pressure

$$\ddot{P} - \nabla(c_0^2 \nabla P) = \Gamma/V_0 \dot{Q}$$

c_0 : speed of sound; $\Gamma = \Gamma(V) = V/c_V (\partial P/\partial T)_V$

- 2nd time derivative \Rightarrow split in 2 PDE for FlexPDE:

EQUATIONS

$$p_t: \quad \text{dt}(p_t) - \text{div}(c_0 * \text{grad}(p)) = \text{Gamma} * \text{qdot}(t)$$

$$p: \quad p_t - \text{dt}(p) = 0$$

- Analyse pressure at time scale $\mathcal{O}(10^{-10} \text{ s})$

- Use Gaussian approximation for \dot{Q} :

$$\text{qdot}(t) = \text{const} / \text{sigr}^2 * z * \text{Exp}(-(z - c * t)^2 / \text{sigz}^2) * \text{Exp}(-r^2 / \text{sigr}^2)$$

- Time scale of bunch crossing target: $l_T/c \sim 5 \cdot 10^{-11} \text{ s}$

Hydrodynamical model

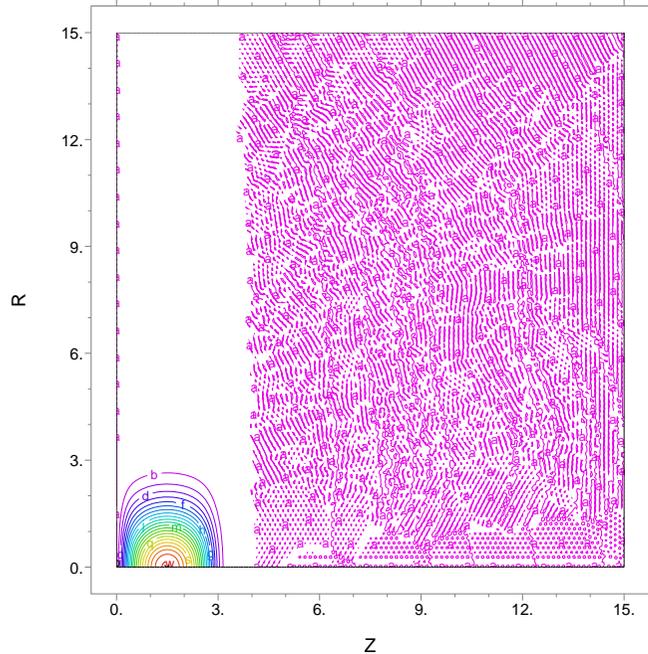
PDE for pressure

$$t = 10^{-11} \text{ s}$$

Contours of P in a.u.

Heatflow and pressure in target with qdot

19:13:23 10/19/09
FlexPDE 6.07

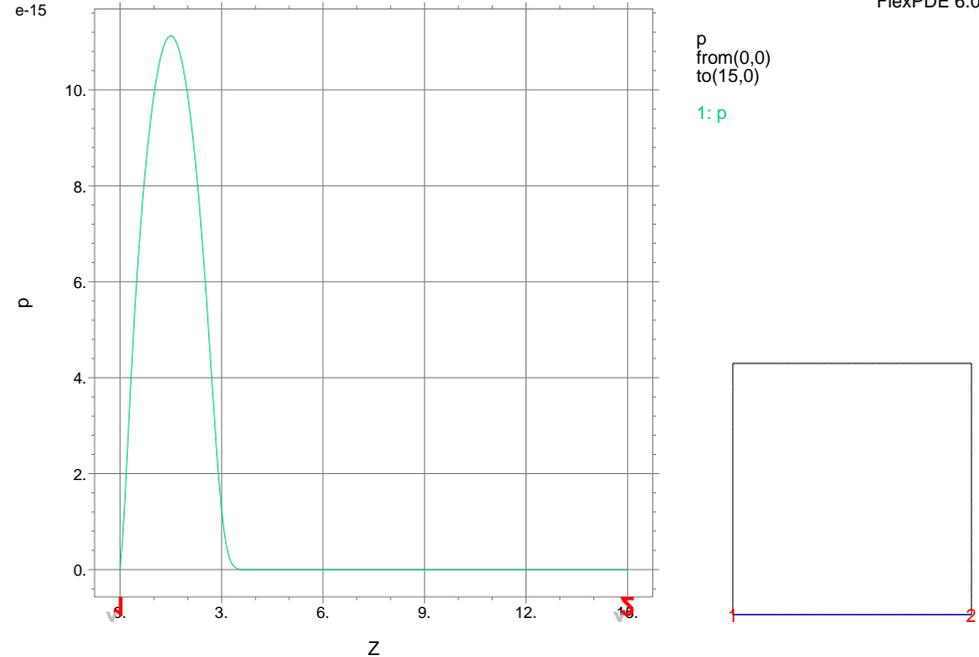


pressure_qdot3: Cycle=106 Time= 1.0000e-11 dt= 8.8914e-14 P2 Nodes=44405 Cells=22002 RMS Err= 2.8e-6
Vol_Integral= 1.584657e-13

P on beam axis

Heatflow and pressure in target with qdot

19:13:23 10/19/09
FlexPDE 6.07



pressure_qdot3: Cycle=106 Time= 1.0000e-11 dt= 8.8914e-14 P2 Nodes=44405 Cells=22002 RMS Err= 2.8e-6
Surf_Integral= 1.408875e-18

Hydrodynamical model

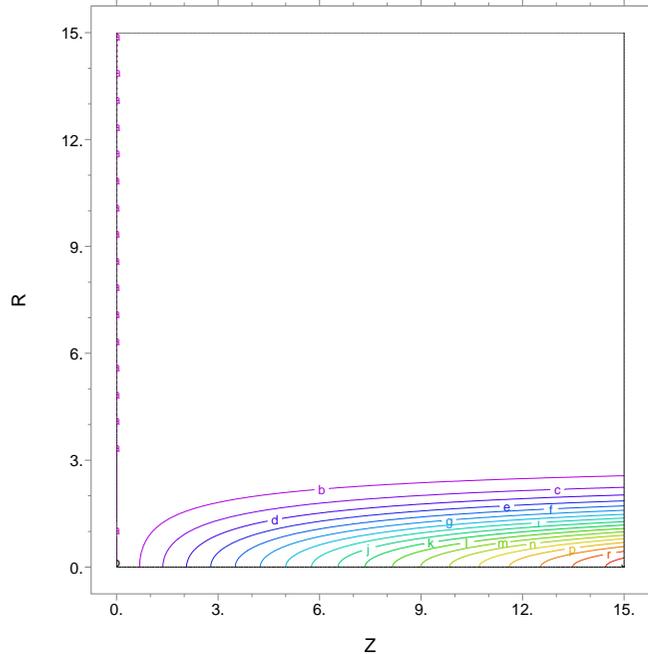
PDE for pressure

$t = 3 \cdot 10^{-10}$ s, natural boundary conditions

Contours of P in a.u.

Heatflow and pressure in target with qdot

19:13:23 10/19/09
FlexPDE 6.07



p	
max	5.56
s:	5.40
r:	5.10
q:	4.80
p:	4.50
o:	4.20
n:	3.90
m:	3.60
l:	3.30
k:	3.00
j:	2.70
i:	2.40
h:	2.10
g:	1.80
f:	1.50
e:	1.20
d:	0.90
c:	0.60
b:	0.30
a:	0.00
min	-9e-4

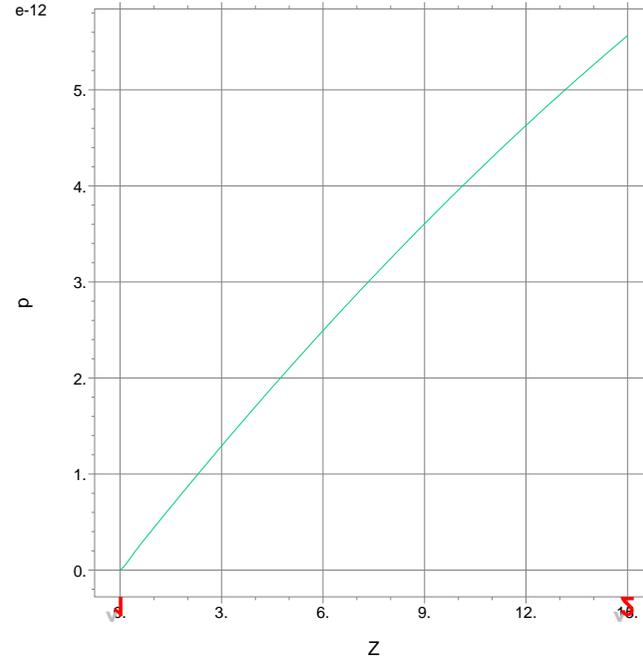
Scale = E-12

pressure_qdot3: Cycle=3006 Time= 3.0000e-10 dt= 8.8914e-14 P2 Nodes=44405 Cells=22002 RMS Err= 3.e-14
Vol_Integral= 3.145502e-10

P on beam axis

Heatflow and pressure in target with qdot

19:13:23 10/19/09
FlexPDE 6.07



p
from(0,0)
to(15,0)
1: p

pressure_qdot3: Cycle=3006 Time= 3.0000e-10 dt= 8.8914e-14 P2 Nodes=44405 Cells=22002 RMS Err= 3.e-14
Surf_Integral= 2.796767e-15

Hydrodynamical model

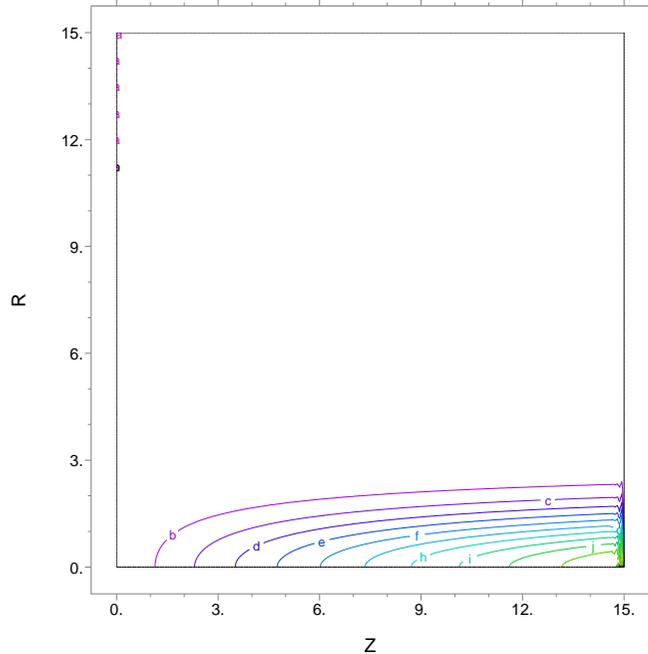
PDE for pressure

$$t = 3 \cdot 10^{-10} \text{ s}, P = 0 \text{ for } z = 0, 15 \text{ mm}$$

Contours of P in a.u.

Heatflow and pressure in target with qdot

15:18:00 10/20/09
FlexPDE 6.07



p	
max	8.12
q:	8.00
p:	7.50
o:	7.00
n:	6.50
m:	6.00
l:	5.50
k:	5.00
j:	4.50
i:	4.00
h:	3.50
g:	3.00
f:	2.50
e:	2.00
d:	1.50
c:	1.00
b:	0.50
a:	0.00
min	0.00

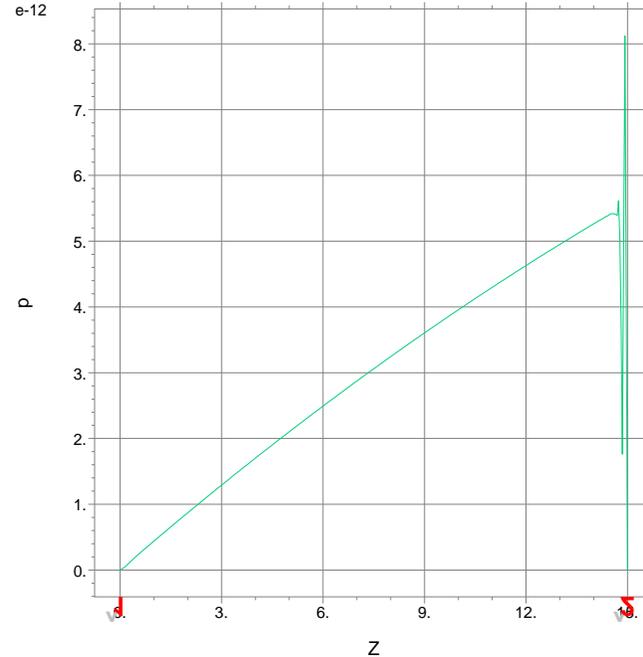
Scale = E-12

pressure_qdot3: Cycle=3006 Time= 3.0000e-10 dt= 8.8914e-14 P2 Nodes=44405 Cells=22002 RMS Err= 3.e-14
Vol_Integral= 3.130920e-10

P on beam axis

Heatflow and pressure in target with qdot

15:18:00 10/20/09
FlexPDE 6.07



p
from(0,0)
to(15,0)
1: p

pressure_qdot3: Cycle=3006 Time= 3.0000e-10 dt= 8.8914e-14 P2 Nodes=44405 Cells=22002 RMS Err= 3.e-14
Surf_Integral= 2.777251e-15

Hydrodynamical model

Work in progress

- Improvement of simulation
 - Boundary conditions
 - Moving mesh
- Timescales: $\mathcal{O}(10^{-10} \text{ s}) \leftrightarrow \mathcal{O}(10^{-7} \text{ s})$ for pressure waves
(speed of sound in $\ddot{P} - \nabla(c_0^2 \nabla P) = \Gamma/V_0 \dot{Q}$)
- Improve description of \dot{Q}
- Improvement of hydrodynamical model

Summary

- Goal: Check possible pressure shock waves at target exit at $\mathcal{O}(10^{-10} \text{ s})$
- Simulations with FlexPDE
- Hydrodynamical model
 - Heat equation: $\nabla(k\nabla T) + \dot{Q} = \rho c_V \dot{T} \rightarrow$ time scale $\mathcal{O}(1 \text{ s})$
 - Pressure: $\ddot{P} - \nabla(c_0^2 \nabla P) = \Gamma/V_0 \dot{Q}$
 - \rightarrow time scale $\mathcal{O}(10^{-10} \text{ s})$ for \dot{Q}
 - and $\mathcal{O}(10^{-7} \text{ s})$ for pressure wave (c_0)
- \rightarrow Work in progress