

# Testing dynamic stabilization in complex Langevin simulations

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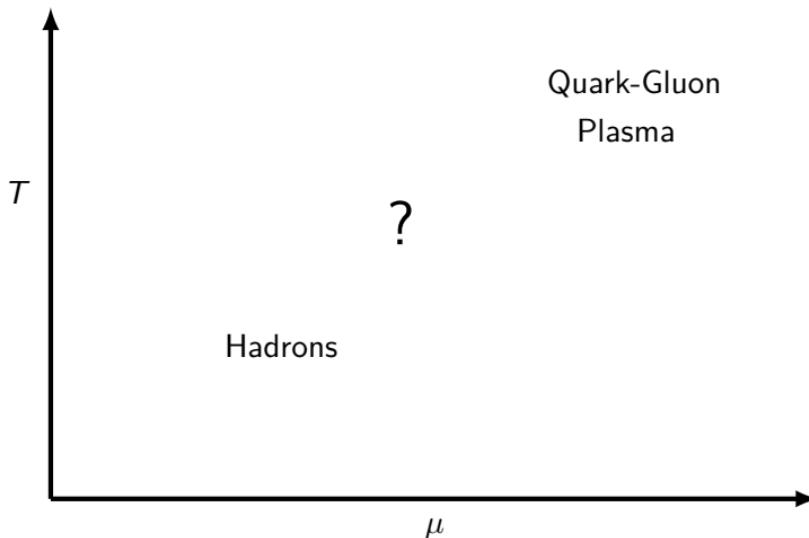


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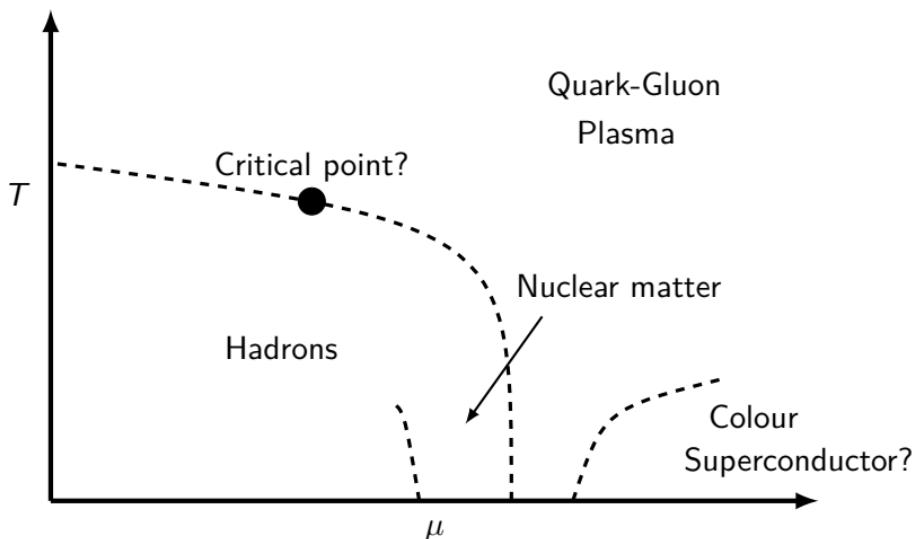
In collaboration with G. Aarts, F. Attanasio, D. Sexty



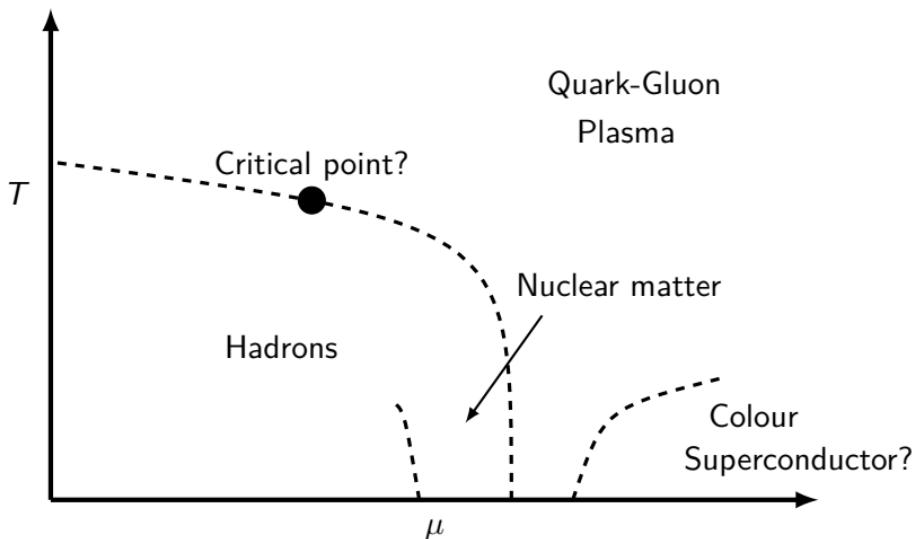
# Phase diagram for QCD



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# Phase diagram for QCD



- Sign problem  $\leftrightarrow \det D(\mu \neq 0) \in \mathbb{C}$

# Complex Langevin simulations

- Complexify degrees of freedom  $SU(3) \rightarrow SL(3, \mathbb{C})$

$$U_{x,\nu} = \exp \left[ i a \lambda^c (A_{x,\nu}^c + i B_{x,\nu}^c) \right]$$

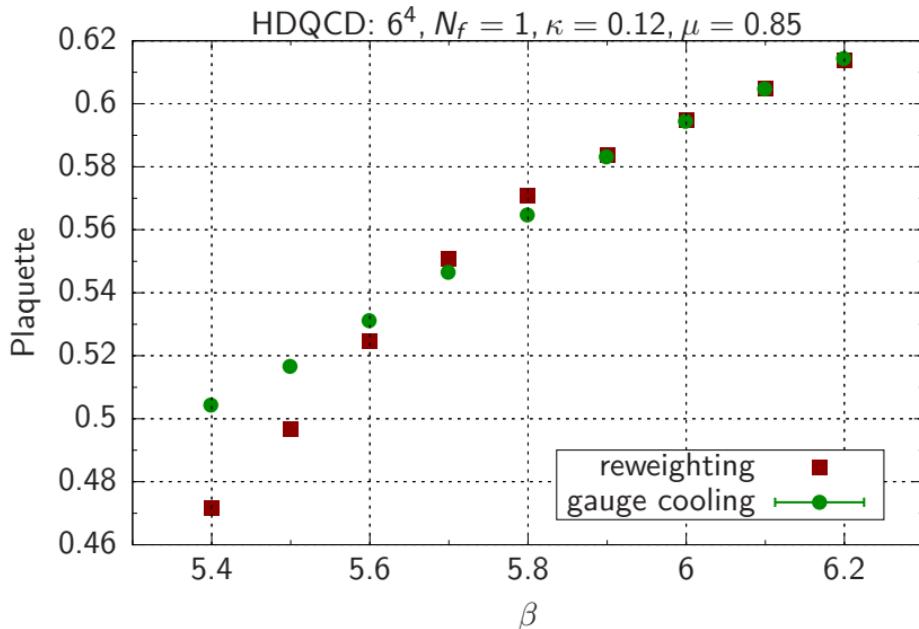
- Evolve links according (1st order) Langevin equation

$$U_{x,\nu}(\theta + \varepsilon) = \exp \left[ i \lambda^a (\varepsilon D_{x,\nu}^a S + \sqrt{\varepsilon} \eta_{x,\nu}^a) \right] U_{x,\nu}(\theta)$$

- Gauge cooling is essential, but sometimes not sufficient..

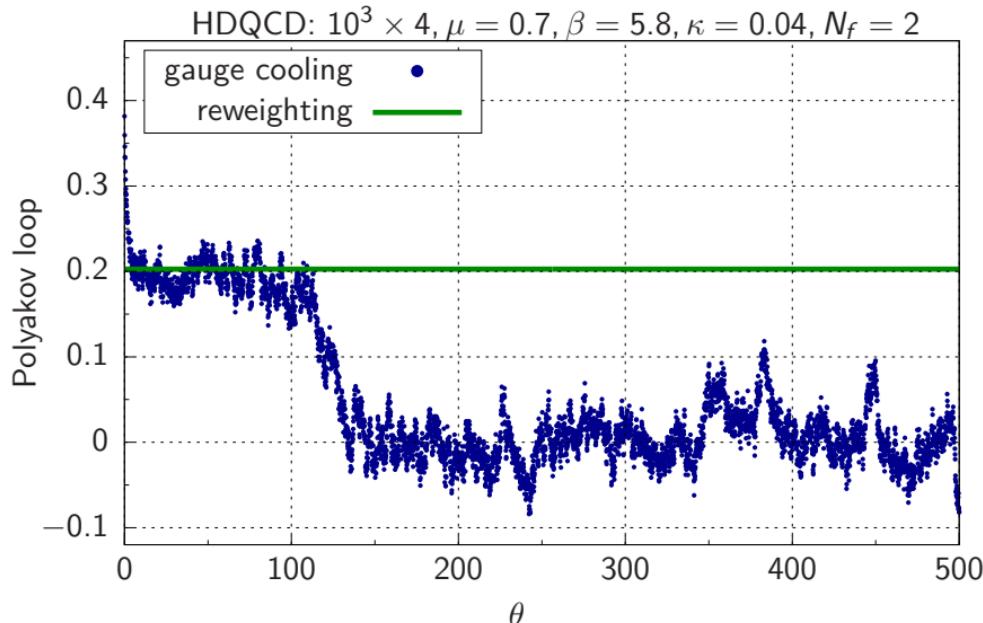
$$U_{x,\nu} = \Omega_x U_{x,\nu} \Omega_{x+\nu}^{-1}$$

## Gauge cooling



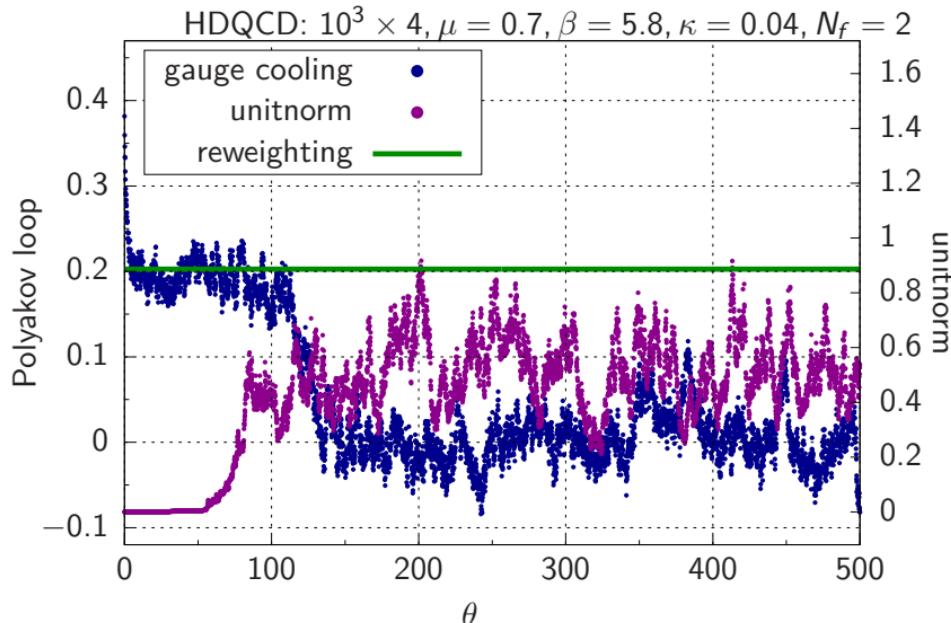
- For small  $\beta$  Complex Langevin results differ from reweighting.

## Gauge cooling



- Tunneling to wrong results.

## Gauge cooling



- Tunneling to wrong results, when unitnorm grows too large.

# Dynamic stabilization

- Adding a trivial force to the Langevin dynamics

$$U_{x,\nu}(\theta + \varepsilon) = \exp \left[ i\lambda^a (\varepsilon K_{x,\nu}^a - \varepsilon \alpha_{DS} M_x^a + \sqrt{\varepsilon} \eta_{x,\nu}^a) \right] U_{x,\nu}(\theta)$$

where

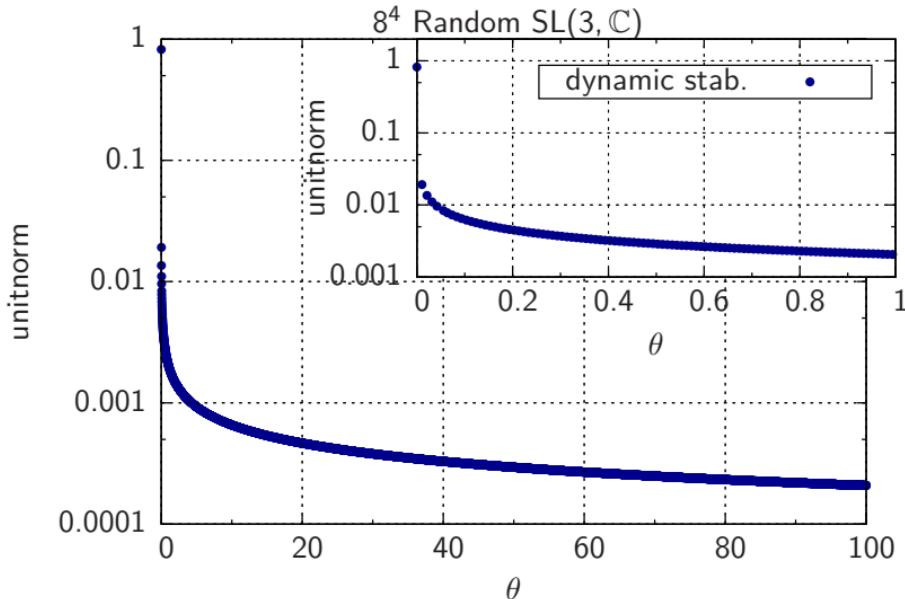
$$M_x^a = b_x^a \left( \sum_c b_x^c b_x^c \right)^3 \text{ and } b_x^a = \text{Tr} \left[ \lambda^a \sum_\nu U_{x,\nu} U_{x,\nu}^\dagger \right].$$

- Expanding the force in terms of gauge fields  $A$  and  $B$

$$M_x^a \sim a^7 \left( \overline{B}_y^c \overline{B}_y^c \right)^3 \overline{B}_x^a + \mathcal{O}(a^8).$$

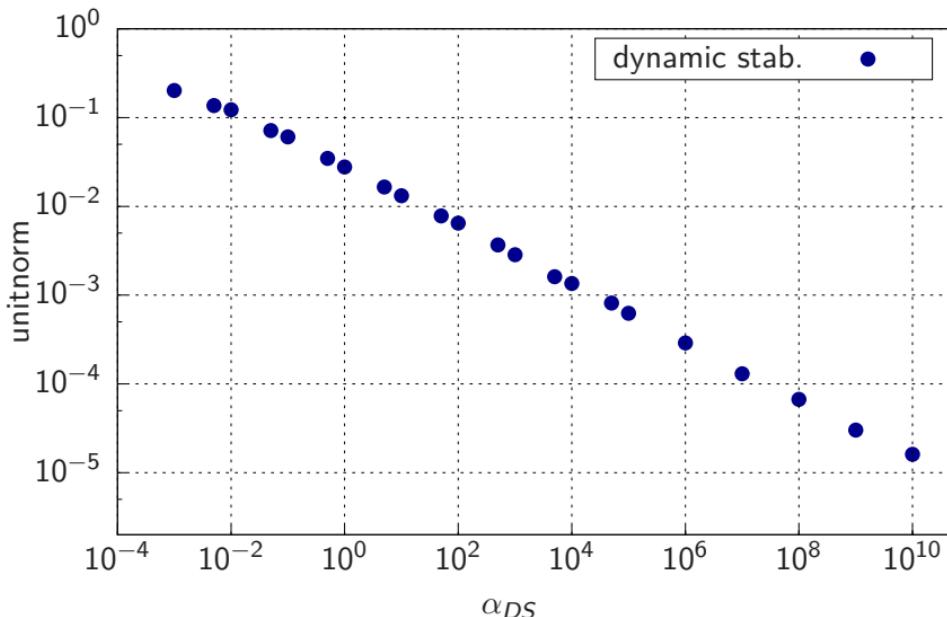
- Dynamic stabilization is numerically cheap and can be combined with gauge cooling (Here: 1 step)

## Dynamic stabilization



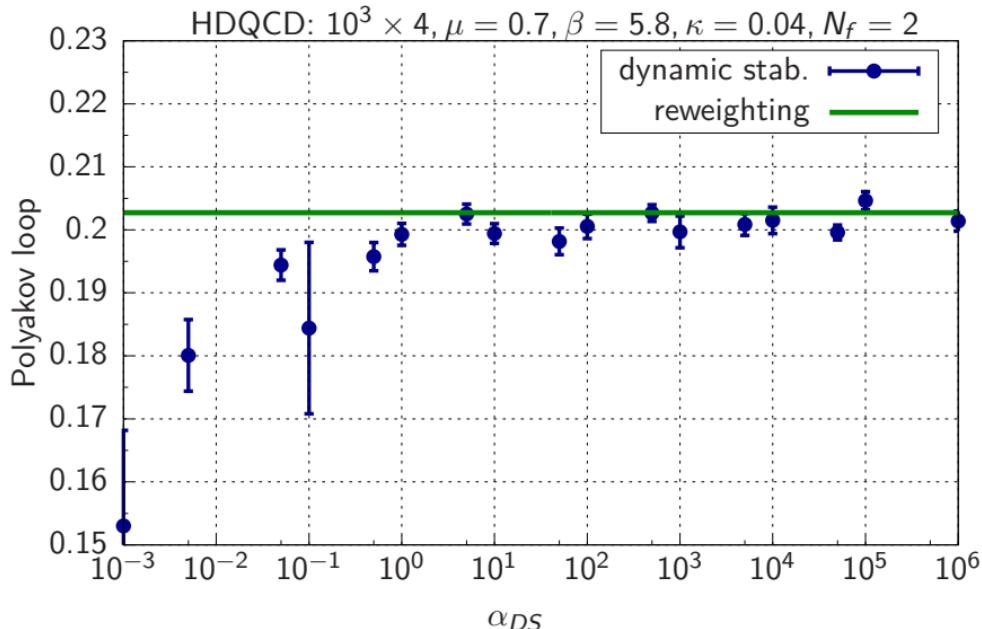
- Start with random  $SL(3, \mathbb{C})$  configuration.
- Only Dynamic stabilization, no action and noise

## Dynamic stabilization



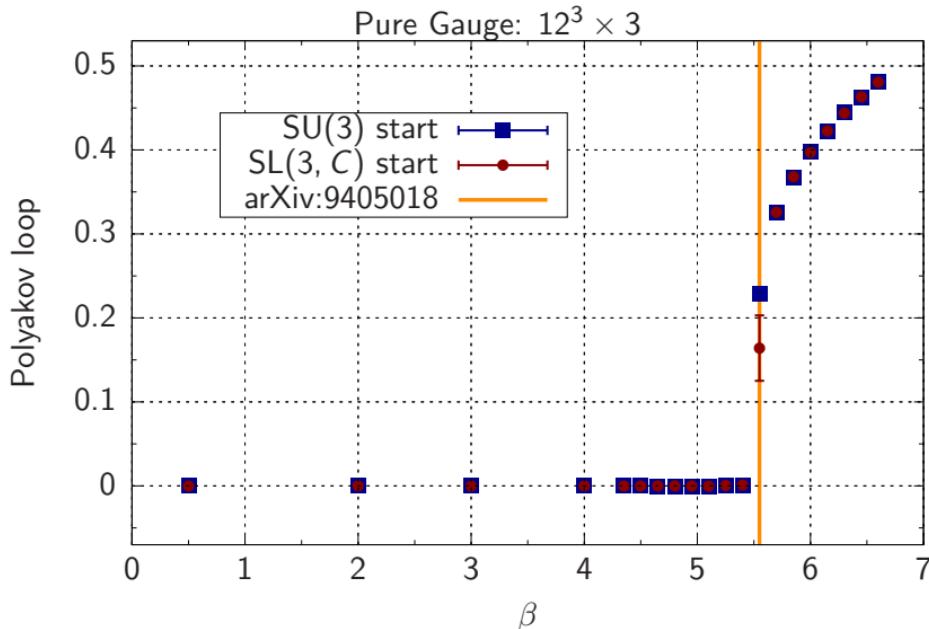
- Strength of dynamic stabilization → Control of unitnorm

## Dynamic stabilization



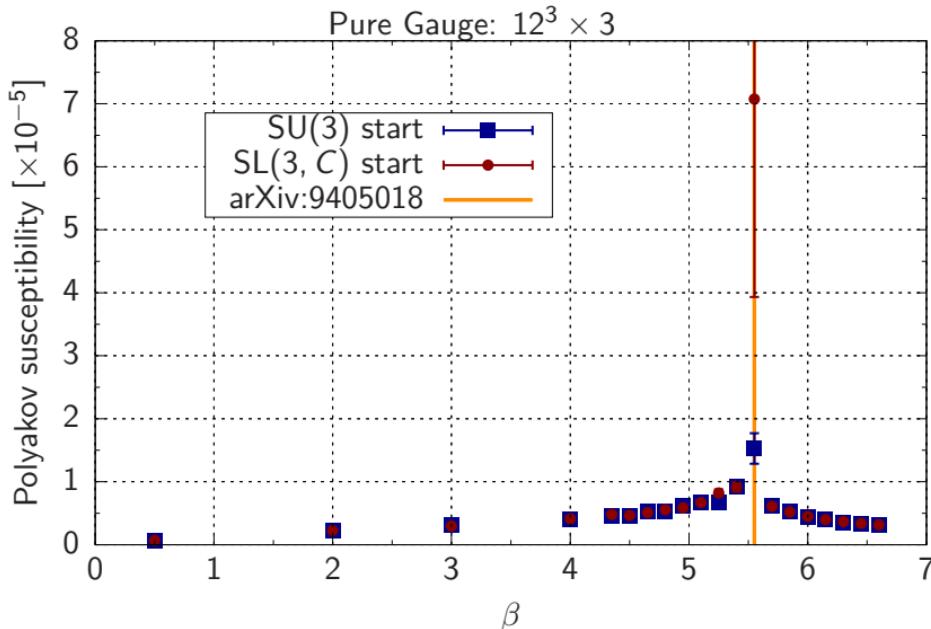
- For sufficient large  $\alpha_{DS}$  we obtain the correct result.

# Pure Gauge



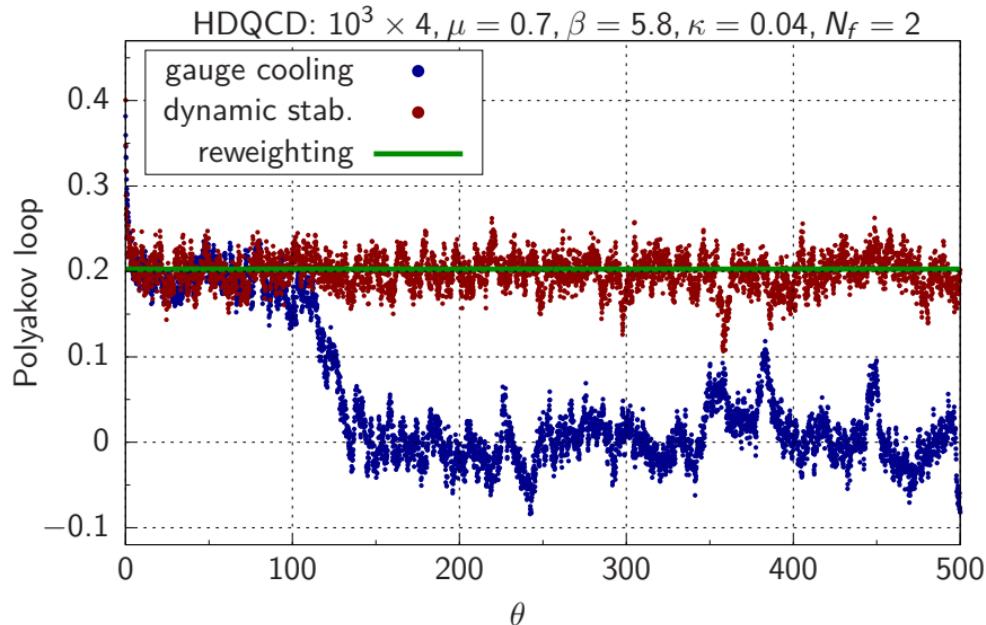
- The correct transition is obtained, even for  $SL(3, \mathbb{C})$  start.

# Pure Gauge



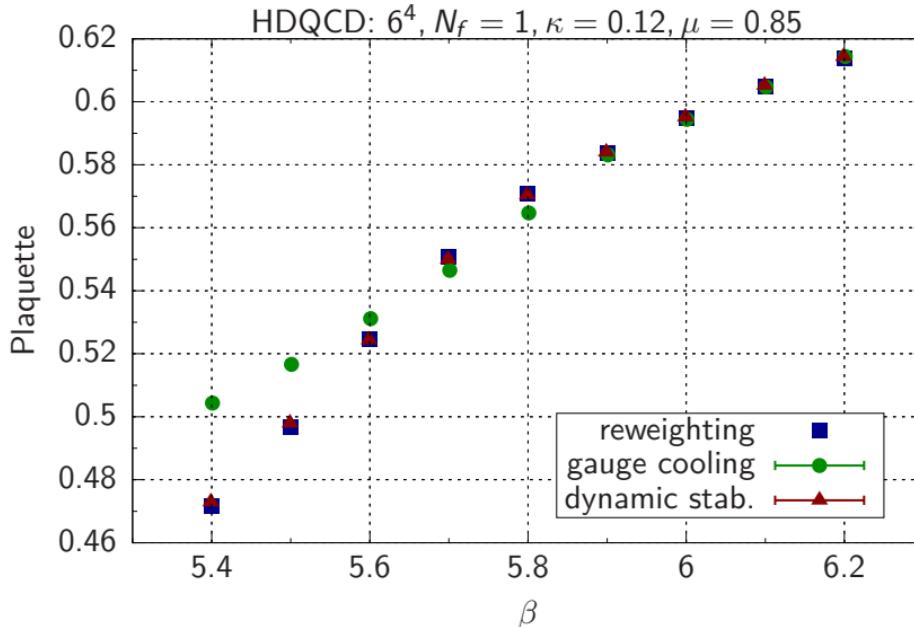
- The correct transition is obtained, even for  $SL(3, \mathbb{C})$  start.

# Heavy Dense QCD



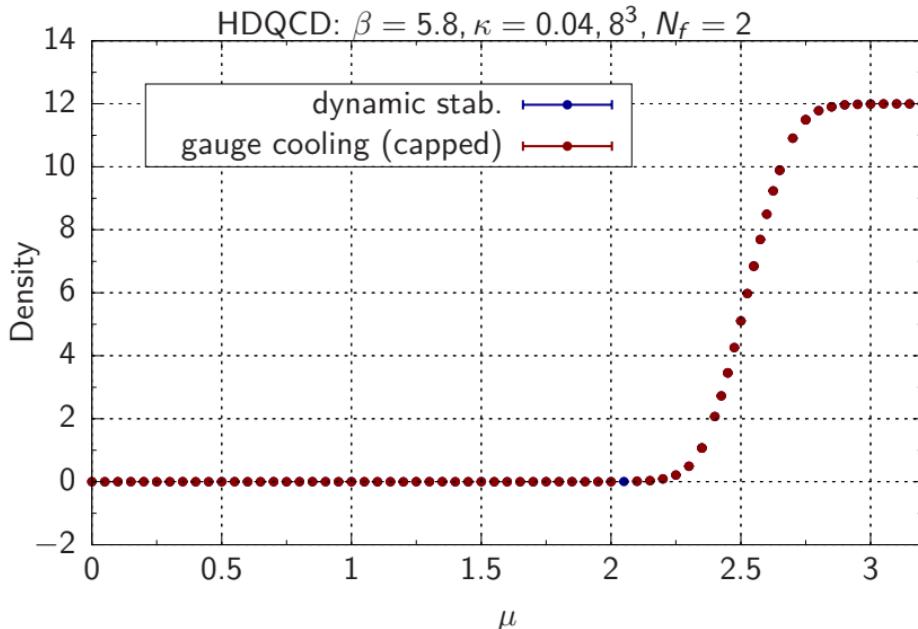
- Improved stability using dynamic stabilization

# Heavy Dense QCD



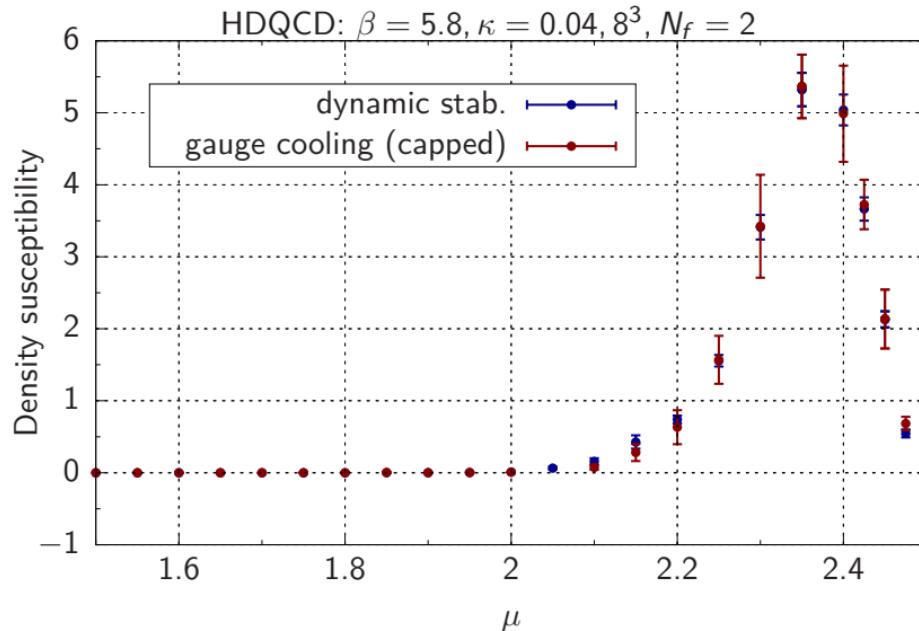
- Correct values recovered for all gauge couplings.

## Heavy Dense QCD



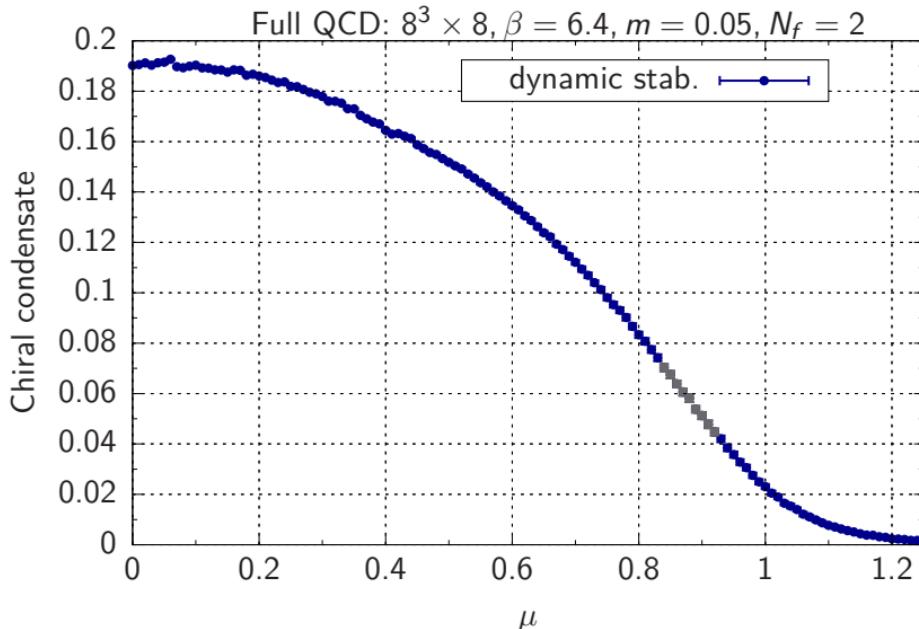
- Comparison of with capped ( $\text{unitnorm} < 0.03$ ) gauge cooling

# Heavy Dense QCD



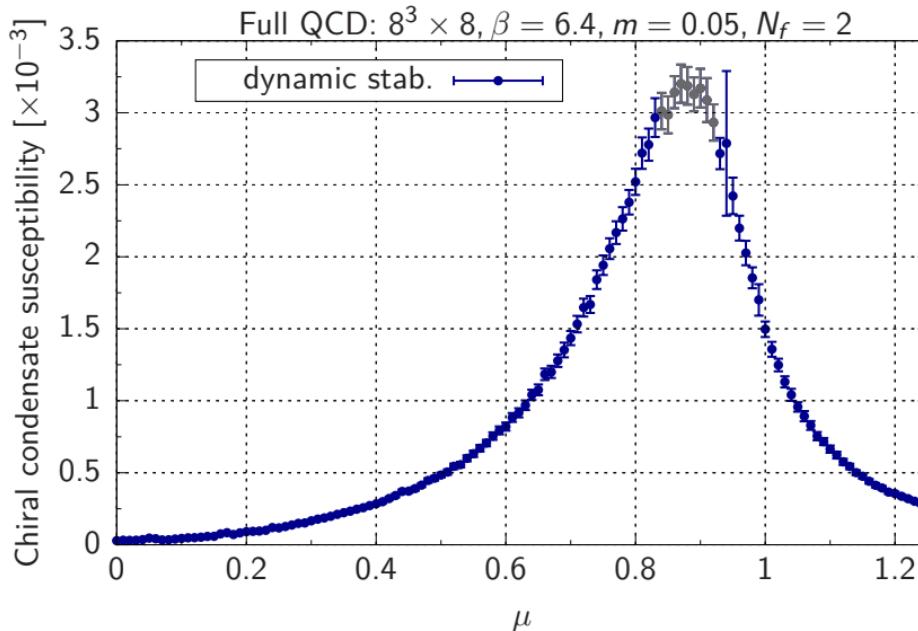
- Comparison of with capped ( $\text{unitnorm} < 0.03$ ) gauge cooling

## Last but not least - Full QCD



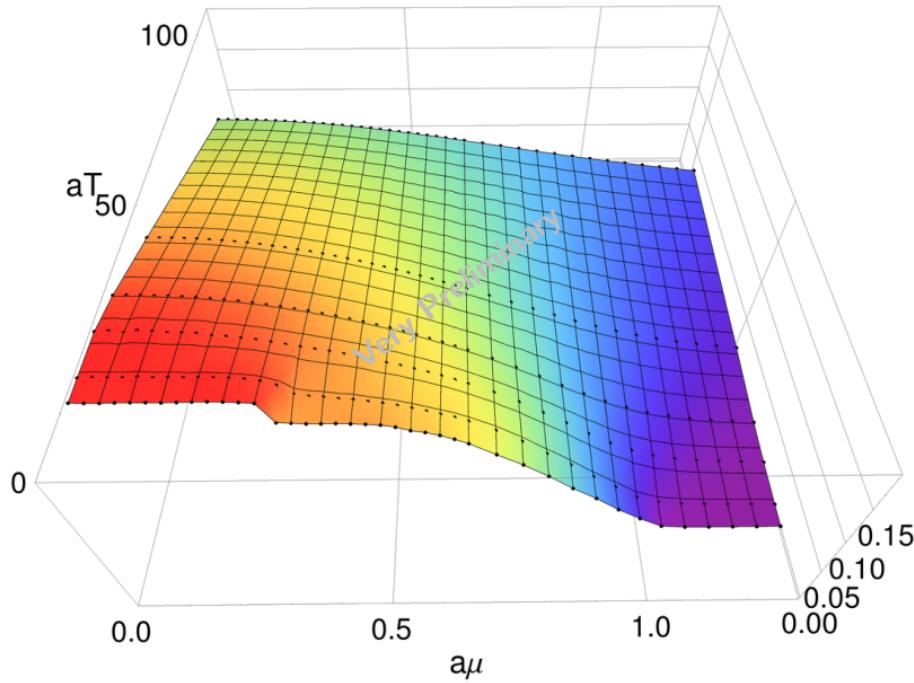
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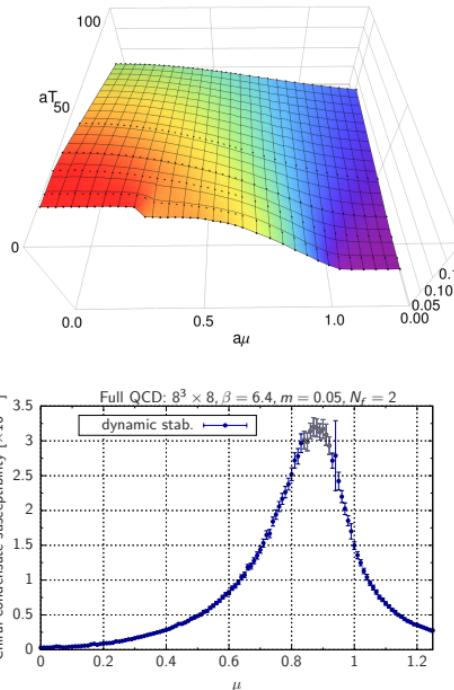
# Future work

## Conclusion

- Dynamical stabilisation allows to control the excursion into imaginary directions of  $SL(3, \mathbb{C})$
- Dynamical stabilisation improves convergence

## Future work

- More tests to check correct behaviour
- Start Full QCD simulations to identify phase structure of QCD.
- Extend simulations to real time QCD ( $e^{iS_{QCD}}$ ).



Thank you for your attention!