

# A first law for entanglement rates

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arXiv:1612.07769  
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# Entanglement entropy

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**Definition of entanglement entropy:**

Split the Hilbert space of a quantum system into subspace  $\mathcal{A}$  and its complement  $\mathcal{B}$ . Reduced density matrix:

$$\rho_{\mathcal{A}} = \sum_{|\psi\rangle \in \mathcal{B}} \langle \psi | \rho | \psi \rangle$$

EE = von Neumann entropy of reduced density matrix

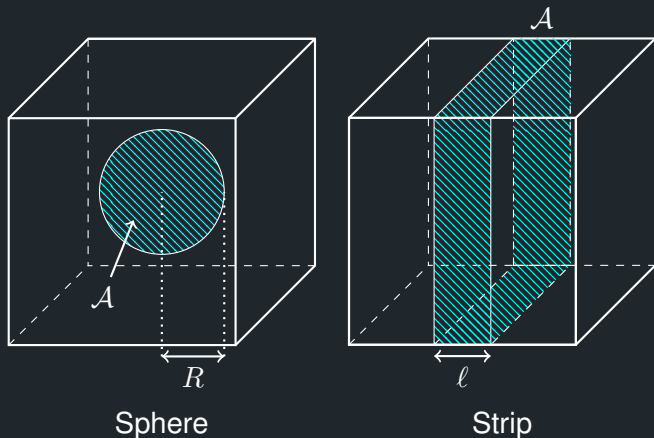
$$S_{\text{EE}} = -\text{Tr} \rho_{\mathcal{A}} \log \rho_{\mathcal{A}}$$

# Entanglement entropy

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For a QFT, it is natural to divide the Hilbert space by dividing a spatial slice of the manifold on which the QFT lives.

We make two choices of  $\mathcal{A}$ :



# The first law of entanglement

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Modular Hamiltonian  $H$ :  $\rho_A \equiv e^{-H}$

For small perturbations of the state of a QFT:

$$\delta S_{EE} = \delta \langle H \rangle \quad \text{“First law of entanglement”}$$

D. D. Blanco, H. Casini, L. Hung,  
R. C. Myers, 1305.3182 [hep-th]

Sometimes the change in the modular Hamiltonian is proportional to the change in energy

$$\delta S_{EE} = \frac{\delta E}{T_{\text{ent}}}$$

J. Bhattacharya, M. Nozaki, T. Takayanagi,  
T. Ugajin, 1212.1164 [hep-th]

Comparing different states in different theories, the first law may not hold. We will study certain time-dependent perturbations to Hamiltonians.

Entanglement entropy is difficult to calculate in QFT, so we use holography.

# Entanglement entropy in holography

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In AdS/CFT: a gravity theory on AdS  $\Leftrightarrow$  CFT on its boundary

EE in the CFT is proportional to the area of an extremal surface in the AdS space.

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Boundary

Time-independent holographic EE:

S. Ryu, T. Takayanagi, hep-th/0603001

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Time-dependent holographic EE:

V. E. Hubeny, M. Rangamani, T. Takayanagi, 0705.0016 [hep-th]

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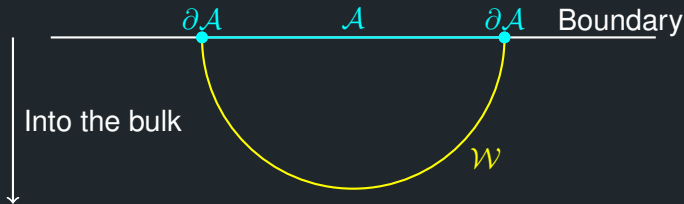


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$$S_{EE} = \frac{A[\mathcal{W}]}{4G_N}$$

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# Perturbative holographic entanglement entropy

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Area is a functional of embedding:  $A[X, G]$

Metric  $G$  = background + perturbation

Perturbing the background metric changes EE

$$\delta S_{\text{EE}} = \frac{1}{4G_N} \int d^{d-2}\xi \left( \frac{\delta A}{\delta X^m} \delta X^m + \frac{\delta A}{\delta G_{mn}} \delta G_{mn} \right)$$

Change in embedding                      Change in metric

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$$\delta S_{\text{EE}} = \frac{1}{4G_N} \int d^{d-2}\xi \frac{\delta A}{\delta G_{mn}} \delta G_{mn}$$

$\frac{\delta A}{\delta G_{mn}}$  and the integral are evaluated on the extremal surface in the background metric.

# A first law for rates

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Asymptotically AdS metric

$$ds^2 = \frac{L^2}{z^2} (dz^2 + g_{\mu\nu} dx^\mu dx^\nu)$$
$$g_{\mu\nu} = g_{\mu\nu}^{(0)} + g_{\mu\nu}^{(2)} z^2 + \dots + g_{\mu\nu}^{(d)} z^d + \dots$$

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Our setup:

$$\text{Background: } ds^2 = \frac{L^2}{z^2} (dz^2 + g_{tt}(z) dt^2 + g_{xx}(z) \delta_{ij} dx^i dx^j)$$

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	$\delta g_{ij} = \delta g_{xx} \delta_{ij}$	Rotational invariance
	$\partial_t \delta g_{\mu\nu}^{(n < d)} = 0$	Boundary conditions



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First law of entanglement rates:  $\partial_t \delta S_{\text{EE}} \propto \partial_t \delta E$

## A first law for rates

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Under our assumptions, rate of change of EE

$$\partial_t \delta S_{\text{EE}} = \partial_t \delta g_{xx}^{(d)} \frac{d}{4G_N} \int d^{d-2} \xi z^d \frac{\delta A}{\delta g_{xx}}$$

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Boundary stress tensor

$$\langle T_{\mu\nu} \rangle = \frac{dL^{d-1}}{16\pi G_N} g_{\mu\nu}^{(d)} + X_{\mu\nu} [g^{(n<d)}]$$

S. de Haro, K. Skenderis,  
S. N. Solodukhin, hep-th/0002230

$\delta g^{(d)}$  traceless  $\Rightarrow \delta \langle T_{tt} \rangle = d \delta \langle T_{xx} \rangle - \delta X^\mu{}_\mu$

With our assumptions, the Weyl anomaly is time-independent,  
 $\partial_t \delta \langle T^\mu{}_\mu \rangle = \partial_t \delta X^\mu{}_\mu = 0$ , so rate of change of the energy:

$$\partial_t \delta E = \partial_t \delta g_{xx}^{(d)} \frac{d(d-1)L^{d-1}}{16\pi G_N} \text{Vol}(\mathcal{A})$$

## A first law for rates

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Rate of change of energy is proportional to rate of change of EE, “First law of entanglement rates”:

$$\partial_t \delta S_{\text{EE}} = \partial_t \delta E \underbrace{\frac{1}{4\pi(d-1)L^{d-1}\text{Vol}(\mathcal{A})} \int d^{d-2}\xi z^d \frac{\delta A}{\delta g_{xx}}}_{T_{\text{ent}}^{-1}}$$

# Massless scalar field

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Einstein gravity coupled to massless scalar field

$$S = \frac{1}{16\pi G_N} \int d^{d+1}x \sqrt{-G} \left( R - 2\Lambda - 8\pi G_N (\partial\phi)^2 \right)$$

Massless scalar  $\phi \leftrightarrow$  Marginal scalar operator  $\mathcal{O}$

$$\phi = \underbrace{\phi_0}_{\text{Source}} + \phi_2 z^2 + \dots + \underbrace{\phi_d z^d}_{\text{Determines } \langle \mathcal{O} \rangle} + \dots$$

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Choose a source  $\phi_0 = -ct$ .

Shift symmetry of  $\phi \Rightarrow g_{\mu\nu}^{(n < d)}$  depend only on derivatives of  $\phi$   
 $\Rightarrow$  are time independent.

# Massless scalar field

---

To be concrete, choose  $d = 3$ .

Solving Einstein's equations near the boundary:

$$g_{\mu\nu} = \eta_{\mu\nu} + (8\pi G_N c^2 \delta_\mu^t \delta_\nu^t + 2\pi G_N c^2 \eta_{\mu\nu}) z^2 + \delta g_{\mu\nu}^{(3)} z^3 + \dots$$
$$\phi = -ct + \phi_3 z^3 + \dots$$

Coefficients of  $z^3$  undetermined by near boundary analysis.

Time-independent contribution to EE from coefficient of  $z^2$ .  
Time-dependent contribution from coefficient of  $z^3$ .



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Boundary energy momentum tensor

$$\langle T_{\mu\nu} \rangle = -\frac{2}{\sqrt{-g^{(0)}}} \frac{\delta S}{\delta g_{\mu\nu}^{(0)}} = \frac{3L^2}{16\pi G_N} g_{\mu\nu}^{(3)}$$

Contribution to energy comes from the coefficient of  $z^3$ .

# Massless scalar field

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$$\delta S_{\text{EE}}^{\text{sphere}} = \frac{\delta E}{T_{\text{ent}}^{\text{sphere}}} + \frac{2}{3}\pi c^2 R^2$$
$$\delta S_{\text{EE}}^{\text{strip}} = \frac{\delta E}{T_{\text{ent}}^{\text{strip}}} + \frac{\pi^2 \Gamma\left(\frac{1}{4}\right)}{6\sqrt{2}\Gamma^3\left(\frac{3}{4}\right)} c^2 \ell \text{Vol}(\mathbb{R})$$

First law of entanglement is violated, but taking time derivatives gives a first law for the rates.

Entanglement temperature depends on geometry:

$$T_{\text{ent}}^{\text{sphere}} = \frac{2}{\pi R}$$
$$T_{\text{ent}}^{\text{strip}} = \frac{16\Gamma\left(\frac{3}{4}\right)}{\pi\Gamma^2\left(\frac{1}{4}\right)} \frac{1}{\ell}$$

The same as for a time-independent perturbation of the state of a 3d CFT.

# Massless scalar field

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Can carry out the same calculation in other dimensions.

In  $d = 2$

$$\delta S_{\text{EE}} = \frac{\delta E}{T_{\text{ent}}} + \frac{2\pi}{9} c^2 R^2 (4 - 3 \log(2R/L) + 6\eta)$$

$\eta$  comes from scheme dependence in renormalization.

In  $d = 4$ , for a sphere

$$\delta S_{\text{EE}} = \frac{\delta E}{T_{\text{ent}}} - \frac{\pi^2}{9} c^2 R^2 (5 - 6 \log(2R/\epsilon))$$

$\epsilon$  is a short distance cutoff.

# An example with an electric field

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On  $\text{AdS}_5 \times \text{S}_5$ , insert a D7-brane filling the  $\text{AdS}_5 \times \text{S}_3$  subspace.

$$S_{\text{D7}} \propto \int d^8 \zeta \sqrt{-\det(\Gamma_{ab} + 2\pi\alpha' F_{ab})}$$

Metric on D7-brane  $\nearrow$  U(1) gauge field strength  $\uparrow$

Make ansatz for  $x$  component of gauge field:

$$A_x = -\mathcal{E} t + a_x(u)$$

Electric field in CFT  $\nearrow$  Some function of radial coordinate  $\nwarrow$

To compute entanglement entropy and energy in the CFT, we need the linearised backreaction of the brane.

We find the first law for rates is satisfied for sphere and strip.

# Conclusions

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For time dependent perturbations under certain assumptions a first law for rates holds, but the first law in the form  $\delta S_{EE} \propto \delta E$  can be violated.

Explicit examples of a first law for rates: marginal scalar operators with time-dependent sources, electric field.

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How general is the first law for rates? Answering this could help to understand non-equilibrium physics.