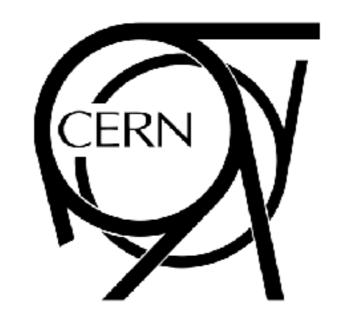
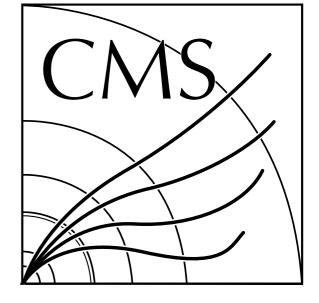
Machine learning applications to jet tagging in CMS

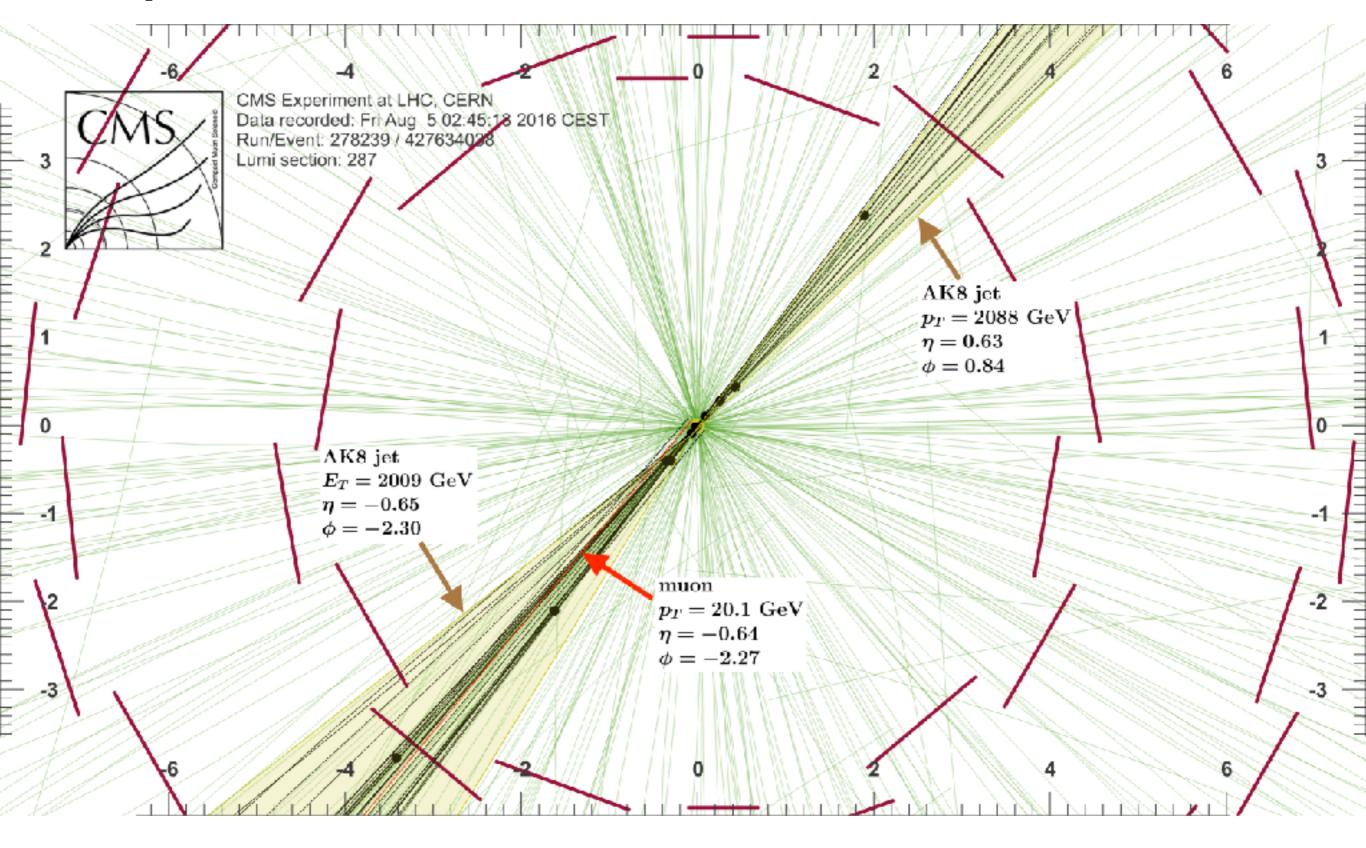
Mauro Verzetti (CERN and FWO) on behalf of the CMS Collaboration



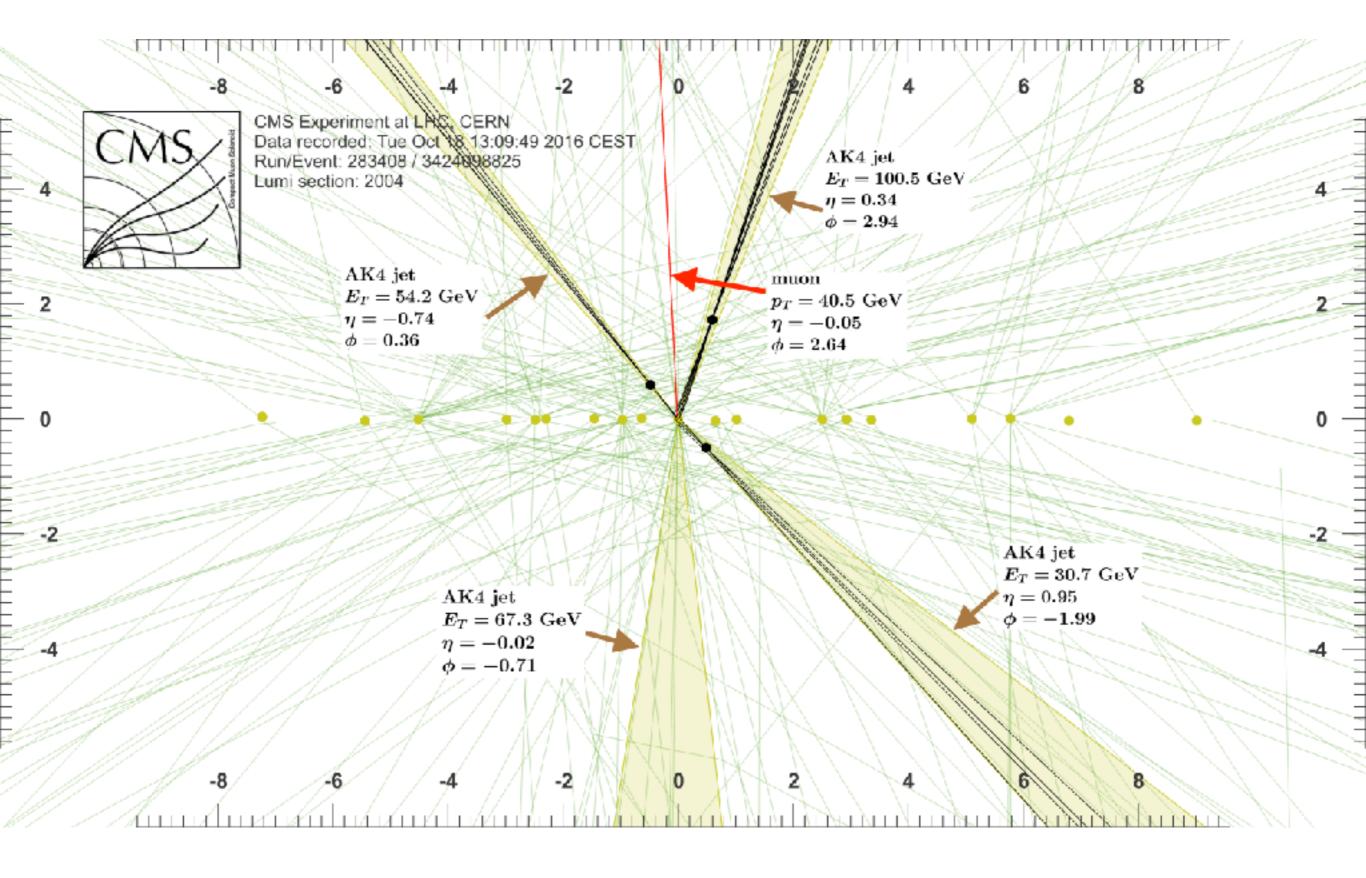




The problem

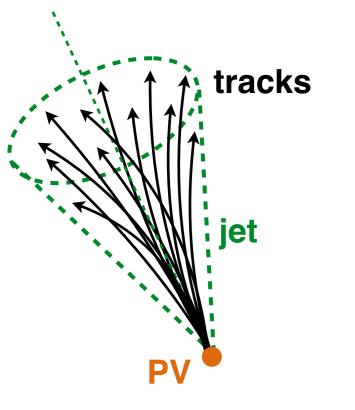


The problem

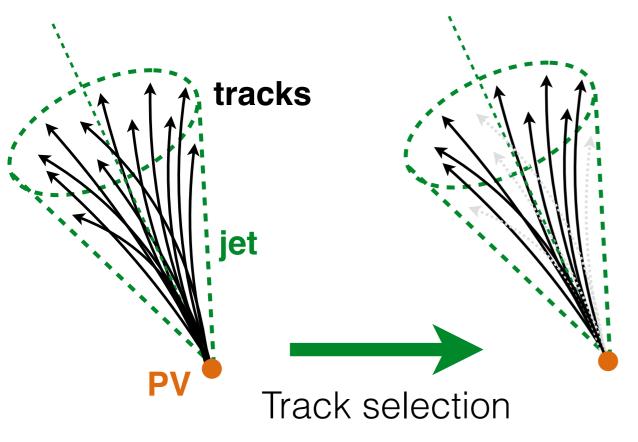


"resolved" AK4

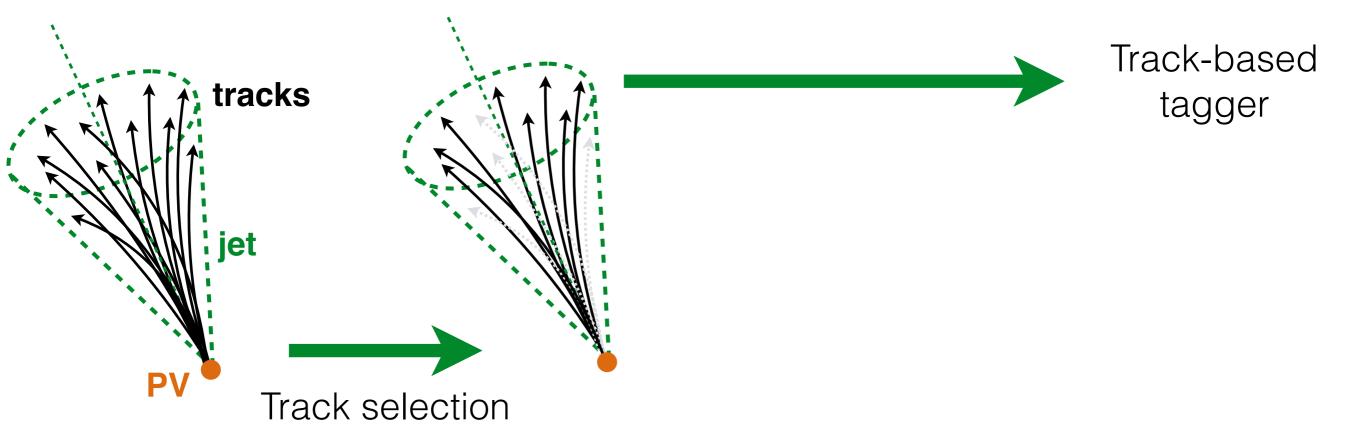
HF tagging @ CMS — <u>arXiv:1712.07158</u>



HF tagging @ CMS — <u>arXiv:1712.07158</u>



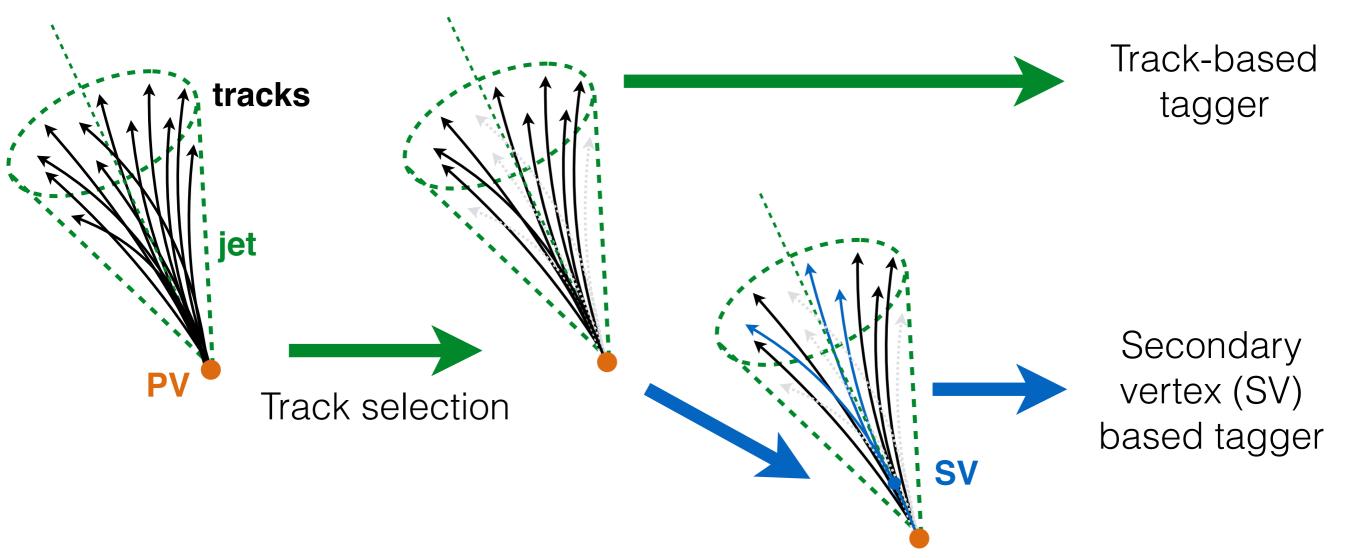
HF tagging @ CMS — <u>arXiv:1712.07158</u>



e.g.: Jet Probability (JP)

Few marking features → binned likelihood discriminant

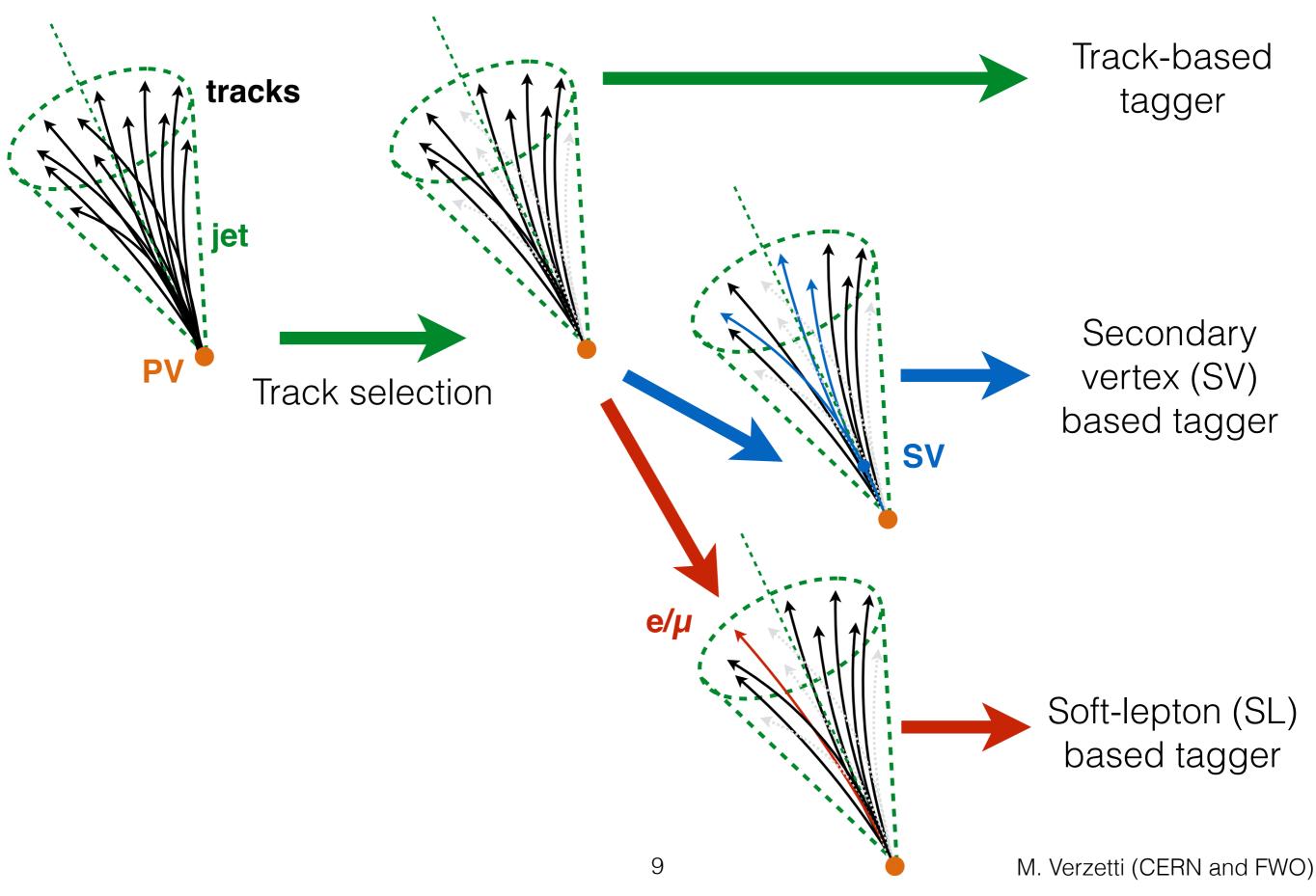
HF tagging @ CMS — <u>arXiv:1712.07158</u>

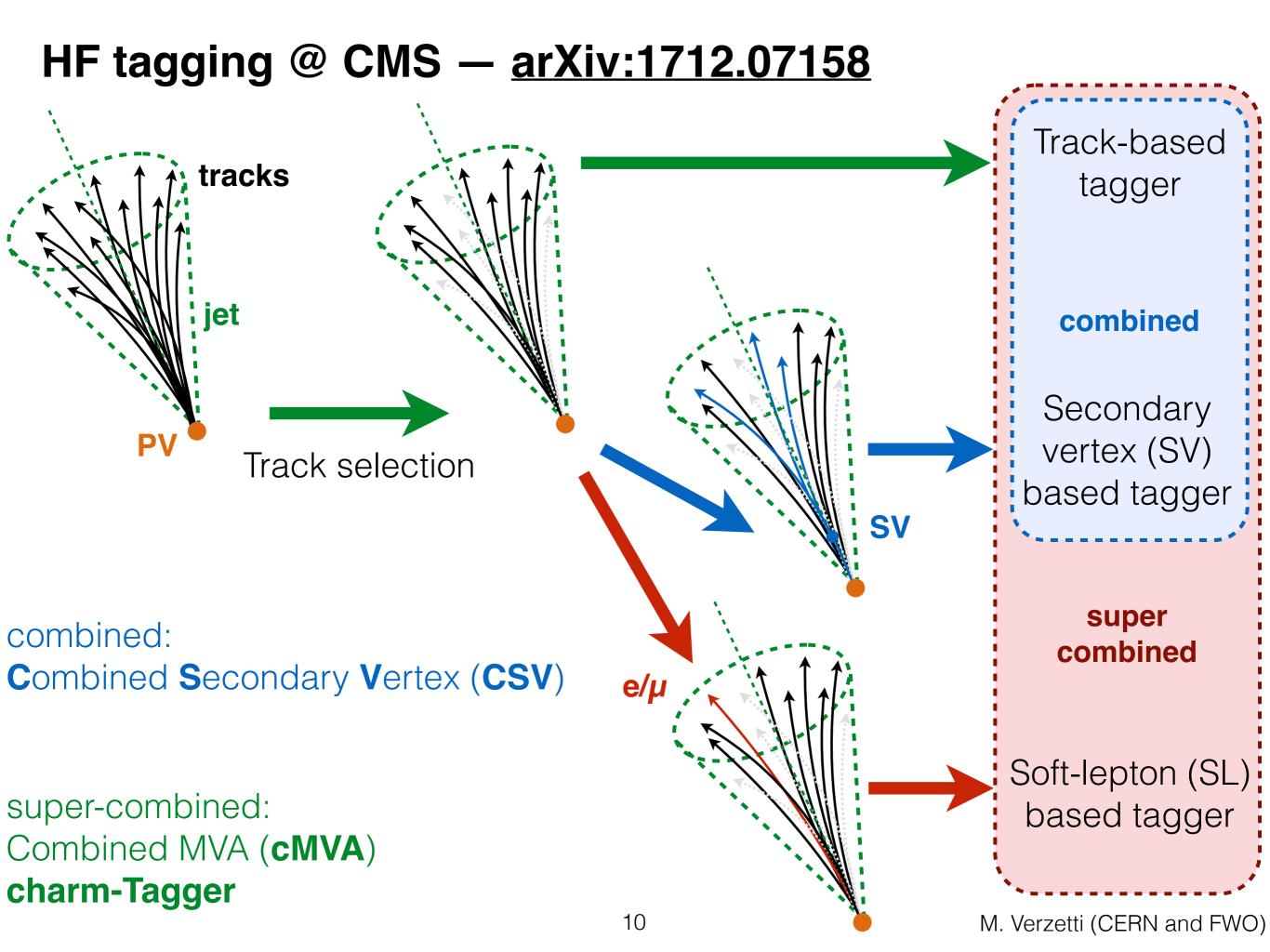


- Adaptive Vertex Reconstruction (AVR): applied on tracks associated to the jet
- Inclusive Vertex Fitter (IVF): on the full set of tracks recorded in the event (SV ΔR-matched to jet).

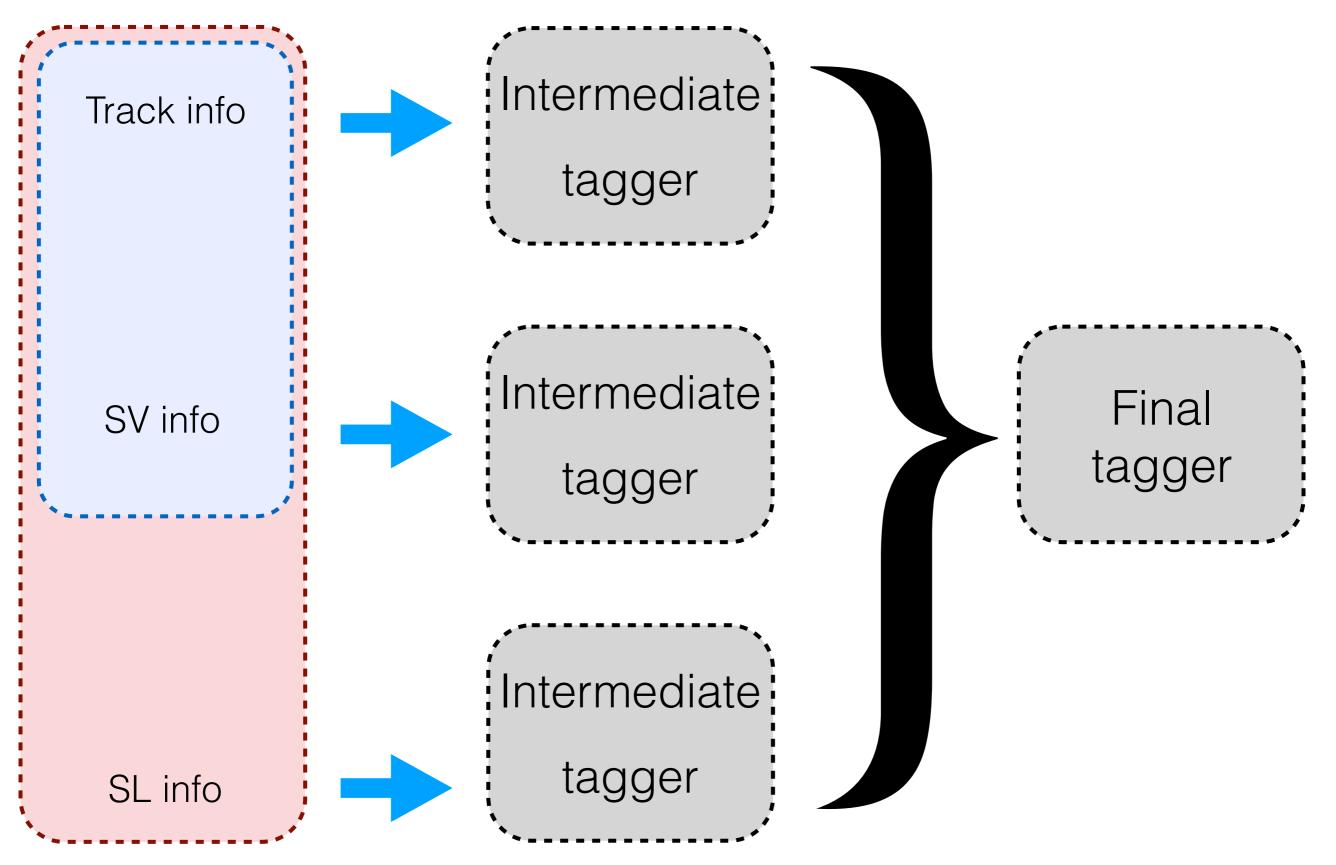
Current reconstruction default

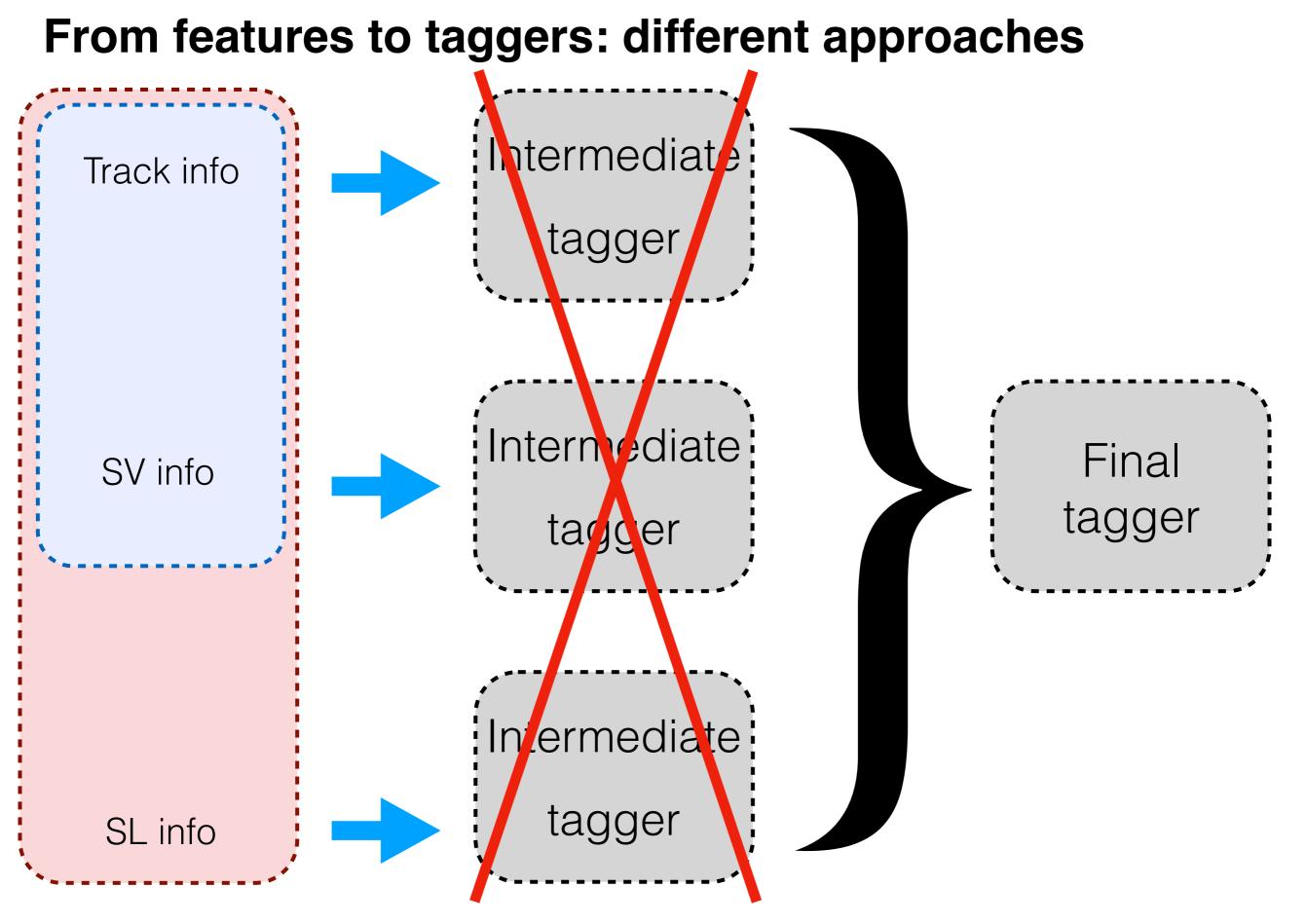
HF tagging @ CMS - <u>arXiv:1712.07158</u>





From features to taggers: different approaches

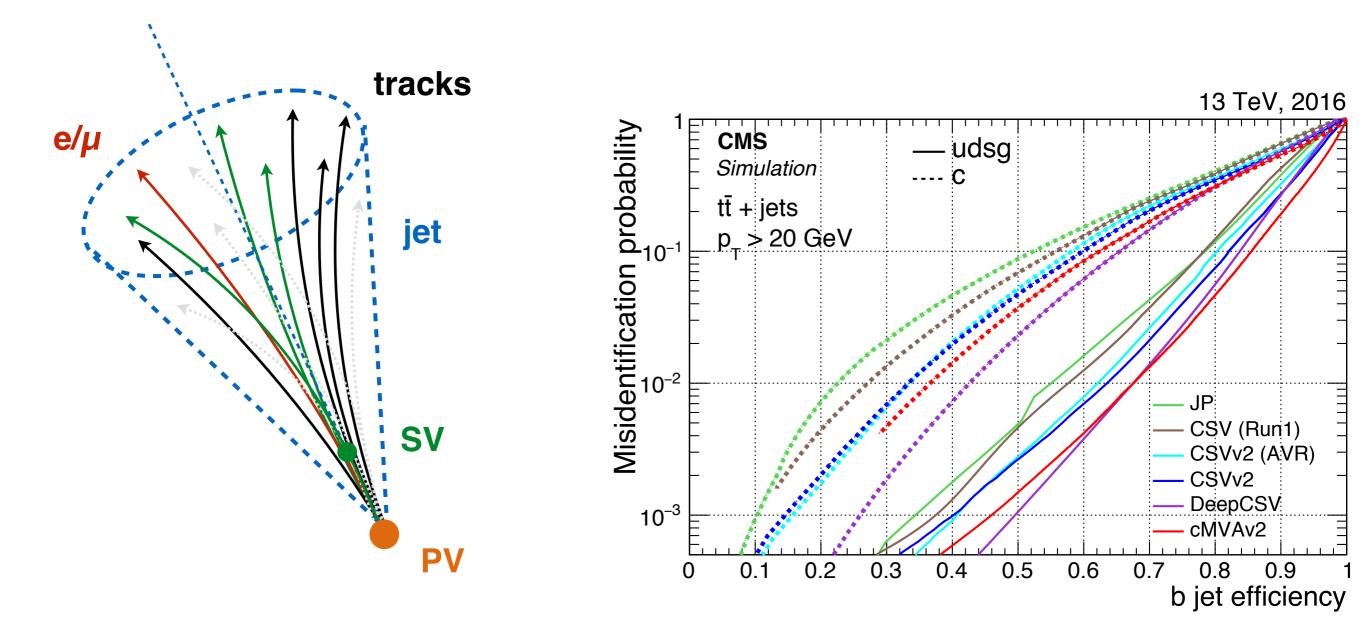




The four main CMS taggers

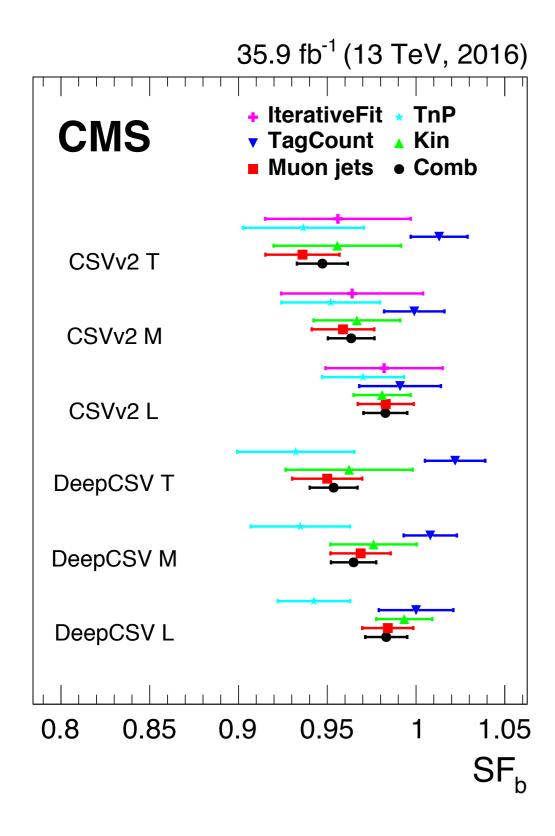
- CSVv2: three shallow NNs, depending on the vertex information, combined with a likelihood method
- cMVAv2: meta-tagger that combines the outputs of CSVv2 and other simpler taggers in a single BDT discriminator
- **C-tagger:** set of two BDT classifiers to identify charm jets
- DeepCSV: deep DNN that retains the simplicity of CSV, with a different ML approach

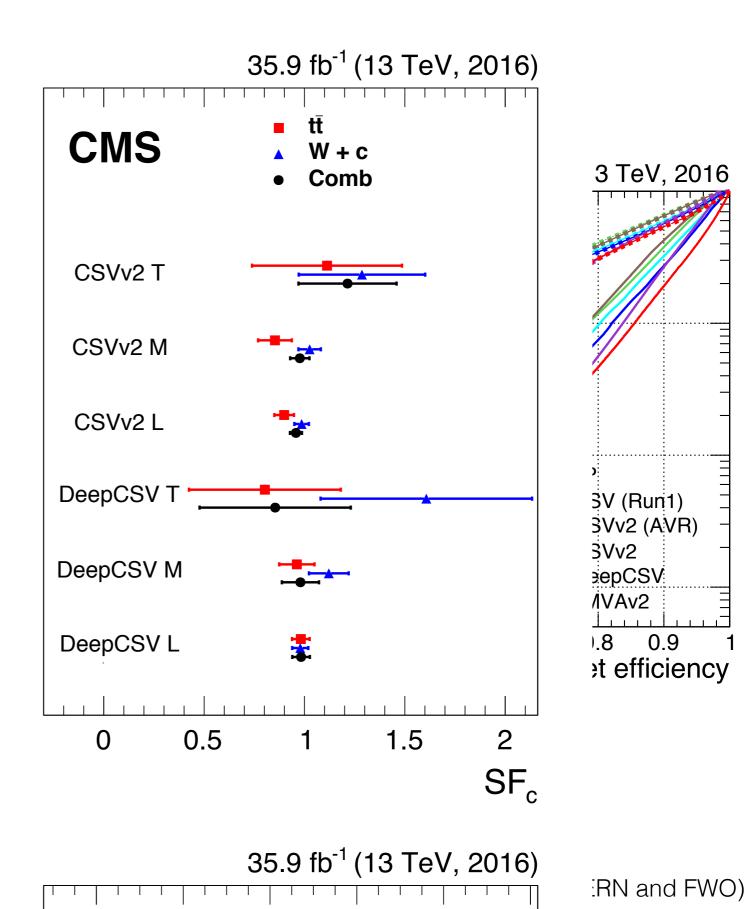
HF tagging @ CMS - arXiv:1712.07158



DeepNN shows best performance

HF tagging @ CMS - arXiv:1712.07158

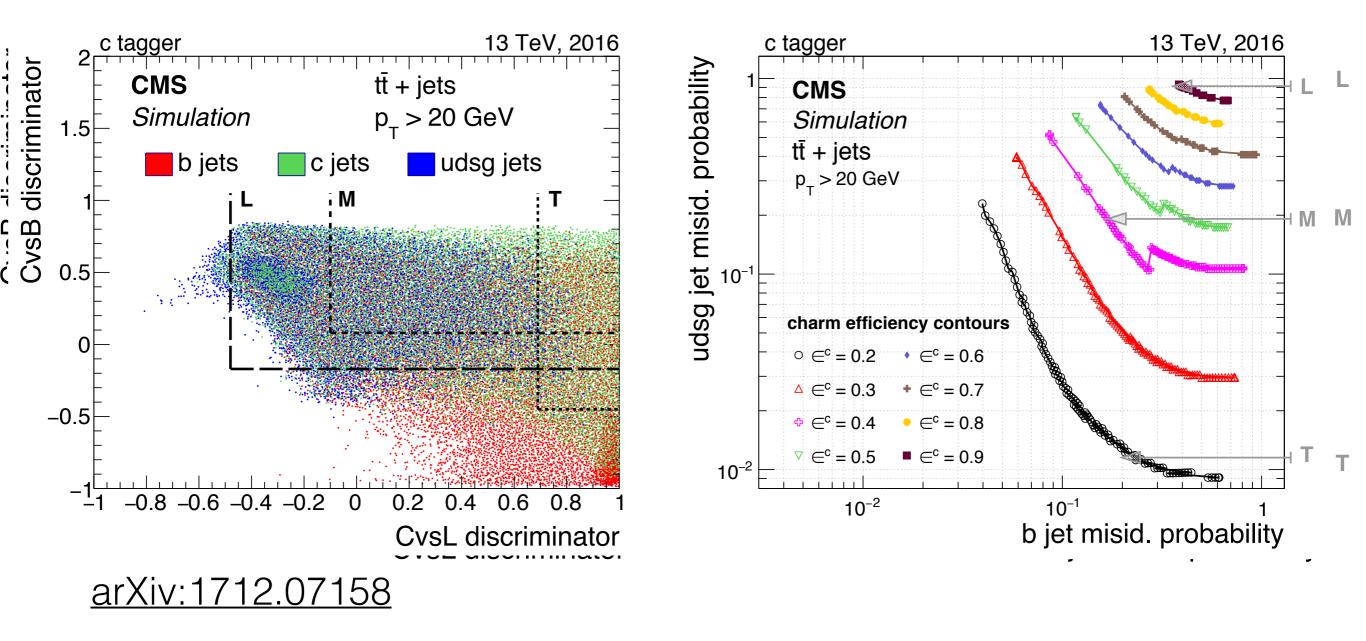




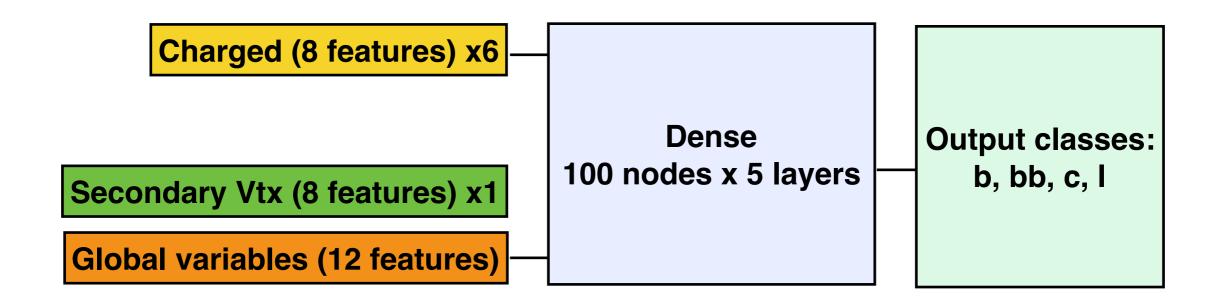


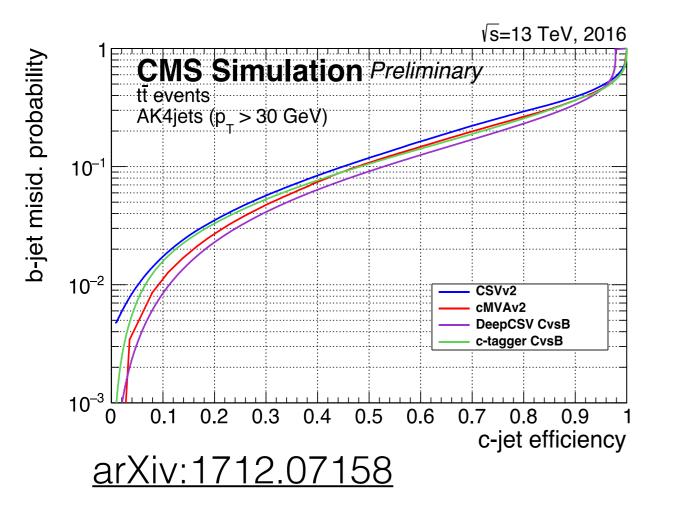
Charm tagging

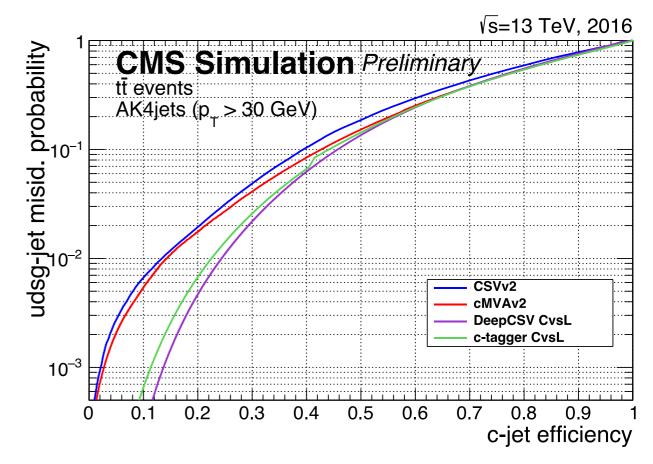
Use two BDT's to discriminate the charm from the light and B components



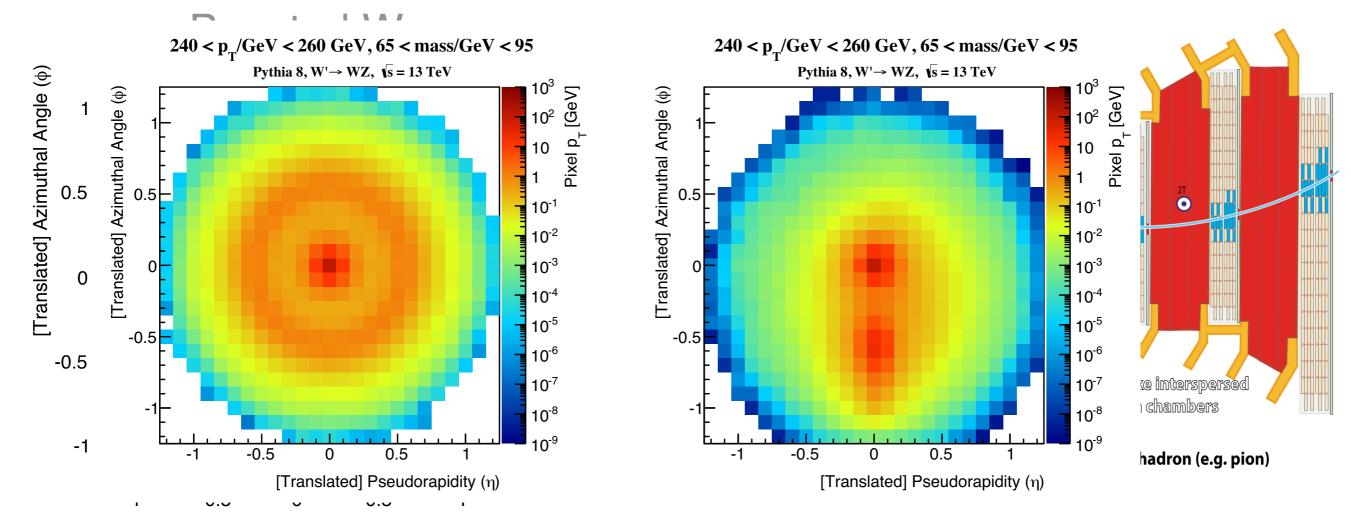
Heavy flavor jets with DNN — DeepCSV







After pre-processing, the leading subjet within the jet-image is located at the center of the image, and Trying more icomplex architectures image. In facial recognition tasks, this is equivalent to aligning the eyes within an image of a face. With such a standardized • Convolutional NN successfully applied in neutrino physics and image recognition in the jet-image, thus allowing the learning to focus more effectively on discrimination. The effect of • Some proposals for the state of the state of the second of the sec

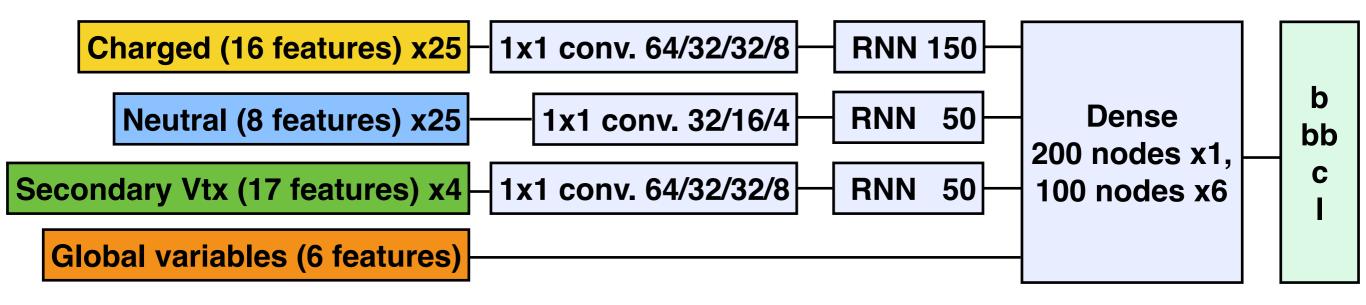


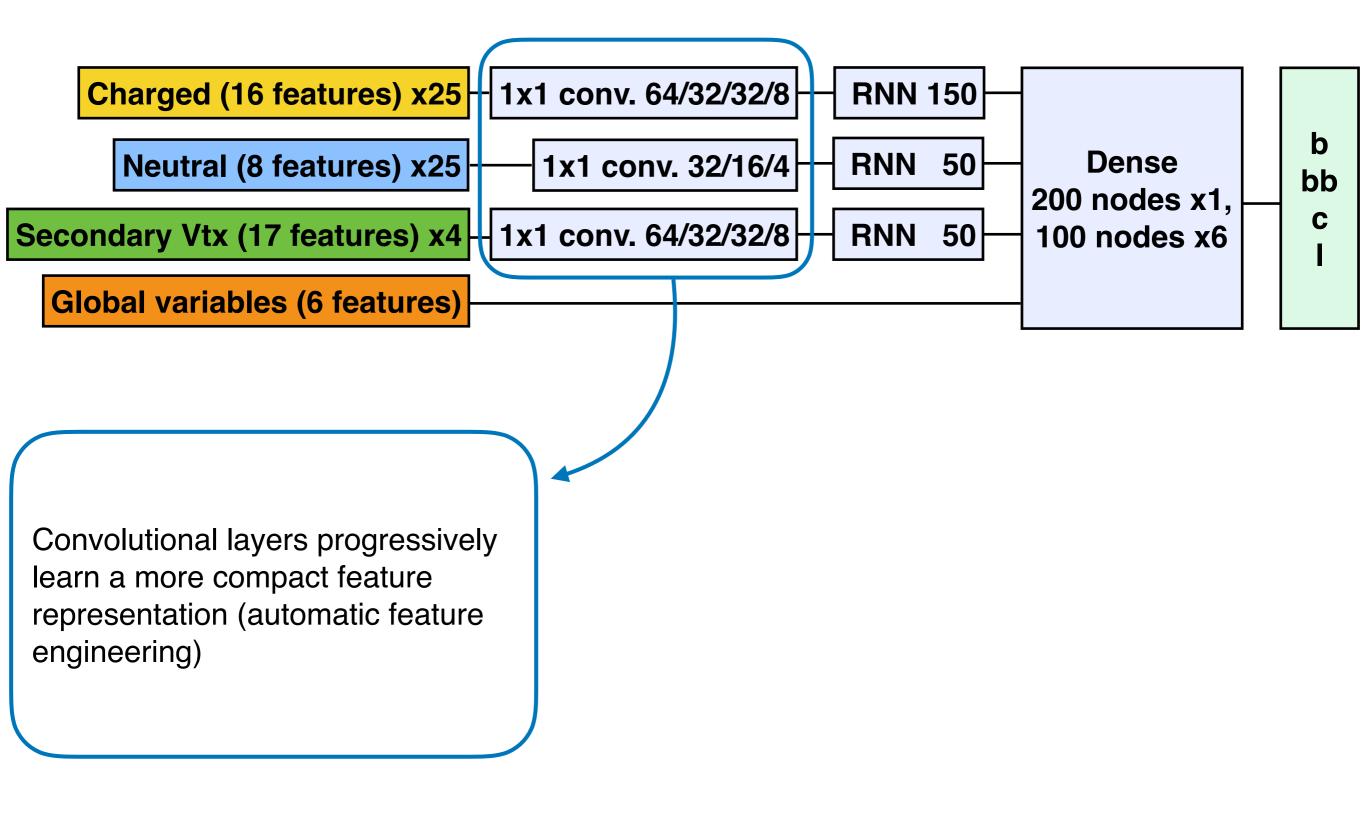
[Translated] Pseudorapidity (η) **Figure 1.** The average jet-image for W jets before (left) and after (right) pre-processing. The average is taken **but** r jet-images with 240 GeV/ $c < p_T < 260 \text{ GeV}/c$ and 65 GeV/ $c^2 < m < 95 \text{ GeV}/c^2$.

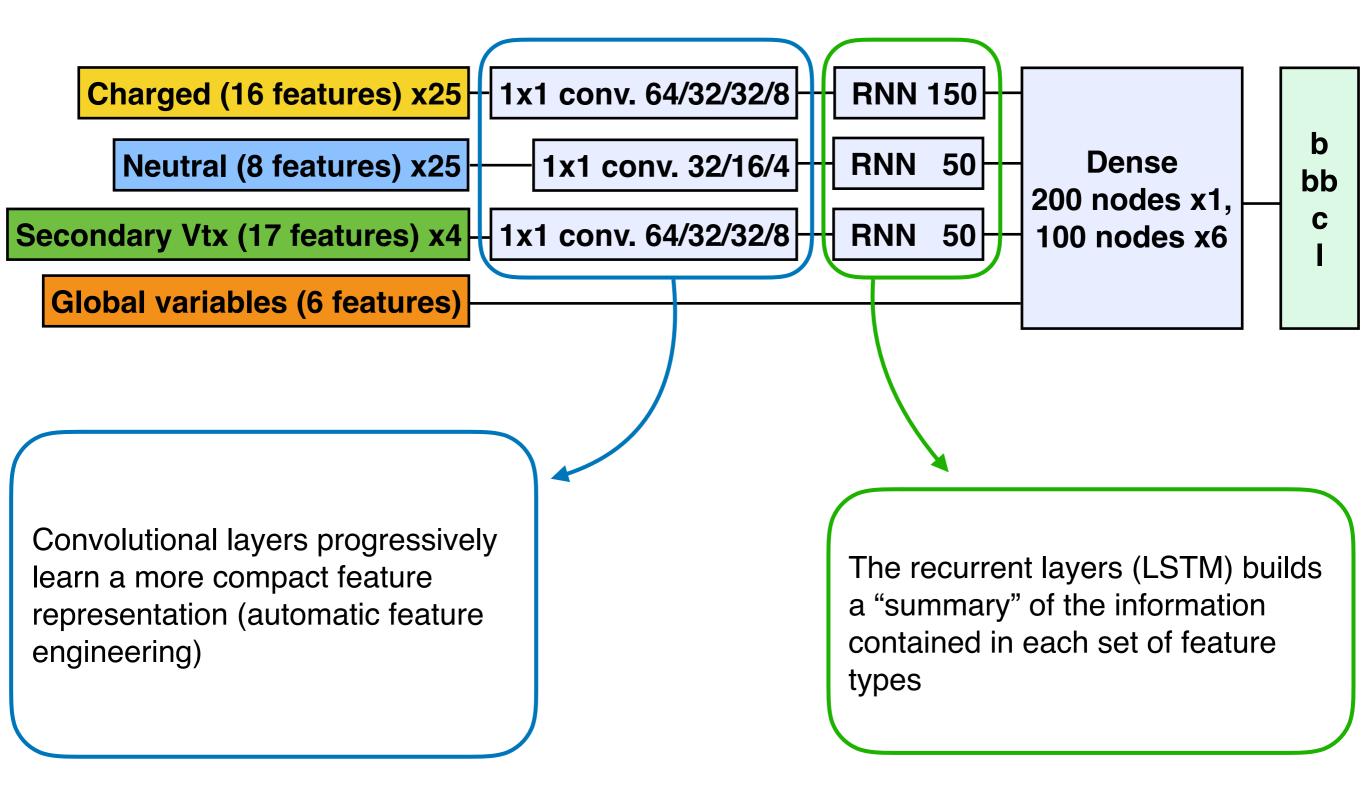
lookslike pormal images! S,•&##

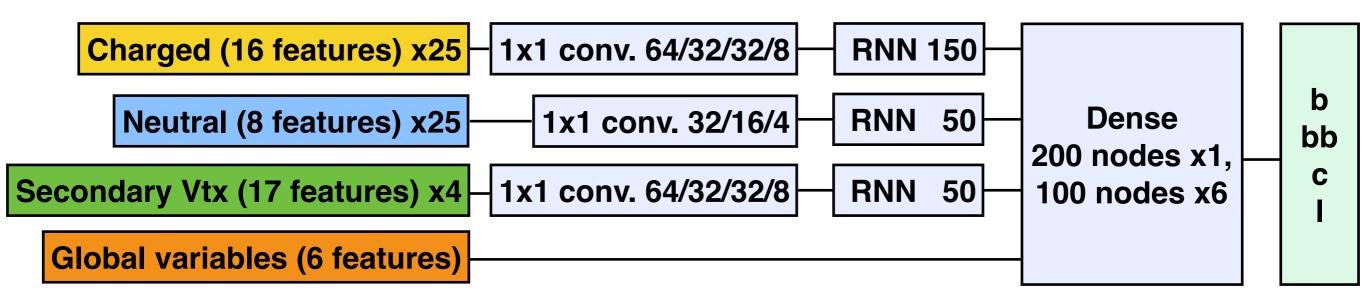
IS events are way more complex and bring more information than a flat image 4. Deep lear hing architectures and training

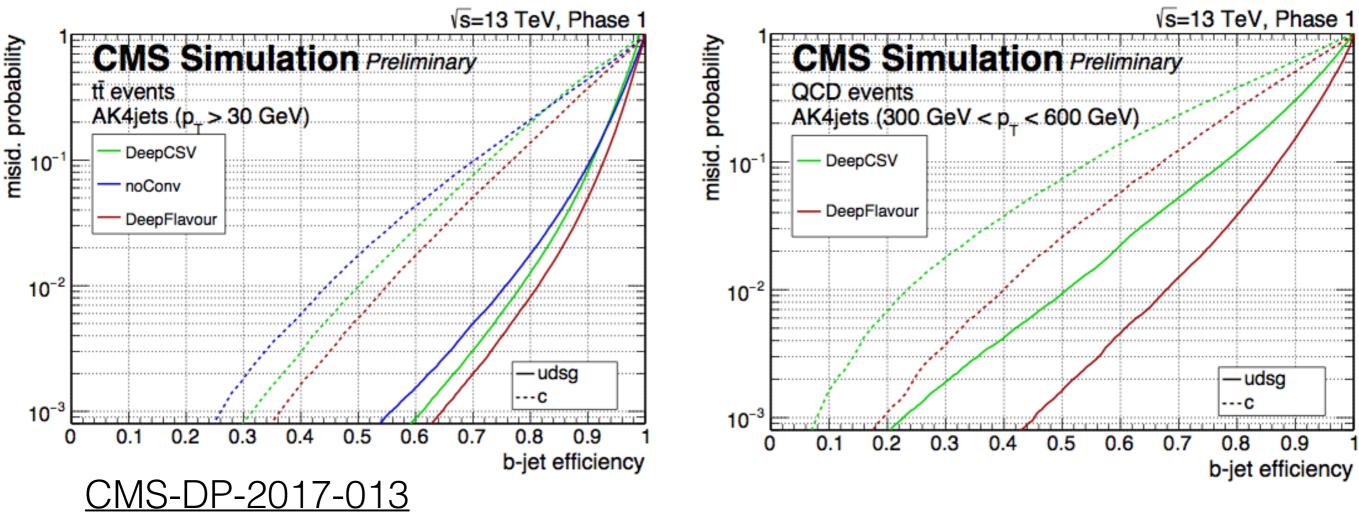
Discrimination between W and quark/gluon jet-images is performed using deep neural Metworks (CERN and FWO)

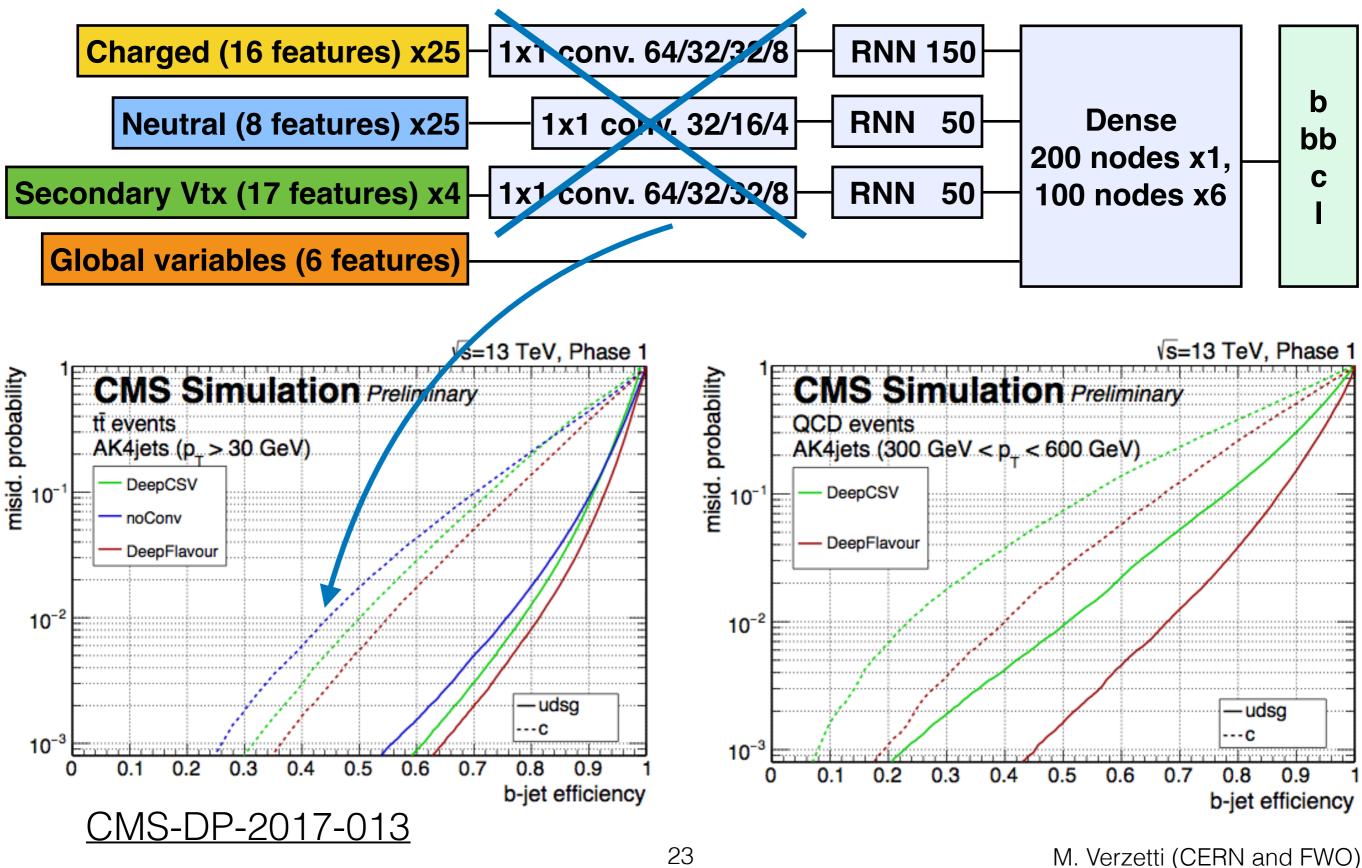


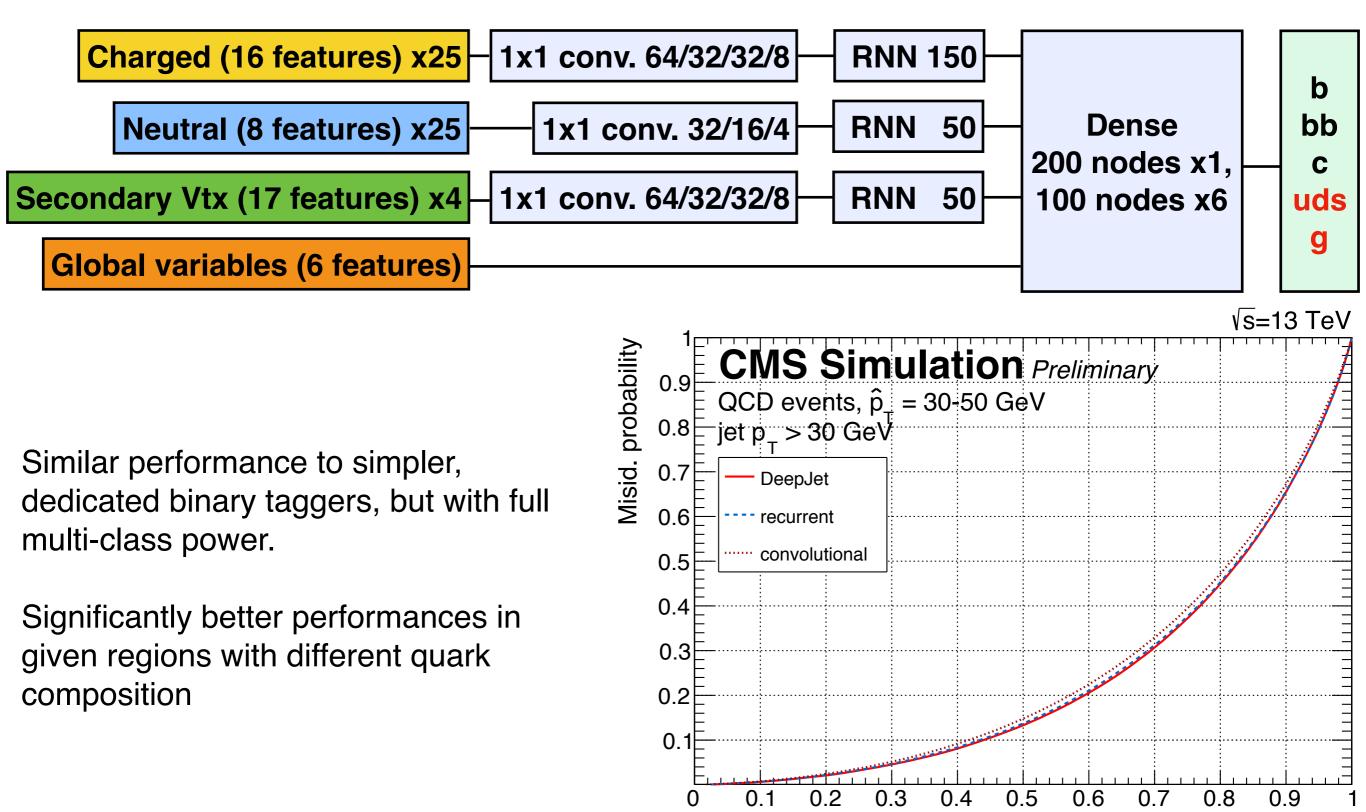










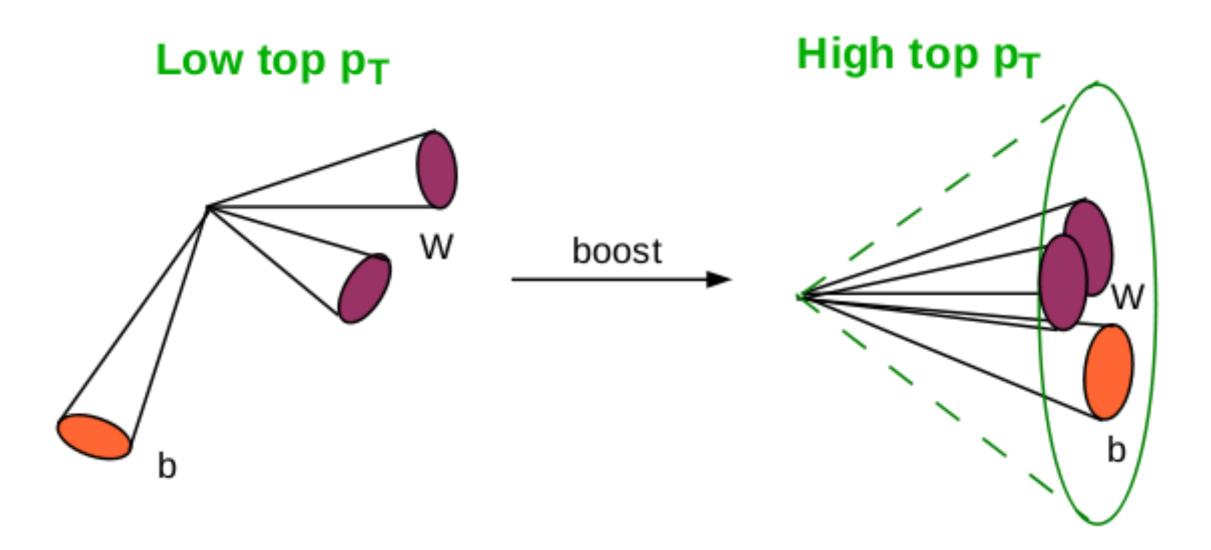


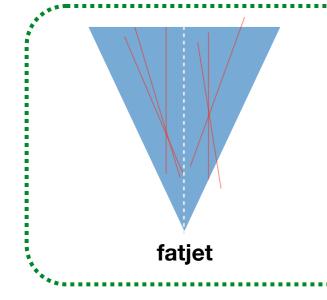
CMS-DP-2017-027

Light quark efficiency

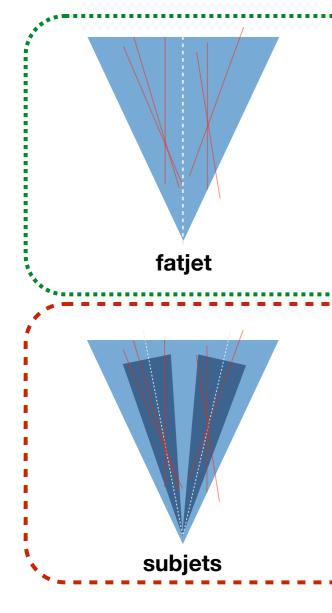
M. Verzetti (CERN and FWO)

Boosted objects AK8



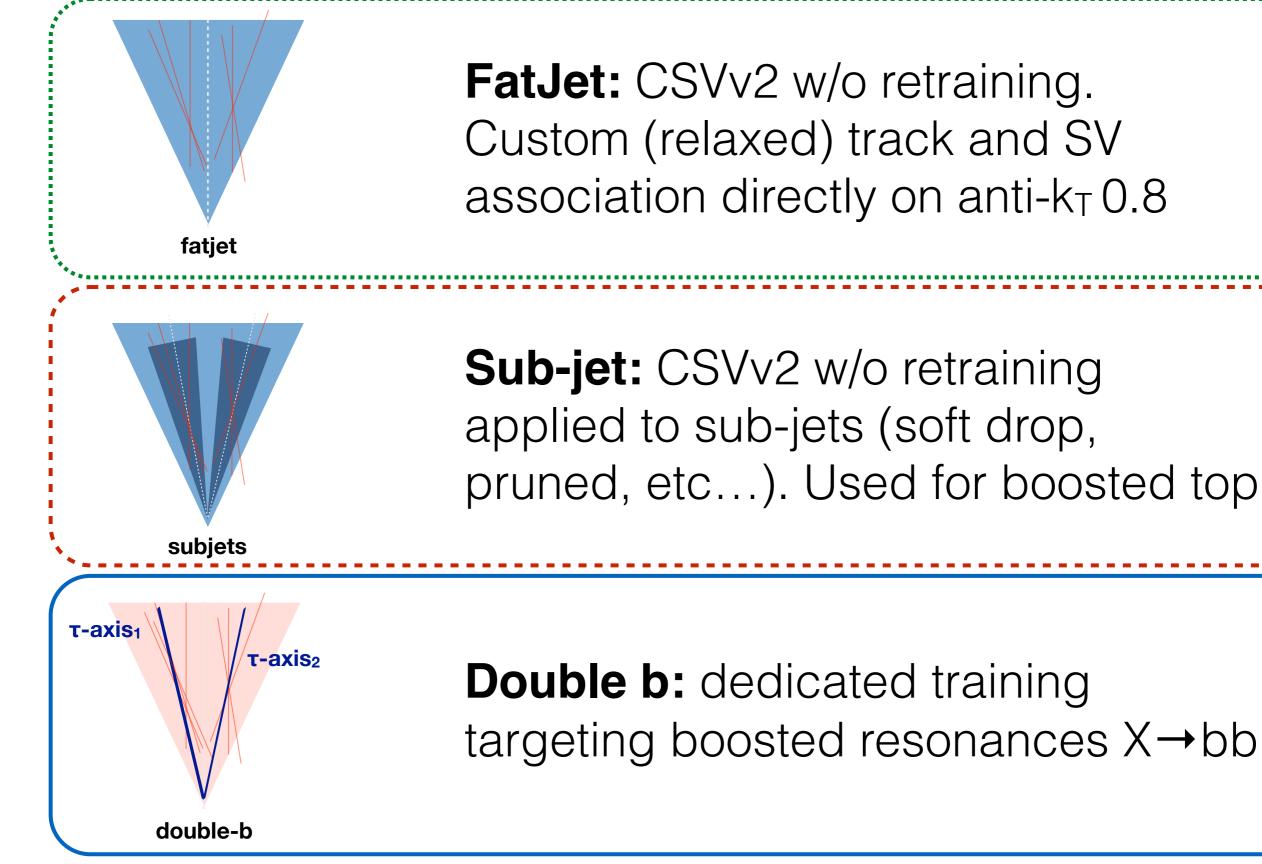


FatJet: CSVv2 w/o retraining. Custom (relaxed) track and SV association directly on anti- k_T 0.8



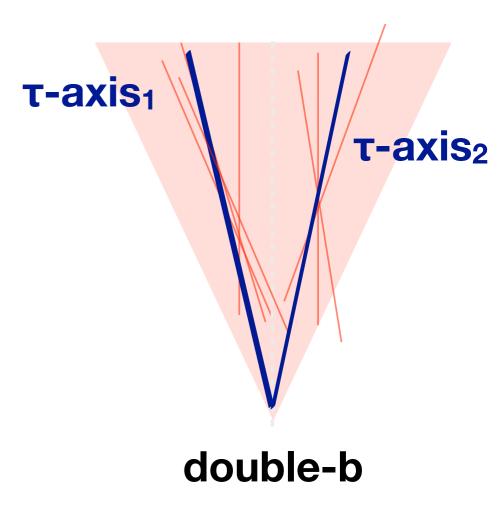
FatJet: CSVv2 w/o retraining. Custom (relaxed) track and SV association directly on anti- k_T 0.8

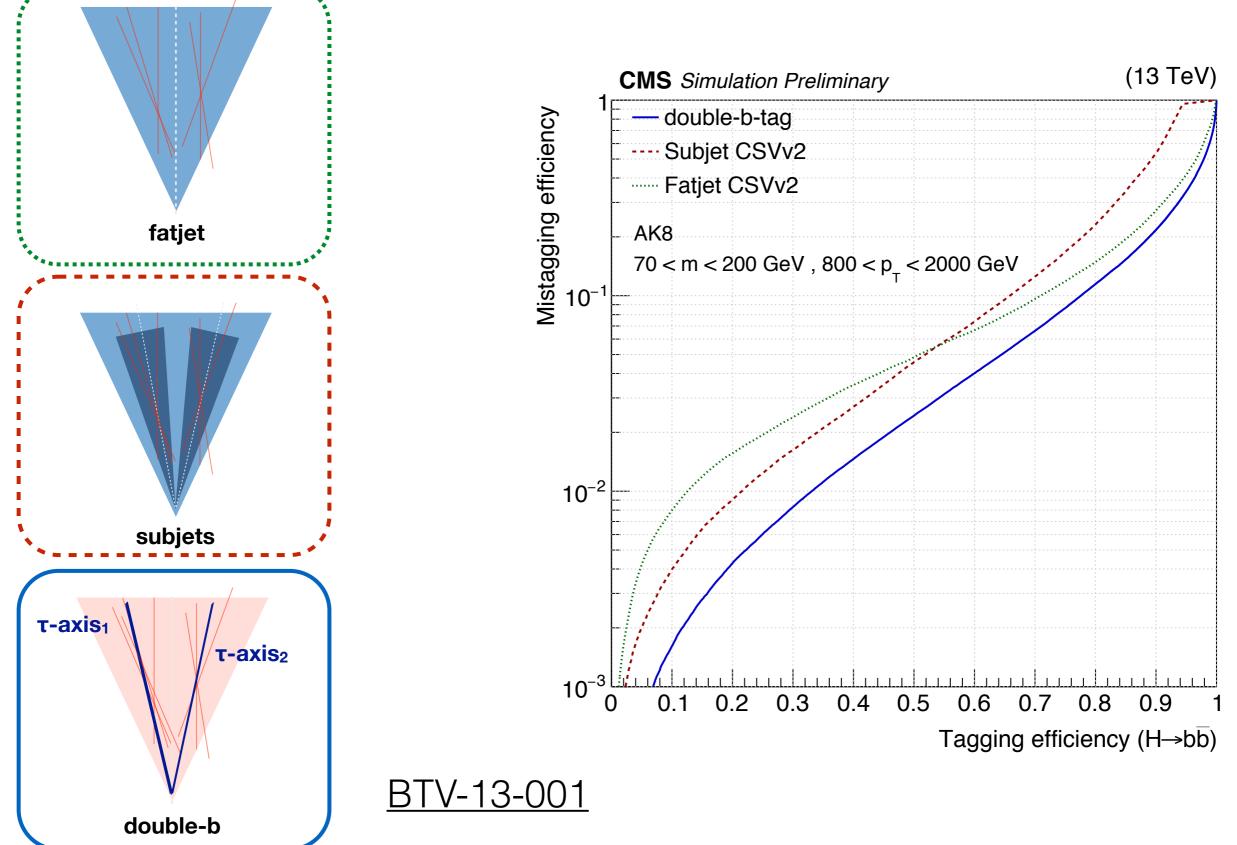
Sub-jet: CSVv2 w/o retraining applied to sub-jets (soft drop, pruned, etc...)



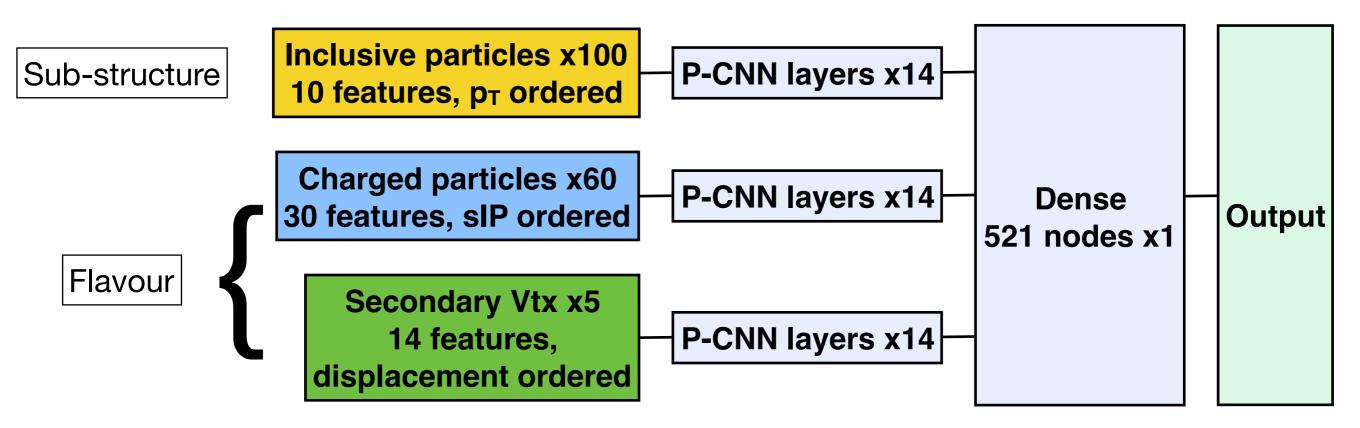
Double-b tagger

- All input features ~duplicated to account for the two sub-jet axes
- The input features are checked to be ~independent from the jet p_T and mass to ease background estimation in the analyses
- A total of 27 input features combined in a BDT

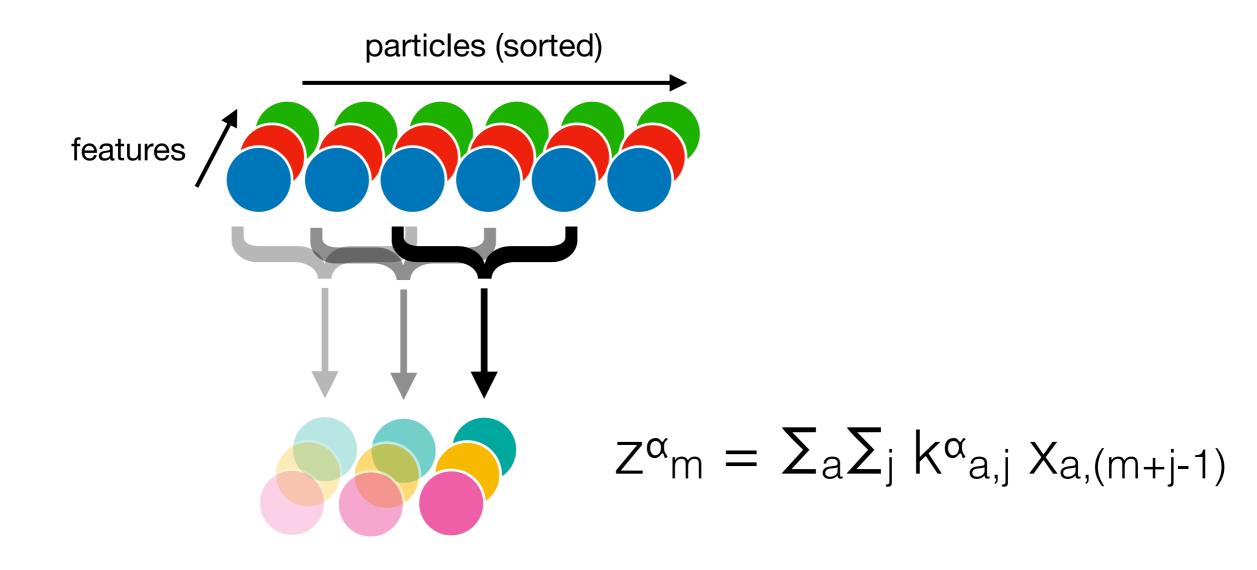


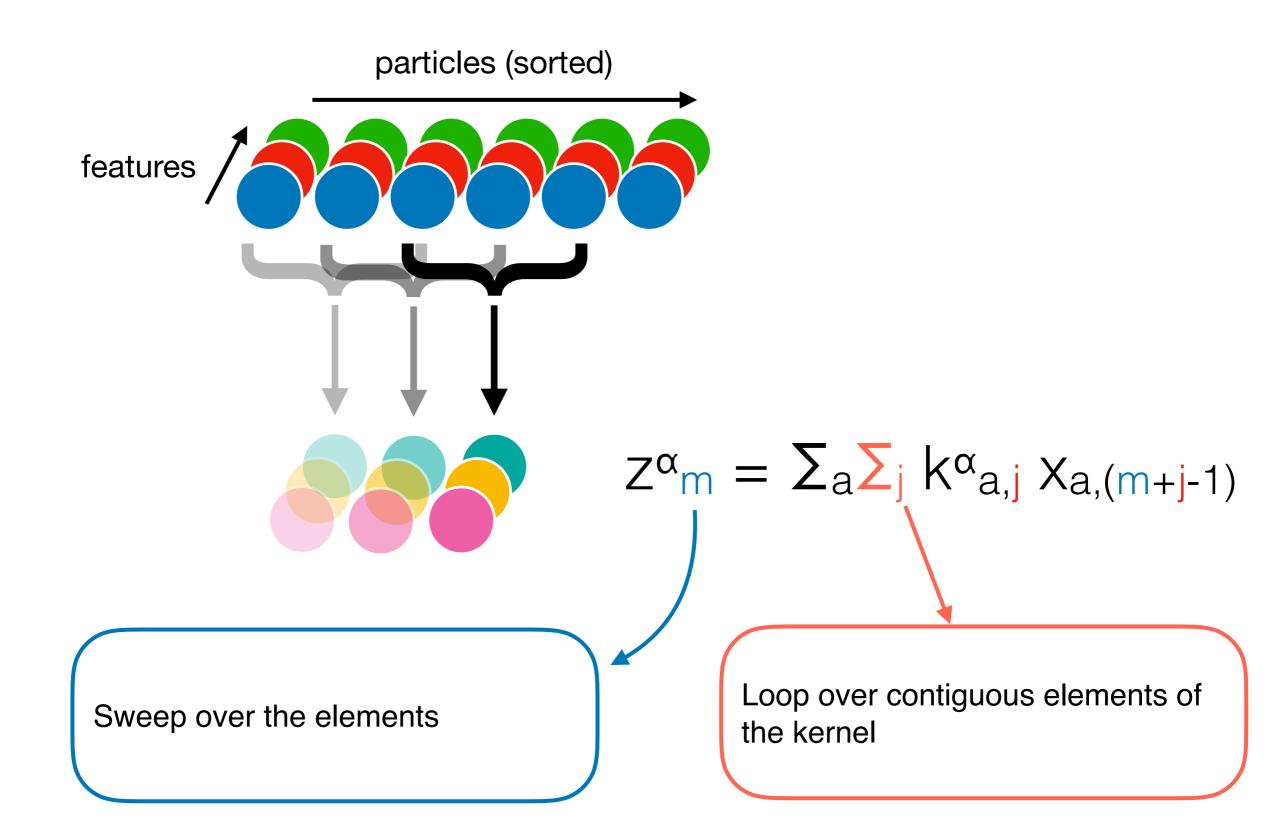


DeepJet for boosted resonances

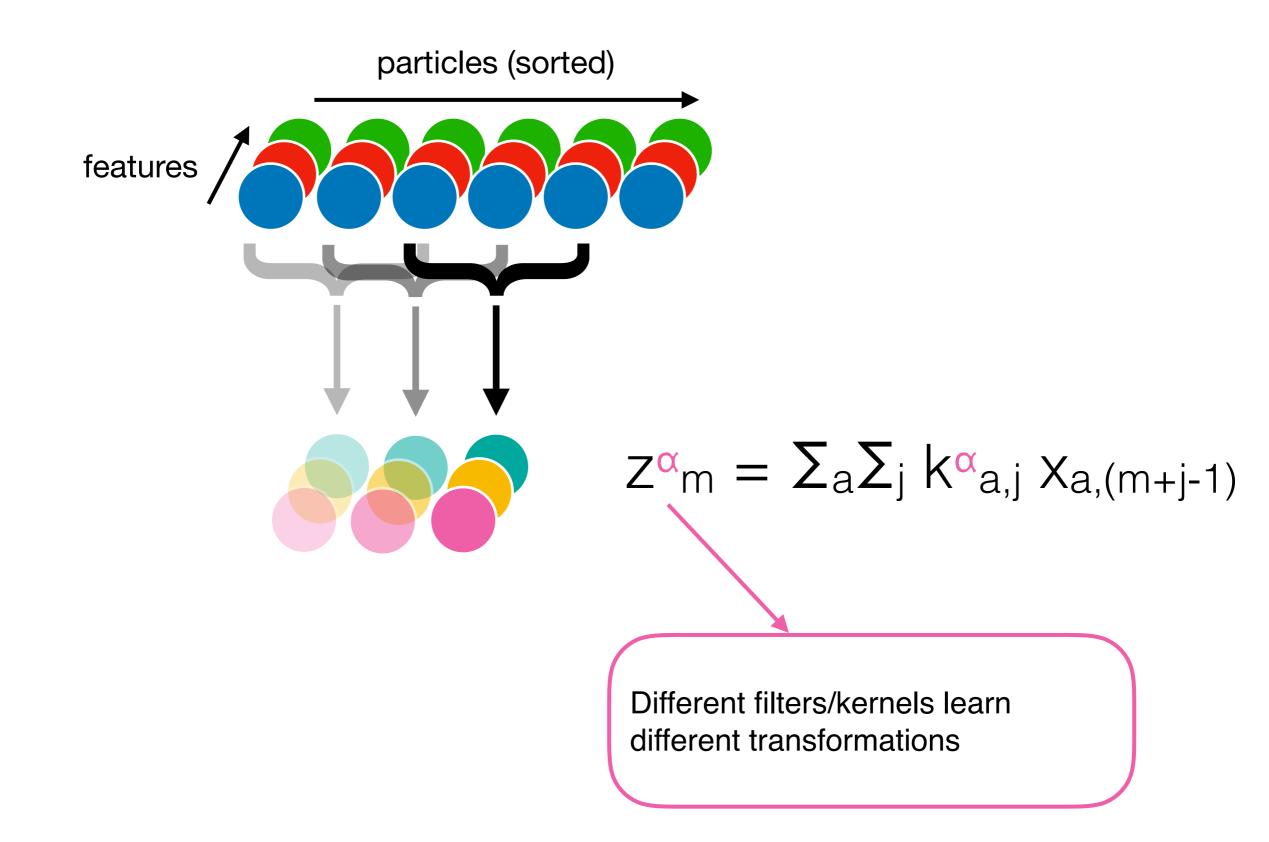


- Significantly larger amount of candidates used to accomodate for 90% of the fat jets
- Need to learn substructure from both charged and neutral candidates
- RNNs become computationally too expensive to train
- Use particle-level convolutional layers (P-CNN) where each feature is treated as a "colour"



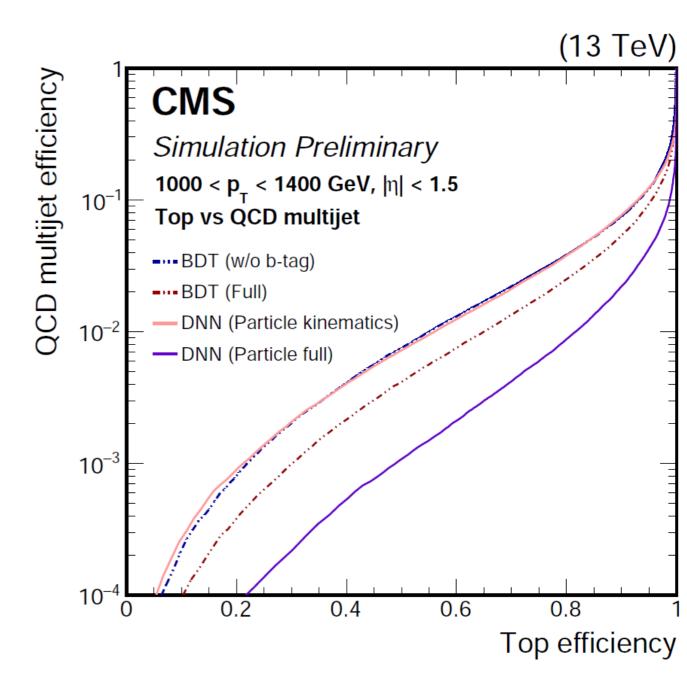


particles (sorted) features $Z^{\alpha}_{m} = \sum_{a} \sum_{j} k^{\alpha}_{a,j} X_{a,(m+j-1)}$ Multiple features ("colours") are accounted computing the transformation



Performance

- Flavour information largely improves jet tagging
- Large improvement w.r.t to the BDT approach
- Introduces mass sculpting, not necessarily a bad thing



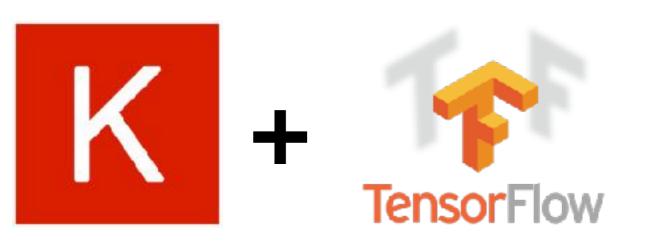
<u>CMS-DP-2017-049</u>

From training to practice

Two worlds colliding

Training / Analysis:

- Keras + TensorFlow
- Python-based
- Private productions
- Minimal interaction with ROOT
- Few processes, single threads
- Little memory constraints
- Expendable jobs



Production:

- Custom framework
- C++ based (speed!)
- Mostly ROOT-centric (at least I/O)
- Many processes, multiple threads
- Many other concurrent activities → memory constraints
- Processes cannot die (e.g. trigger)

Integration of DeepJet (AK4) into CMSSW. PR #19893

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#19 & Mer		
E.	pablodecm commented on 25 Jul 2017 • edited - Contributor +	Reviewers
		🚔 makortel 🖓 🖓
	This pull request integrates the new DeepFlavour tagger, using the library CMSSW-DNN by @riga (the	🍥 riga 🛛 🖓
	required part is also included) and adds it to the standard sequences. You can find an overview of the reason and design behind this PR in this BTV WG presentation.	👧 mverzett 🖓
		🅭 Dr15Jones 🖓
	PAT vs reference training framework (latest version)	Smuzaffar 🖓
	Here are some checks of compatibility of CMSSW pat-based discriminators computed using the producers develop for this PR with the output from the training framework (DeepJet) as 2D histograms	🔜 slava77 🖓 🖓

Integration of DeepJet (AK4) into CMSSW. PR #19893

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Backend choice

X Interface based on TF python API:

- Uses python C API and a pre-built TF package
- Large overhead and no handle on memory/threading
- X Interface based on TF C API:
 - Low level and not very convenient
 - Lots of customisations and ad-hoc handling needed
- $\sqrt{\text{Interface}}$ based on TF C++ API:
 - Access to all the needed internals for production usage with minimal need for custom code
 - Shallow interface to connect TF to the CMSSW internals (e.g. logging)

Issue 1: Multithreading

- TF starts lots of threads in its own thread pool to:
 - Faster loading of data
 - Parallelism between operations (inter_op_parallelism_threads)
 - Parallelism within operations (intra_op_parallelism_threads)
- Normally a good thing, has a critical impact on memory consumption in HEP frameworks, which have their own thread schemes/pools (CMSSW uses TBB)
- Solved with the implementation of two custom sessions:
 - Without any threading (NTSession)
 - Sharing the thread pool with the rest of the framework (TBBSession)

import os import psutil import tensorflow as tf p = psutil.Process(os.getpid()) print(p.num_threads()) $\rightarrow 2$ sess = tf.Session() $\rightarrow 10$ print(p.num_threads())

Issue 2: Memory footprint

- Initially DeepJet graph was large (~150MB)
 - Not feasible for production operations
 - Weights stored as Variables, which need more memory then Constants
 - By default Keras stores a lot of ancillary information on top of the model (operations and tensors used for training, optimiser status etc.)
- Reduction of O(10-100) by removing things not needed for inference and converting to constants
- Further reduction: one single computation graph loaded and shared across threads, multiple sessions computing inference
- In the future: AOT compilation?

Summary

- Jet tagging is of paramount importance for the CMS Physics program
- Lots of development in the last ~1.5 years to apply modern machine learning techniques to this field
 - Large improvements in performance
 - Still some room for new developments, especially in the boosted regime
- Flavour tagging is not only fancy algorithms, but solid and performing computing infrastructures as well