

Machine learning application for background modelling ATLAS Higgsino search in $hh \rightarrow 4b$

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Introduction

- BDT Reweighting for background modelling in the context of a Higgsino search in ATLAS
- Target Signal:
 - hh(→4b) + MET final state





• Two analyses

Low/High Higgsino mass → Low/High missing transverse energy



High-mass

- MET trigger
- Targets high signal masses
- Conference Note for SUSY17 : ATLAS-CONF-2017-081

• Backgrounds

- ~95% QCD
- ~5% leptonic ttbar (\rightarrow 50% for MET ~ 150 GeV)
- Jets
 - >= 4 jets with pT > 40 GeV
- Event categories :
 - 4-tag events : >= 4 jets are b-tagged
 - 2-tag events : == 2 jets are b-tagged

• Di-Higgs candidates:

- Use Dhh to resolve pairing ambiguity (3 combinations)
- Shortest distance to line from (0,0) to (120,110) GeV in the mass plane of the lead/subl pT Higgses.
- Top Veto:
 - Leptonic top :
 - Events with electron or muon
 - Hadronic top :
 - Reconstruct top and W boson candidates from three jets
 - 'B-jet' from top decay must be a Higgs candidate jet
 - Any other two jets for W boson candidate
 - Veto events with $X_{Wt} < 1.5$

$$X_{Wt} = \sqrt{\left(\frac{m_W - 80.4 \text{ GeV}}{0.1m_W}\right)^2 + \left(\frac{m_t - 172.5 \text{ GeV}}{0.1m_t}\right)^2}$$





Regions



- 2D plane of higgs masses is used to define regions
 - Leading pT Higgs vs Subleading pT Higgs

Signal region (SR)

$$X_{hh} = \sqrt{\left(\frac{m_{2j}^{\text{lead}} - 120}{0.1 \times m_{2j}^{\text{lead}}}\right)^2 + \left(\frac{m_{2j}^{\text{subl}} - 110}{0.1 \times m_{2j}^{\text{subl}}}\right)^2} < 1.6$$

Control region (CR)

$$X_{hh} = \sqrt{\left(\frac{m_{2j}^{\text{lead}} - 120}{0.1 \times m_{2j}^{\text{lead}}}\right)^2 + \left(\frac{m_{2j}^{\text{subl}} - 110}{0.1 \times m_{2j}^{\text{subl}}}\right)^2} > 1.6$$

$$R_{hh}^{\text{CR}} \equiv \sqrt{(m_{2j}^{\text{lead}} - 126.0)^2 + (m_{2j}^{\text{subl}} - 115.5)^2}$$
 < 55 GeV

Validation region 1 (VR1)

$$X_{hh}^{\text{VR1}} \equiv \sqrt{\left(\frac{m_{2j}^{\text{lead}} - 96}{0.1 \times m_{2j}^{\text{lead}}}\right)^2 + \left(\frac{m_{2j}^{\text{subl}} - 88}{0.1 \times m_{2j}^{\text{subl}}}\right)^2} \quad < 1.4$$

Validation region 2 (VR2)

$$X_{hh}^{\text{VR2}} \equiv \sqrt{\left(\frac{m_{2j}^{\text{lead}} - 149}{0.1 \times m_{2j}^{\text{lead}}}\right)^2 + \left(\frac{m_{2j}^{\text{subl}} - 137}{0.1 \times m_{2j}^{\text{subl}}}\right)^2} \quad < 1.25$$





Strategy

- Background estimation relies on use of 2-tagged events
- **Reweighting:** Reweight 2-tagged events to look like 4-tagged events

Reweight function: $f: 2-tag \rightarrow 4-tag$



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- Reweight function split into two pieces:
 - Normalisation (about a factor of 200 more 2-tag events than 4-tag events)
 - Kinematic reweighting based on BDTs derived to correct residual mis-modelling



BDT-based Reweighting

- Kinematic reweighting of 2-tagged data → 4-tagged data
- BDT has capability to reweight events based on multiple dimensions.
 - Splits space of variables in motivated/clever way to capture differences between datasets.
 - Doesn't suffer from 'curse of dimensionalty', always good statistical precision on weights.
 - Divides space of variables into O(30) regions.
- Procedure :
 - For each variable, determine the cut that divides the distribution into two bins which maximises the chi2.
 - Divide sample into two by cutting on the variable with maximum chi2.
 - For each resulting sub-sample, repeat first two steps until some stop-criteria is reached.
 - Each event on a given "leaf" gets the weight :

 $\frac{W \text{leaf, target}}{W \text{leaf, original}}$

- This defines one tree. Before repeating whole procedure, apply the weights to the sample.
- This way, build a forest of trees.
- The final weight for a given event is the product of contributions from the individual trees.



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BDT-based Reweighting

- Variables :
 - Determined by adding one variable at the time, in a "greedy" fashion.
 - The single best was added first, by checking how well a BDT could distinguish the reweighted 2-tagged data from the 4-tagged data.
 - This was repeated, addding more variables, until convergence was reached.
 - Variables:
 - The number of jets in the event.
 - $p_{\rm T}$ of each of the four jets in the Higgs candidates.
 - η of each of the four jets in the Higgs candidates.
 - The ΔR separation of the closest two of the four jets in the Higgs candidates.
 - The ΔR separation of the other two of the four jets in the Higgs candidates.
 - For each of the four jets in the Higgs candidates, the scalar sum of track-jet mass over the scalar sum of track-jet $p_{\rm T}$, for track-jets matched to the jet.
 - Which of each Higgs candidate's jets are b-tagged. (For the four-tag selected events, two of the tagged jets are randomly identified as "untagged".)
 - The number of track-jets matched to each Higgs candidate.
 - ΔR separation of the jets in each Higgs candidate.
 - $p_{\rm T}$ of each Higgs candidate.
 - Mass of di-Higgs system.
 - $\Delta \eta$ separation of the two Higgs candidates.
 - $E_{\rm T}^{\rm miss}$.
 - Variable sensitive to all-hadronic top decays: X_t .



BDT-based Reweighting

- Hyperparameters :
 - Optimised in a way similar to identifying the variables.
 - A BDT was trained to distinguish the reweighted 2-tag data from the 4-tag data.
 - The configuration of hyperparameters for which this BDT did worst, was chosen.
 - Very similar performance for most configurations, no clear optimal choice.
 - Parameters:
 - Minimum #events on leafs : 250
 - Maximum #layers : 5
 - Number of trees : 30
 - Learning rate : 0.7
 - Sampling fraction : 0.7



After BDT

Control Region Plots

- Missing transverse momentum before/after BDT reweighting
- "Data" is 4-tag events
- "Background" is reweighted 2-tag events



Before BDT

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- Control Region Plots
 - 'Unrolled' 2D distribution of missing transverse momentum vs. the effective mass
 - (Discriminant in statistical analysis)







- Background modelling uncertainties
 - Non-closure
 - Transfer of weights
 - Statistical uncertainty in 2-tag SR

- Background modelling uncertainties
 - Non-closure \rightarrow bin-by-bin differences between data and background in CR
 - Transfer of weights
 - Statistical uncertainty in 2-tag SR



- Background modelling uncertainties
 - Non-closure
 - Transfer of weights \rightarrow norm./shape differences in the validation regions
 - Statistical uncertainty in 2-tag SR





 New reweighting functions were derived for this check, excl. the VR under consideration: f_{CR \ {VRi}}(2-tag_{VRi}) = 4-tag_{VRi} estimate

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Results



- Signal Region Plot
 - 'Unrolled' 2D distribution of missing transverse momentum vs. the effective mass
 - (Discriminant in statistical analysis)

$$\mathbf{m}_{\text{eff}}^{4\text{b-jets}} = \sum_{i=1,..,4} p_{\text{T}}^{j_i} + E_{\text{T}}^{\text{miss}}.$$



No signs of new physics :-(



• Exclusion limits – low-mass analysis





• Exclusion limits – combined with high-mass analysis





• Exclusion limits – separately for high/low-mass analyses





Bootstrap Aggregation (bagging)

- Build multiple models based on sub-set of the data
 - Randomly draw percentage of data (with replacement), typically 60-70%
 - Train algorithm on each "bag" of data separately
- · Final model is the average of the individual models
 - Each event weight is the average of the weights from all models
 - Gives a handle on the uncertainty in the final weight \rightarrow the spread in weights!

Random Forests

- Based on Decision Trees and Bagging
- Trees independent of each other
 - Each tree uses random sub-set of data (bagging)
 - AND random sub-set of variables (feature-bagging)
- Final weight is the average of the weights from all trees
- Can be grown in parallel! (Contrary to BDTs)

Extremely Randomised Trees (ExtraTrees)

- Same as Random Forest, except
 - Nodes are split by randomly choosing variable and splitting point
 - This is contrary to Random Forests and BDTs which split the nodes in a "greedy" fashion.

All of the above are currently under investigation – stay tuned for more !!



Back ups